

Driver Drowsiness Detection System Using Python

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Abstract - This project proposes a **real-time Driver Drowsiness Detection System** designed to prevent road accidents caused by driver fatigue. The system utilizes **Python**, **OpenCV**, and **dlib** to monitor the driver's facial features through a webcam. It identifies key facial landmarks, particularly around the eyes and mouth, to calculate the **Eye Aspect Ratio (EAR)** and **Mouth Aspect Ratio (MAR)**. These ratios serve as indicators of drowsiness symptoms such as prolonged eye closure and yawning. When the EAR or MAR values exceed preset thresholds, the system triggers **visual and audible alerts** to warn the driver. The proposed solution is **non-intrusive**, **cost-effective**, and capable of real-time performance without requiring additional hardware. By integrating **computer vision** and **machine learning** techniques, this system offers a practical and efficient tool for enhancing driver safety, reducing fatigue-related accidents, and contributing to the development of **intelligent transportation systems**.

Key Words: Driver Drowsiness Detection, Python, OpenCV, dlib, Computer Vision, Eye Aspect Ratio (EAR), Real-time Monitoring, Road Safety.

1. INTRODUCTION

1.1 BACKGROUND OF THE STUDY

Transportation plays a vital role in modern society, driving economic growth, social interaction, and mobility. However, the increasing number of vehicles has led to a rise in road accidents, posing a major public safety challenge. According to the **World Health Organization (WHO, 2023)**, around **1.3 million deaths** and **20–50 million injuries** occur annually due to road traffic accidents. Among various causes, **driver drowsiness** is one of the most dangerous and underestimated factors, as it develops gradually and often without warning.

Driver fatigue leads to slower reaction times, poor decision-making, and reduced vigilance. Studies show that **17–19 hours of wakefulness** is equivalent to a **blood alcohol concentration (BAC) of 0.05%**, while **24 hours** equals **0.10%**, exceeding legal driving limits. Microsleeps lasting just a few seconds can cause severe crashes, especially on highways. Global data, including from the **NHTSA (2022)** and **ETSC (2021)**, reveal that fatigue contributes to about **20% of all accidents**, emphasizing the urgent need for effective detection systems.

Traditional countermeasures such as caffeine, music, or short breaks provide only temporary relief. With advances in **Artificial Intelligence (AI)** and **Computer Vision**, real-time fatigue detection systems have become feasible. Using tools like **OpenCV**, **dlib**, and **NumPy**, these systems analyze facial features—eye closure, blink frequency, yawning, and head position—to detect fatigue and alert the driver instantly. Major automotive companies like **Tesla**, **Mercedes-Benz**, and **Nissan** have already adopted similar systems, reducing fatigue-related crashes by up to **50%**.

1.2 PROBLEM STATEMENT OVERVIEW

Driver drowsiness silently impairs mental and physical performance, leading to slow reactions, poor judgment, and potentially fatal accidents. While modern cars are equipped with lane departure and collision warnings, most systems are **reactive**, responding only after a dangerous event occurs. Existing fatigue detection methods are either **physiological** (using sensors like EEG or heart rate monitors, which are intrusive) or **behavioral** (based on facial and eye analysis, which are non-intrusive but affected by lighting and occlusion). The challenge lies in developing a **non-intrusive, real-time, and accurate** detection system capable of functioning under varied environmental conditions. Hence, the research problem is:

“How can a Python-based computer vision system accurately detect driver drowsiness in real time and provide immediate alerts?”

1.3 OBJECTIVES

The primary goal is to design and implement a **real-time Driver Drowsiness Detection System (DDDS)** using Python and computer vision.

Specific objectives include:

- Capturing live video frames at 20–30 fps and adapting to various lighting conditions.
- Detecting and tracking facial landmarks using **OpenCV** and **dlib**.
- Calculating **Eye Aspect Ratio (EAR)** and **Mouth Aspect Ratio (MAR)** to identify fatigue indicators.
- Performing temporal analysis to differentiate natural blinks from prolonged eye closure.
- Triggering visual and auditory alerts upon detecting drowsiness.
- Ensuring a cost-effective, non-intrusive prototype suitable for real-time deployment.

