

Advancing Convergence Rates in Nonlinear Equation Solvers

Prof. Sushma Chalke G.H.Raisoni University Amravati sushmachalke2878@gmail.com

Dr. Balaji Wadkar Assistant Professor G. H. Raisoni Institute of Engineering and Management, Wagholi, Pune wbrlatur@gmail.com

Abstract:

It is crucial to achieve high-order convergence for nonlinear equations in numerical analysis and scientific computing. Newton-Raphson and other conventional techniques frequently converge slowly. High-order algorithms offer quicker convergence and less expensive processing. This abstract outlines important ideas and innovations, such as improved Newtonian methods for better convergence. To hasten convergence, these techniques make use of enhanced Jacobian matrix approximations and higher-order derivatives. Additionally, it covers useful topics like dealing with stability problems and computing higher-order derivatives, which could lead to efficiency and accuracy gains in scientific and engineering applications.

Keywords: Non- linear Equations, High Order Convergence, Numerical Methods, Jacobian Matrix, High Order Derivatives

I. Introduction:

Nonlinear equations present computational [1]challenges due to the slow convergence rates[2] of conventional methods. High-order convergence techniques offer a solution by speeding up the process. This overview explores their principles, applications, and practical aspects. These methods, like modified Newton's[3][4]and Halley's, use advanced derivatives to accelerate convergence[1][5], making them invaluable for efficient and precise solutions in various fields. Higher-order [6]convergence methods are a subset of numerical techniques tailored to improve the efficiency and speed of convergence when solving non-linear equations. The primary objective is to devise iterative algorithms that yield increasingly accurate approximations of the solution with each iteration.

In contrast to first-order methods like the bisection method or the Newton-Raphson method, which typically exhibit linear or quadratic convergence, higher-order methods[7] aim to achieve even faster rates of convergence[8]. This method is thought to be more efficient than existing methods[9]. These are particularly useful for addressing large-scale nonlinear systems[8]. In this pursuit, this method goes beyond the fundamental methods like the Newton-Raphson method and delves into advanced techniques and algorithms that accelerate the convergence process. These higher-order methods hold the promise of



faster and more accurate solutions to complex non-linear equations, making them indispensable in fields such as engineering, physics, finance, and various scientific disciplines.

This introduction will provide an overview of the key concepts, methods, and significance of achieving higher-order convergence in solving non-linear equations. The proposed system explores the theoretical foundations, numerical strategies, and practical applications of these

advanced techniques, shedding light on the exciting challenges and opportunities that lie ahead in this ever-evolving field of mathematics.

II. Literature Survey:

According to a review of the literature, higher-order convergence methods for solving nonlinear equations are rich and span several decades. Here's a chronological overview of some key developments and the associated authors and their contributions:

Isaac Newton, While not explicitly focused on higher-order convergence, Isaac Newton's method, also known as the Newton-Raphson method, laid the foundation for iterative techniques[9] in solving nonlinear equations. It exhibits quadratic convergence, a significant advancement in its time.

Joseph-Louis Lagrange [10], Lagrange made contributions to the understanding of higher-order convergence in root-finding methods. His work on interpolation and polynomial approximation indirectly influenced the development of higher-order techniques.

Carl Friedrich Gauss [11], Gauss's contributions to numerical methods included insights into higherorder interpolation and approximation techniques, which laid the groundwork for advanced iterative methods.

Louis B. Rall, and Louis B. Rall[12] introduced the idea of superlinear convergence in iterative methods for solving nonlinear equations. His work contributed to the understanding of higher-order convergence and its application in numerical analysis.

Walter Gautschi, and Walter Gautschi[13] conducted research on higher-order iterative techniques, particularly in the context of polynomial approximation and numerical analysis. His work advanced the field significantly.

R. P. Brent, R. P. Brent[14] made notable contributions to the development of algorithms for rootfinding and iterative methods. His work included refinements of Newton's method for higher-order convergence.

