

AUTOMATIC ANESTHESIA

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ABSTRACT:- For any operation, anesthetic is given to the patient. During medical procedure, the patient won't feel any pain using anesthetics. The impact of anesthesia should be there until the operation goes on for specified time interval. What will happen if it is not administered at a particular time interval? This will create serious health problem to the patient. To overcome such unfavorable condition the project automatic anesthesia using PIC is design. In this design, the anesthetic set the amount of anesthesia into it. Using the switch panel, system is turned ON the start signal is received by PIC it controls all the system which sends signal to motor, motor turns on & start infusing anesthesia. Before the system turns ON, the patient parameters like heart rate, temperature, blood pressure is checked and the signal is given to PIC, if its normal system turns ON & anesthesia is injected to the patient. If the patient parameters are not normal then the system is switched off. The parameters like heart beats, temperature, blood pressure are checked by sensors & module.

Keywords:- PIC, Anesthesia, sensor, module, infusion.

Introduction:- Surgeries are mainly performed to remove or reconstruct the damaged parts in the human body. During these surgeries losing blood and pain takes place. Therefore it is necessary to remove the pain and reduce the blood loss. Anesthesia takes major role in the painkilling. So it is necessary to give anesthesia. If surgery taking longer time, like for 4 or 5 hours so we cannot give

anesthesia in single dose. It may cause the death of the patient. Suppose less amount of anesthesia is injected, due to that patient may wake up at the mid of surgery. In other case if excess dose to the patient may lead to critical situation. To minimize this problem the designing of automatic surgery of anesthesia machine based on a microcontroller is helpful. Anesthesia plays an important role in performing painless surgery, so automatic use of anesthesia is required to get successful surgery. In this design, PIC processor is used for controlling various biomedical parameters such as temperature, heart rate, blood pressure etc.

ANESTHESIA definition is – loss of sensation with or without loss of consciousness. Anesthesia is a way to control pain during a surgery. It may help to control the breathing and blood pressure, heart rate of the patient. But all types of anesthesia cannot make the patient unconscious. Anesthesia can be injected to the various parts of the body.

The aim of the project is to control the drug injection speed depending on the patient's state during the surgery. The manually given dosage by the doctor during the operation may vary from standard value, it may cause the effects on the patient. In order to avoid such a problem automatic anesthesia is helpful.

Hardware requirements:-

- 1)PIC16f877a
- 2)Stepper Motor
- 3)Blood pressure & Heart beat module
- 4)Relay driver
- 5)Temperature Sensor
- 6)Syringe Pump

PIC16f877a: The Pic Microcontroller PIC16f877a is one of the most renowned Microcontrollers in the industry. This controller is easy to use and also easy to coding or programming. The main advantages of this PIC16f877a is that uses the write-erase as many times possible because it uses flash memory technology. It has total 40 number of pins. Due to presence of EEPROM in the PIC16f877a Microcontroller, the information can be stored permanently like transmitter codes and receiver frequencies and some related data.

Blood pressure and Heartbeat module: Blood pressure and Heartbeat are shown on display with serial output. With the help of LCD display the systolic, diastolic and pulse readings can be shown. The design is easy to use wrist style eliminates the pumping. The main advantage is that, it does not require external power supply.

16X2 LCD: It displays 16 characters per line and there are 2 such a lines. And also each character is displayed in 5X 7 pixel matrix. The LCD consist of 2 registers such as command and Data. The command register stores the command instruction and Data register store the data to be displayed. A command is an instruction in given to LCD to do predefined task such as intialising LCD, clearing the screen, setting the cursor position, controlling display.

Relay: Relay is electrically operated switch. It consist of input and set of operating terminals. The input terminals is for single or multiple control signals. The conventional form of a relay uses an electromagnet to operate the contacts. When an electric current is flows through the coil it creates magnetic field that activates the movable contact either makes or breaks a connection with a fixed contact.