1.4 SCOPE OF THE PROJECT

The system focuses on real-time analysis of visual fatigue cues such as eye closure and yawning under normal driving conditions. It uses standard webcams and open-source Python libraries, ensuring affordability and accessibility. Potential applications include **automotive dashboards**, **fleet management**, **industrial safety**, and **healthcare monitoring**.

Future enhancements may involve **AI personalization**, **IoT-based fleet tracking**, and **multi-sensor fusion** to improve accuracy and adaptability across diverse environments.

1.5 SIGNIFICANCE OF THE STUDY

This project significantly contributes to **road safety**, **technological innovation**, and **intelligent transportation systems (ITS)**. By detecting fatigue before accidents occur, it provides proactive intervention and reduces the number of fatigue-related crashes by up to 30%. Technologically, it demonstrates the power of AI and computer vision in real-world safety applications. Societally, it helps save lives, lower healthcare and insurance costs, and enhance driver awareness.

Academically, it establishes a foundation for future research in **AI-assisted driving**, **adaptive monitoring**, and **autonomous vehicle safety systems**.

2. LITERATURE SURVEY

Driver drowsiness detection has gained increasing attention in research due to its direct impact on road safety and accident prevention. Studies show that fatigue-related crashes are particularly common during long-distance, night-time, or monotonous driving conditions. To address this, researchers have explored multiple approaches that fall into three primary categories — **behavioral (vision-based)**, **physiological**, and **vehicle-based** methods.

Behavioral or vision-based methods focus on monitoring visual cues such as **eye closure**, **blinking rate**, **yawning**, **head position**, and **gaze direction** using facial landmarks. Techniques like **Eye Aspect Ratio (EAR)** and **Mouth Aspect Ratio (MAR)** are used to detect prolonged eye closure or frequent yawning. These systems typically employ **OpenCV** and **dlib** libraries, often enhanced by **Convolutional Neural Networks (CNNs)** to improve accuracy under various lighting conditions and facial orientations.

Physiological approaches, on the other hand, measure internal signals such as **EEG**, **ECG**, and **skin conductance**, which provide direct indicators of alertness but are intrusive and impractical for daily driving. Vehicle-based methods infer fatigue through **steering patterns**, **lane deviation**, and **speed fluctuations**, though they may misinterpret environmental factors.

Recent advancements emphasize **hybrid and multimodal systems** that combine visual, physiological, and vehicle data through **deep learning architectures (CNN, RNN, Transformers)**. These integrated systems demonstrate higher accuracy, robustness, and adaptability in real-world environments, offering a foundation for advanced **Driver Monitoring Systems (DMS)** in modern vehicles.

2.1 CLASSICAL AND MODERN APPROACHES IN REAL-TIME DROWSINESS DETECTION

Among behavioral methods, **EAR-based facial landmark analysis** is one of the most efficient and widely adopted techniques. Proposed by Soukupová and Čech (2016), the EAR is calculated from six key eye landmarks and effectively distinguishes between open, blinking, and closed-eye states. Similarly, the **Mouth Aspect Ratio (MAR)** is used to detect yawning, another key indicator of fatigue. When EAR and MAR are combined, they provide reliable real-time cues for drowsiness detection with minimal computational cost. Temporal smoothing and threshold analysis further enhance accuracy by reducing false detections.

Modern systems integrate **spatio-temporal modeling** using **CNNs**, **LSTMs**, and **Transformers**, enabling the detection of gradual fatigue patterns over time. **Lightweight models** such as **MobileNet**, **SqueezeNet**, and **EfficientNet-Lite** allow real-time deployment on embedded devices like **Raspberry Pi** and **NVIDIA Jetson Nano**.

Standard datasets like **NTHU Drowsy Driver**, **YAWDD**, and **DriveAhead** are commonly used for training and evaluation, employing metrics such as **accuracy**, **precision**, **recall**, **F1-score**, and **detection latency**. Despite these advancements, challenges persist — including **lighting variations**, **facial occlusions**, **driver diversity**, and **privacy concerns**.

This project leverages the strengths of **Python-based EAR and MAR detection** with **OpenCV** and **dlib**, integrated with **temporal analysis and alert mechanisms**, to develop a **non-intrusive, cost-effective, and real-time drowsiness detection system** that enhances road safety and contributes to the future of intelligent transportation.