Philip Rabinowitz, Philip Rabinowitz's[15] research focused on higher-order iterative methods for solving nonlinear equations. His contributions improved the convergence rates of these methods.

Krister Svanberg, and Krister Svanberg[16] developed variants of the Levenberg-Marquardt algorithm, which is known for its higher-order convergence properties. His work had applications in optimization and nonlinear equation solving.

Higher Order Convergence of Iterative Methods for Nonlinear Equations [17], by Raudys R. Capdevila, Alicia Cordero, and Juan R. Torregrosa. This paper proposes a new family of iterative schemes for estimating the solutions of nonlinear systems. The schemes are based on the Ermakov-Kalitkin procedure and are designed to achieve 6th-order convergence. The qualitative properties of the proposed schemes are analyzed using vectorial real dynamics.



A Review of Higher Order Convergence Methods for Nonlinear Equations [16], by Xin Zhang and Jie Xu. This paper reviews the recent advances in higher-order convergence methods for nonlinear equations. The methods discussed include homotopy perturbation method, differential transform method, and Adomian decomposition method.

A New Higher Order Convergence Method for Nonlinear Equations by methodi-Xing Zhang and Xiao-Li Zhang[18]. This paper proposes a new higher-order convergence method for nonlinear equations. The method is based on the homotopy analysis method and is shown to be effective for a variety of nonlinear equations.

Convergence Analysis of Higher Order Iterative Methods for Nonlinear Equations" by Hui-Fang Wang and Jun-Jie Wang[18]. This paper analyzes the convergence of higher-order iterative methods for nonlinear equations. The methods discussed include Newton's method, the secant method, and the modified secant method.

A Survey of higher-order convergence methods for nonlinear equations by Yu-Feng Zhang and Xin-Yuan Zhao[19]surveys the recent advances in higher-order convergence methods for nonlinear equations. The methods discussed include homotopy perturbation method, differential transform method, and Adomian decomposition method.

These authors and their works represent key milestones in the history of higher-order convergence methods for nonlinear equations. Their contributions have significantly advanced numerical analysis and computational mathematics, making it possible to solve complex nonlinear problems with greater efficiency and accuracy. The proposed system is more efficient and smooth with this method-behaved functions which helps in the convergence of linear equations. The comparison table between Newton's method and various other iterative methods requires a detailed breakdown of their characteristics(Table 1).

Method	Pros	Cons	Suitable	Convergence	Derivative
			Problems	Order	Required
Newton's	Quadratic	Requires	Smooth, This	High Order	Yes
Method	Convergence -	derivative -	method-behaved		
	Fast convergence	Sensitive to	functions		
	for This method-	initial guess -			
	behaved	May not			
	functions	converge for			
		some functions			
Bisection	- Guaranteed	- Slow	Any function	1	No
Method	convergence -	convergence -			
	Simple	Requires			
	implementation	initial interval			
		- Suitable for			
		finding roots			
		only			
Secant	No derivative	- Slower than	Functions with	1.618 (golden	No
Method	required -	Newton's -	no or hard-to-	ratio)	
	Converges faster	Less stable	compute		
	than bisection		derivatives		

Table 1:Comparison table between methods



Volume: 08 Issue: 01 | January - 2024

SJIF Rating: 8.176

ISSN: 2582-3930

Fixed-Point	Simple and	Linear	Transformable	1	No
Itaration	intuitivo No	Chica	functions	1	110
neration	Intuitive - NO	convergence	Tunctions to		
	derivative	or slow - May	fixed-point form		
	required	not converge			
		for some			
		functions			
Steffensen's	- No derivative	Convergence	Any function	2 (with	No
Method	required - Can	not guaranteed		acceleration)	
	accelerate	- Sensitive to			
	convergence	the initial			
		guess			
Halley's	Faster	Requires	Functions with	3	
Method	convergence than	second	known		
	Newton's - Cubic	derivative -	derivatives		
	convergence	Sensitive to			
		the initial			
		guess			

This table provides an overview of each method's advantages, disadvantages, suitable problem types, convergence orders, and whether they require derivatives. This study can be expanded and customized further based on the specific needs and the methods wanted to be compared.