Relay Driver [ULN2003]: The ULN2003 is high voltage, high current darlington transistor arrays. Each array consists of seven NPN Darlington pairs that provide high voltage outputs. In single Darlington pair, the collector current rating is 500 mA. For higher current capability, the Darlington pairs can be paralleled. ULN2003 device have 2.7k ohm series base resistor. This driver IC is used when we require to drive high current loads using digital logic such as Op-amps, Timers, Gates, PIC etc.

LM35: LM35 temperature sensor which is a semiconductor based sensor. LM35 is an integrated analog temperature sensor whose electrical output is proportional to degree centigrade. It does not require external calibration to provide accuracies. The LM35's low output impedance, linear output, and precise inherent calibration make interfacing to readout or control circuitry easy.

Syringe pump: Syringe pump is a small infusion pump used to insert small amount of fluid to patient or can be used in chemical and biomedical research. It is used for people living with terminal illness. It is also useful for delivering IV medications over several minutes

Block Diagram:

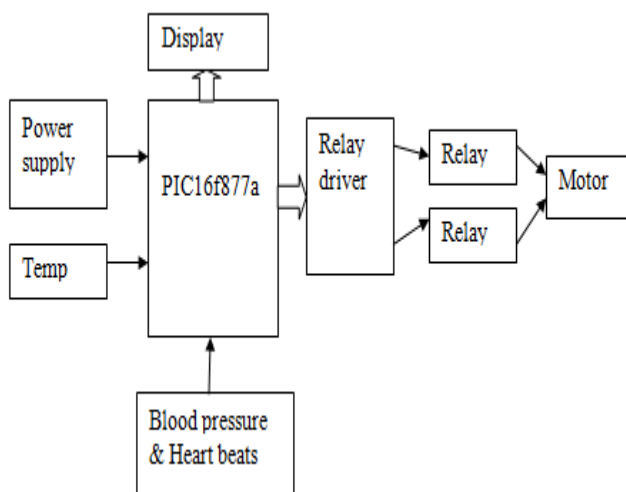


Fig.1-I Block Diagram intelligence Anesthesia

Working:- In this system microcontroller PIC16f877a is used which is the central part of our system. The analog inputs like heartbeats, blood pressure, & temperature connected to it. Heartbeat sensor is used to calculate the rate of heartbeat per min. of patient. The blood pressure module uses an air pump to inflate a cuff surrounding an upper arm or a wrist with sufficient pressure to prevent blood flow in local artery. This pressure is then released gradually using digitally controlled solenoid valve until the moment that blood begins to flow through artery. The blood pressure measured by a pressure sensor at this point determines the systolic pressure. Pulse rate is also sensed at this time. The measurement taken when the blood flow is no longer restricted determines the diastolic pressure. The signal from the pressure sensor is conditioned with an instrumentation amplifier before data conversion by an ADC. The systolic, diastolic pressure & pulse rate measurements are displayed on LCD, time stamped and stored in non-volatile memory. These values will give input to microcontroller. On the board, the anesthesia dosage is set which can be altered using increment/decrement buttons. The heartbeats,

temperature, blood pressure and dosage will be indicated on the display. Whenever the situation arises, the system provides anesthesia by pressing the start button, then the DC motor turns ON which is connected to a syringe tube that starts injecting anesthetics. The motor drives in bidirectional i.e. forward and reverse direction. If the displayed parameters are abnormal, the system will not work until it gets to normal. In contrast, when the parameters get normal, the system works & the patient is injected with anesthetics. The utilization of automatic anesthesia control system increases patient safety, and comfort for the anesthesiologist. The system will calculate the initial dose to be injected, then after the parameters of the patient are continuously monitored by the device.

Expected result:- By observing temperature, blood pressure and heartbeats of the patient from that, if the condition is normal, then anesthetics can be injected to the patient and if the condition is not normal, then the system is hindered.

Conclusion & future scope:-

In this project, we have monitored various parameters of the patient like body temperature, heartbeats, blood pressure. The complete system is developed by using PIC controller and relay driver circuit for the motor attached to the insertion assembly.

This system is definitely a great solution for the doctors while requirement of the anesthesia given to the patient at the time of operation.

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