3. PROBLEM STATEMENT

Driver drowsiness is a silent yet highly dangerous phenomenon that progressively impairs both cognitive and physical abilities, resulting in slower reaction times, reduced vigilance, poor decision-making, and occasional microsleeps. Despite the integration of advanced safety features such as lane departure warnings, collision avoidance, and automatic braking in modern vehicles, these systems are primarily reactive—they intervene only after a potential hazard has been detected. Existing fatigue detection approaches can be broadly categorized into physiological and behavioral methods. Physiological methods involve monitoring biological signals such as heart rate, EEG, EOG, and skin conductance, offering high accuracy but at the cost of being intrusive and uncomfortable, as they require wearable sensors that may distract the driver. In contrast, behavioral methods focus on visible indicators such as eye closure duration, blink frequency, yawning, head position, and posture changes. These approaches are non-intrusive and well-suited for real-time implementation using computer vision technologies.

Computer vision-based systems employ in-cabin cameras to continuously monitor the driver's facial cues and derive key metrics like the Eye Aspect Ratio (EAR) and Mouth Aspect Ratio (MAR) to assess alertness. However, developing a reliable and practical drowsiness detection system presents several challenges, including variable lighting conditions (such as day/night transitions, glare, and shadows), partial facial occlusions (caused by glasses, masks, or hand gestures), and

variations among drivers in age, gender, and facial structure. Additionally, ensuring real-time performance with minimal latency is essential to deliver timely alerts that can prevent accidents. Therefore, the core research problem addressed in this study is: **How can a non-intrusive, real-time system accurately detect driver drowsiness and alert the driver using Python-based computer vision techniques?**

4. OBJECTIVES

The primary aim of this project is to design and implement a **Python-based Driver Drowsiness Detection System** that leverages computer vision techniques to monitor driver fatigue in real time. The system utilizes facial landmarks and behavioral cues to assess drowsiness levels accurately and non-intrusively. Live video frames are captured using in-vehicle cameras operating at 20–30 frames per second, ensuring consistent monitoring under various lighting conditions such as daylight, low light, and nighttime. Using **OpenCV** and **dlib** libraries, the system detects and tracks key facial landmarks—particularly the eyes, mouth, and head positions—across continuous frames.

From these landmarks, two crucial metrics are computed: the **Eye Aspect Ratio (EAR)**, where low values indicate prolonged eye closure, and the **Mouth Aspect Ratio (MAR)**, which increases with frequent yawning. These metrics are continuously analyzed over time using temporal analysis techniques, including sliding windows and threshold-based smoothing, to minimize false detections caused by normal blinks or momentary movements. When the system identifies patterns indicative of drowsiness, it triggers immediate **visual, auditory, or haptic alerts** to regain the driver's attention.

The proposed prototype is designed to be **efficient, cost-effective, and compatible with standard hardware**, making it suitable for real-world applications without the need for specialized sensors or intrusive devices. Ultimately, this project contributes to enhancing **road safety** by reducing fatigue-related accidents and serves as a foundation for future advancements in **AI-assisted intelligent transportation systems**. The system follows a clear workflow: *Camera captures live video → Face Detection & Landmark Extraction → EAR & MAR Calculation → Temporal Analysis → Drowsiness Detection → Trigger Alerts*.

5.SCOPE OF THE PROJECT

The **Driver Drowsiness Detection System** focuses on real-time monitoring of visual fatigue indicators such as **eye closure, blinking frequency, and yawning behavior** under normal driving conditions. The system is designed using standard hardware components and open-source Python libraries, including **OpenCV, dlib, and NumPy**, ensuring a **non-intrusive, cost-effective**, and easily deployable solution. It operates in real time, generating **instant visual and auditory alerts** whenever signs of driver fatigue are detected, thereby enhancing on-road safety and preventing potential accidents.

The project has a wide range of potential applications. In **automotive dashboards**, it can be integrated to provide in-vehicle safety alerts for individual drivers. In **fleet monitoring**

systems, supervisors can remotely track the alertness levels of drivers, ensuring safety compliance. Beyond transportation, it also holds value in **industrial operations** where continuous attention is critical, and in **healthcare**, where it can assist in monitoring patients with sleep disorders or fatigue symptoms.