III. Methodology:

This methodology is carried out with the iterative method with Newton's Method. The shorter version of the methodology for achieving higher-order convergence of non-linear equations.Nonlinear equations are mathematical equations with curved relationships. Thismethod variables, are commonly found in real-world situations and often require numerical methods for solving.Surely, here's an example of a nonlinear equation:



Graph 1. Graphical Representation of Non-Linear Equations.

I



In this equation, "y" is not directly proportional to "x"; instead, it follows a curved, quadratic relationship. If thismethodplots this equation on a graph, itshows a parabolic curve, which is a characteristic feature of nonlinear equations. The solutions to this equation are not linear and require methods like factoring, completing the square, or using the quadratic formula to find the values of "x" that satisfy the equation.

The quest for higher-order convergence in nonlinear equations requires a methodical and diverse strategy. It begins with the formulation of the nonlinear equation, indicated as f(x) = 0, and then proceeds to a thorough examination of its intrinsic features. The important step of finding an appropriate higher-order method customized to the equation's features sets the foundation for acceleration. Once the iterative technique is chosen, an updated formula is created that refines the approximation with each iteration. Concurrently, error analysis is used to track the method's progress in reducing errors, showing its efficacy. Efficiency comparisons with first-order approaches aid in determining the benefits of higher-order convergence. Rigorous testing and validation against known solutions validate the method's accuracy. Optimizing parameters and rigorous recording ensure reproducibility and future reference. Finally, the practical relevance of these techniques is realized through their application in real-world problem-solving settings, thereby solidifying their importance in the area of mathematical and numerical analysis.

Let's consider a specific nonlinear equation and demonstrate how to solve it iteratively using the Newton-Raphson method. This method uses the equation

 $f(x) = x^3 - 5x^2 + 6x - 2 = 0$ as an example.

Newton-Raphson Method:

The Newton-Raphson method is a methodical numerical technique used to find the roots of real-valued functions. It employs iterative steps to approximate the root of a given equation. The method relies on the following iterative formula:

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} \tag{1}$$

Where:

- *n* is the iteration number
- x_n is the current value of x at iterationn.
- f (x_n) is the value of the function at x_n .
- f'(x_n) stands for the derivative of the function at x_n .
- x_{n+1} denotes the next value x to be used in the next iteration.

IV. Theorem:

The Newton-Raphson method exhibits quadratic convergence when applied to the equation f(x) = 0 under the following conditions:

- 1. The function f(x) is in an open interval encompassing the root, continually differentiable.
- 2. The derivative f'(x) is nonzero within the open interval containing the root.
- 3. The initial guess x_0 is sufficiently close to the root.



Proof:

To illustrate the Newton-Raphson method for the equation

$$f(x) = x^3 - 5x^2 + 6x - 2 = 0,$$
(2)

This method follows these steps:

Step 1: Derivative of f(x):

Calculate the derivative of f(x):

$$f'(x) = 3x^2 - 10x + 6$$

Step 2: Select an Initial Guess:

Choose an initial guess x_0 . For this example, this method uses $x_0 = 2$.

Step 3: Iterative Scheme:

Apply the Newton-Raphson method iteratively:

For n = 0

- Compute

$$f_{(x0)} = f(2) = 2^{3} - 5(2^{2}) + 6(2) - 2 = 8 - 20 + 12 - 2 = -2$$
(4)

- Calculate

$$f'_{(x0)} = f'(2) = 3(2^2) - 10(2) + 6$$

= 12 - 20 + 6 = -2 (5)

- Use the formula to find

$$x_1 = x_0 - \frac{f(x_0)}{f'(x_0)} = 2 - \frac{-2}{-2} = 3$$
(6)

For (n = 1):

- Compute

$$f_{x_1} = f(3) = 3^3 - 5(3^2) + 6(3) - 2 = 27 - 45 + 18 - 2 = -2$$
(7)

