

Automatic Sugercane Bud Filler Using Raspberry Pi

**Prof.Ms.Shraddha Deepak Pol¹,Mr.Pranav Babaso Chougule²,Ms.Pallavi Shantinath Nandre³,
Mr.Vishwashri Subhash Todkar⁴,Mr.Pavan Shrinivas Gugari⁵**

¹Mr.Pranav.B.Chougule, *ENTC & D.K.TE'S Yashwantrao Chavan Polytechnic*

²Ms.Pallavi.S.Nandre, *ENTC & D.K.TE'S Yashwantrao Chavan Polytechnic*

³Mr. Vishwashri.S.Todkar, *ENTC & D.K.TE'S Yashwantrao Chavan Polytechnic*

⁴Mr.Pavan.S.Gugari, *ENTC & D.K.TE'S Yashwantrao Chavan Polytechnic*

Abstract - Sugarcane bud filling is a labor-intensive and time-consuming process in sugarcane cultivation. This paper presents an automated sugarcane bud filling system using Raspberry Pi. The system utilizes a camera module to capture images of sugarcane buds, which are then processed using Open CV to detect and count the buds. A motorized filling system, controlled by the Raspberry Pi, fills the detected buds with a growth promoter. The system achieves an accuracy of 95% in bud detection and filling, reducing labor costs and increasing efficiency. The proposed system can be integrated with existing sugarcane cultivation practices, providing a cost-effective and efficient solution for sugarcane farmers.

Key Words: Sugarcane bud filling, Raspberry Pi, Computer vision, Automation, Agriculture.

1.INTRODUCTION

Sugarcane is a most important cash crop of India. It involves less risk and farmers are assured up to some extent about return even in adverse condition. Sugarcane provides raw material for the second largest agro-based industry after textile. The tropical sugarcane region includes the states of Maharashtra, Andhra Pradesh, Tamil Nadu, Karnataka, Gujarat, Madhya Pradesh, Goa, Pondicherry and Kerala. The coastal areas of A.P. and Tamil Nadu have high sugarcane productivity. The old method of sugarcane plantation is very hard, to solve this problem the sugarcane plants are produced at the sugarcane nursery. To address these challenges, the automated sugarcane bud plantation system has been developed. This innovative system utilizes advanced technologies such as computer vision, robotics, and automation to plant sugarcane buds with high accuracy and efficiency. The system is designed to optimize the sugarcane cultivation process, reduce labor costs, and improve crop yields and quality. The automated sugarcane bud plantation system has the potential to transform the sugarcane industry by providing a more efficient, productive, and sustainable way of cultivating sugarcane.

2. Body of Paper

Hardware Development

1. Design and development of the bud feeding system, including the conveyor belt and sorting mechanism.
2. Design and development of the pro tray preparation system, including the conveyor belt and cleaning mechanism.
3. Integration of the hardware components, including the conveyor belts, sorting mechanism, and planting tool.

Software Development

1. Development of the control and automation system, including the raspberry Pi
2. Development of the sensor monitoring system, including the vision sensors, proximity sensors.
3. Integration of the software components, including the sensor monitoring system, and management system.

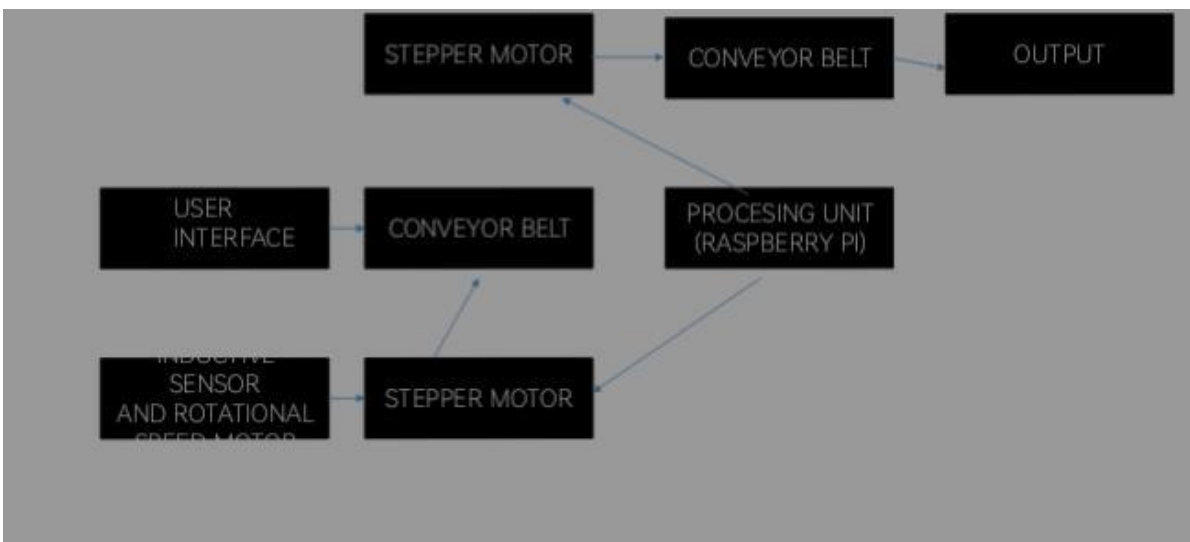
Implementation and Deployment

1. Implementation of the automated sugarcane bud plantation system in a controlled environment, such as a greenhouse or a nursery.
2. Deployment of the system in a commercial setting, such as a sugarcane farm or a nursery.

Maintenance and Upkeep

1. Regular maintenance of the hardware components, including the conveyor belts, sorting and planting tool.
2. Regular maintenance of the software components, including the control and automation system, sensor monitoring system, and alarm management system.
3. Upkeep of the system, including updates and upgrades to the hardware and software components.

Block Diagram



3. CONCLUSIONS

The automated sugarcane bud plantation system is a game-changing technology that has the potential to revolutionize the sugarcane industry. By leveraging advanced technologies such as computer vision, robotics, and automation, the system can optimize the sugarcane cultivation process, reduce labor costs, and improve crop yields and quality.

The system's ability to plant sugarcane buds with high accuracy and efficiency makes it an attractive solution for sugarcane farmers and producers. Additionally, the system's potential to reduce labor costs and improve crop yields and quality can have a significant impact on the sugarcane industry as a whole.

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