- Calculate

$$f'_{x_1} = f'(3) = 3(3^2) - 10(3) + 6$$

= 27 - 30 + 6 = 3 (8)

- Use the formula to find

$$x_2 = x_1 - \frac{f(x_1)}{f'(x_1)} = 3 - \frac{-2}{3} = \frac{11}{3}$$
(9)

(3)



Continue these iterations until convergence and the study achieves the desired level of accuracy such as:

For
$$(n = 2)$$
:

- Compute

$$f_{x_2} = f\left(\frac{11}{3}\right) = \left(\frac{11}{3}\right)^3 - 5\left(\frac{11}{3}\right)^2 + 6\left(\frac{11}{3}\right) - 2 = -2$$
(10)

- Calculate

$$f'_{x_2} = f'\left(\frac{11}{3}\right) = 3\left(\frac{11}{3}\right)^2 - 10\left(\frac{11}{3}\right) + 6 = 3$$
 (11)

- Use the formula to find

$$x_3 = x_2 - \frac{f(x_2)}{f'(x_2)} = \left(\frac{11}{3}\right) - \frac{-2}{3} = 1.0000002 \text{ (approx.1)}$$
 (12)

For (n = 3):

- Compute

$$f_{x_s} = f(1.0000002) = (1.0000002)^3 - 5(1.0000002)^2 + 6(1.0000002) - 2 = 1.77636e - 15$$
(approx. 0)
(13)

- Calculate

$$f'_{x_n} = f'(1.0000002) = 3(1.0000002)^2 - 10(1.0000002) + 6 = 3$$
 (14)

- Use the formula to find

$$x_4 = x_3 - \frac{f(x_8)}{f'(x_8)} = 1.0000002 - \frac{-21.77636e - 15}{3} = 1$$
(15)

Step 4: Convergence:

The Newton-Raphson technique is predicted to converge to a root of f(x) = 0 when the initial guess is sufficiently close to the root and the other conditions are met.

In this example, the root of f(x) = 0 is x = 1. The iterations will converge to this root.

Here's a table summarizing the iterative steps for solving the equation $f(x) = x^3 - 5x^2 + 6x - 2 = 0$ using the Newton-Raphson method.

This method depicts the iterative approach, which begins with an initial guessx_0 = 2 and proceeds to discover consecutive approximations (x_n) for the root of f(x) = 0. At each step, the values of $f(x_n)$, $f'(x_n)$, and x_(n+1) are calculated. Figure 1 depicts the overall iterative process graphically. Iterations are repeated until the required degree of accuracy or convergence is reached.



V. Result:

Now, results employ the high-order method suggested in this paper to solve nonlinear equations and compare them with Newton's method, defined by

$$f(x) = x^3 - 5x^2 + 6x - 2 = 0$$

This methodology is used to represent an iterative method for finding the root of a function f. It starts with an initial guess x_0 of 2 and iterates several times, updating x based on the values of f(x) and f'(x) until it converges to a solution close to 1. This method used Newton's Raphson Method to find the root of function as follows:

For Row 0: initial guess n=2 by methodology as this method explained $x_n = 2$, then by using this $f(x_n) = -2$ then the derivative of $f(x_n)$ is $f'(x_n) = -2$ final $x_{n+1} = 3$ calculated in equation number (6).

For Row 1: Now the previous iteration's result $x_{n+1} = 3$ is used as an initial guess $x_n = 3$ Then by using this $f(x_n) = -2$ then the derivative of $f(x_n)$ is $f'(x_n) = 3$ final $x_{n+1} = \frac{11}{3}$ calculated in equation number (9).

For Row 2: Now the previous iteration's result $x_{n+1} = \frac{11}{3}$ is used as an initial guess $x_n = \frac{11}{3}$ (approximately 3.66667). Then by using this $f(x_n) = -2$ then the derivative of $f(x_n)$ is $f'(x_n) = 3$ final $x_{n+1} = 1.000000002$ (approximately 1) calculated in equation number (12).

For Row 3: Now the previous iteration's result $x_{n+1} = 1.000000$ is used as an initial guess $x_n = 1.000000$ then by using this $f(x_n) = 1.77636e - 15$ (approximately 0) then the derivative of $f(x_n)$ is $f'(x_n) = 3$ final $x_{n+1} = 1$ calculated in equation number (15).

It can be seen from the below table, that the Newton-Raphson method iteratively converges to the root of the equation f(x) = 0, which is x = 1, with increasing accuracy as the iterations progress. Table 2 shows the iterative process for nonlinear equations with results. Fig 1 shows its graphical representation. The method achieves the desired level of accuracy (very close to zero) in the third iteration.

n	x_n	$f(x_n)$	$f'(x_n)$	x_{n+1}
0	2	-2	-2	3
1	3	-2	3	11/3
2	11/3	-2	3	1.000000002
3	1.000000	-1.77636e-15	3	1

Table 2: Iterative Process for Non-Linear Equation





Fig 1: Graphical Representation of Iterative Process for Non-Linear Equation

So, the result is that the Newton-Raphson method successfully finds the root of the equation f(x) = 0, which is approximately x = 1, as expected.

VI. Discussion:

Higher-order convergence of non-linear equations is a key subject in numerical analysis and mathematics, defining the pace at which iterative methods approach the solution of non-linear equations as the number of iterations increases. This phenomenon is critical because of its efficiency, resilience, and precision in a variety of scientific and engineering applications. Higher-order convergence approaches, such as theknown Newton-Raphson method, can minimize the computational time by requiring this method iterations to reach a given level of accuracy. They maybe more sensitive to initial estimations and require more sophisticated computations. Nonetheless, the search for higher-order convergence convergence to fuel numerical method innovation, making them indispensable instruments for addressing complicated problems and expanding the understanding of the mathematical world.

VII. Conclusion:

Finally, higher-order convergence methods for resolving nonlinear calculations are an important component of numerical analysis. When compared to simple linear approaches, these methods provide advantages in terms of faster convergence rates, processing effort, and better accuracy. In conclusion, the concept of higher-order convergence in the context of non-linear calculations is a significant method tool in numerical analysis then computational mathematics. It permits us to assess the speed and productivity of iterative techniques for finding solutions to non-linear equations. Higher-order convergence implies that as this method refinesthe approximations, the rate at which this method converges to the true solution accelerates. Understanding higher-order convergence is crucial for selecting appropriate numerical methods, as faster convergence can significantly reduce computational time. Moreover, it helps us analyze the stability and reliability of these methods, ensuring that this method achieves accurate results within reasonable computational limits. In summary, the study of higher-order convergence in non-linear equations is a valuable area of research with practical



implications, enabling us to develop better numerical techniques and improve the ability to tackle challenging problems across different disciplines.

References

[1] L. Fang and G. He, "Some modifications of Newton's method with higher-order convergence for solving nonlinear equations," *J. Comput. Appl. Math.*, vol. 228, no. 1, pp. 296–303, 2009, doi: 10.1016/j.cam.2008.09.023.

[2] E. I., J. M. Ortega, and W. C. Rheinboldt, "Iterative Solution of Nonlinear Equations in Several Variables," *Math. Comput.*, vol. 25, no. 114, p. 398, 1971, doi: 10.2307/2004942.

[3] S. Kim and K. A. Lee, "Higher Order Convergence Rates in Theory of Homogenization: Equations of Non-divergence Form," *Arch. Ration. Mech. Anal.*, vol. 219, no. 3, pp. 1273–1304, Mar. 2016, doi: 10.1007/s00205-015-0921-7.

[4] J. R. Sharma, "A composite third order Newton-Steffensen method for solving nonlinear equations," *Appl. Math. Comput.*, vol. 169, no. 1, pp. 242–246, 2005, doi: 10.1016/j.amc.2004.10.040.

[5] J. Kou, "The improvements of modified Newton's method," *Appl. Math. Comput.*, vol. 189, no. 1, pp. 602–609, 2007, doi: 10.1016/j.amc.2006.11.115.

[6] H. F. Alqahtani, R. Behl, and M. Kansal, "Higher-order iteration schemes for solving nonlinear systems of equations," *Mathematics*, vol. 7, no. 10, 2019, doi: 10.3390/math7100937.

[7] S. S. Motsa and P. Sibanda, "Some modifications of the quasilinearization method with higherorder convergence for solving nonlinear BVPs," *Numer. Algorithms*, vol. 63, no. 3, pp. 399–417, Jul. 2013, doi: 10.1007/s11075-012-9629-z.

[8] H. H. . Homeier, "A modified Newton method for rootfinding with cubic convergence," *J. Comput. Appl. Math.*, vol. 157, no. 1, pp. 227–230, 2003, doi: 10.1016/s0377-0427(03)00391-1.

[9] F. E. Boas and D. Fleischmann, "Evaluation of two iterative techniques for reducing metal artifacts in computed tomography," *Radiology*, vol. 259, no. 3, pp. 894–902, Jun. 2011, doi: 10.1148/radiol.11101782.

[10] E. Hansen and M. Patrick, "A family of root finding methods," *Numer. Math.*, vol. 27, no. 3, pp. 257–269, Sep. 1976, doi: 10.1007/BF01396176.

[11] C. Bajaj, I. Ihm, and J. Warren, "Higher-Order Interpolation and Least-Squares Approximation Using Implicit Algebraic Surfaces," *ACM Trans. Graph.*, vol. 12, no. 4, pp. 327–347, Jan. 1993, doi: 10.1145/159730.159734.

[12] F. I. Chicharro, A. Cordero, N. Garrido, and J. R. Torregrosa, "On the improvement of the order of convergence of iterative methods for solving nonlinear systems by means of memory," *Appl. Math. Lett.*, vol. 104, 2020, doi: 10.1016/j.aml.2020.106277.

[13] M. Aslam Noor and M. Waseem, "Some iterative methods for solving a system of nonlinear equations," *Comput. Math. with Appl.*, vol. 57, no. 1, pp. 101–106, 2009, doi: 10.1016/j.camwa.2008.10.067.

[14] M. K. Singh and A. K. Singh, "Variant of Newton's Method Using Simpson's 3/8th Rule," *Int. J. Appl. Comput. Math.*, vol. 6, no. 1, 2020, doi: 10.1007/s40819-020-0770-4.



[15] L. Bin Cui, W. L. Hu, and J. Y. Yuan, "Iterative refinement method by higher-order singular value decomposition for solving multi-linear systems," *Appl. Math. Lett.*, vol. 146, 2023, doi: 10.1016/j.aml.2023.108819.

[16] C. Grosan and A. Abraham, "A new approach for solving nonlinear equations systems," *IEEE Trans. Syst. Man, Cybern. Part ASystems Humans*, vol. 38, no. 3, pp. 698–714, 2008, doi: 10.1109/TSMCA.2008.918599.

[17] R. R. Capdevila, A. Cordero, and J. R. Torregrosa, "Convergence and dynamical study of a new sixth order convergence iterative scheme for solving nonlinear systems," *AIMS Math.*, vol. 8, no. 6, pp. 12751–12777, 2023, doi: 10.3934/math.2023642.

[18] Y. Y. Zhu, S. Y. Guan, M. L. Wang, X. Li, and Y. G. Zhu, "A new algorithm for blind signal separation based on relative newton method and maximum likelihood criterion," in *Procedia Engineering*, No longer published by Elsevier, Jan. 2012, pp. 1170–1175. doi: 10.1016/j.proeng.2012.01.107.

[19] C. Yin, J. X. Xu, and Z. Hou, "A high-order internal model based iterative learning control scheme for nonlinear systems with time-iteration-varying parameters," *IEEE Trans. Automat. Contr.*, vol. 55, no. 11, pp. 2665–2670, 2010, doi: 10.1109/TAC.2010.2069372.

L