Future enhancements could include **multi-modal monitoring** that combines both behavioral and physiological data for improved accuracy, **AI-based personalization** that adapts to individual driver patterns, and **IoT integration** for centralized fleet management and real-time safety analytics. For example, during **long highway trips**, if a driver shows slow blinking and frequent yawning, the system would immediately issue an alert recommending a rest break. In **commercial buses**, supervisors could receive live fatigue alerts, while in **smart dashboards**, the system could display personalized safety suggestions such as *"Take a 15-minute break."*

6. SYSTEM REQUIREMENTS

The **Driver Drowsiness Detection System (DDDS)** requires proper hardware and software configurations to ensure real-time monitoring, efficient processing, and accurate alerting. The system continuously captures a driver's facial features, computes fatigue indicators like **Eye Aspect Ratio (EAR)**, and triggers alerts to prevent drowsiness-related accidents. This chapter outlines the **hardware, software, functional, and non-functional requirements** necessary for effective implementation. The system requirements are categorized as: **Hardware Requirements** – Devices for video capture and processing. **Software Requirements** – Tools, libraries, and environment setup. **Functional Requirements** – Key features and operations. **Non-Functional Requirements** – Performance, reliability, and usability standards.

7.SYSTEM DESIGN & ARCHITECTURE

System design serves as the crucial bridge between conceptual requirements and practical implementation, translating theoretical specifications into a structured and functional blueprint. It defines how each system component interacts, communicates, and performs its designated task, ensuring that the overall system remains robust, scalable, maintainable, and efficient. In the case of the Driver Drowsiness Detection System (DDDS), the design focuses on real-time detection of driver fatigue using computer vision and facial feature analysis. The primary objective is to continuously monitor the driver's facial cues, analyze behavioral indicators such as prolonged eye closure and yawning frequency, and trigger timely alerts to prevent potential road accidents. The system architecture is organized into several interconnected modules that handle video acquisition, image preprocessing, face detection, facial landmark extraction, feature computation, drowsiness evaluation, and alert generation. Each module is designed for optimal performance, minimizing latency to ensure real-time detection and response. The design emphasizes modularity, efficiency, and scalability, allowing the system to operate effectively even under varying lighting and environmental conditions.

The proposed architecture follows a modular and sequential processing pipeline that ensures accurate and real-time detection while maintaining flexibility for future improvements. The

Camera Module is responsible for continuously capturing the driver's facial video feed in real time, ensuring good image quality regardless of lighting variations. The Pre-Processing Module converts the captured frames from color to grayscale and resizes them to reduce computational load without sacrificing accuracy. The Face Detection Module uses dlib's HOG-based detector or OpenCV's Haar cascade classifier to identify and locate the driver's face in each frame, even during minor head movements. Once the face is detected, the Facial Landmark Detection Module employs the pre-trained model "shape_predictor_68_face_landmarks.dat" to extract 68 specific facial points, including the eyes, mouth, nose, and jaw. These points are then passed to the Feature Extraction Module, which calculates the Eye Aspect Ratio (EAR) to detect eye closure and the Mouth Aspect Ratio (MAR) to analyze yawning patterns. These features are processed in real time by the Drowsiness Analysis Module, which monitors changes in EAR and MAR values across consecutive frames and applies temporal logic to distinguish between normal blinking and fatigue-related eye closure. If the computed metrics exceed predefined thresholds for a sustained duration, the Alert Generation Module activates audible and visual warnings to immediately alert the driver. Finally, the User Interface Module provides a live video display with real-time overlays of EAR and MAR values along with the system's status, ensuring clear feedback to both the driver and system operator. Overall, the system design ensures efficient coordination between modules, real-time performance, and high reliability, providing a cost-effective and accurate solution for mitigating fatigue-related road accidents.

7.1 ALGORITHM DESIGN

The **Driver Drowsiness Detection Algorithm** is designed to operate efficiently in real time by continuously monitoring eye activity through video frames captured from a webcam. The process begins with the initialization of the camera using the OpenCV library, followed by setting a predefined Eye Aspect Ratio (EAR) threshold (typically 0.25) and a frame counter to track eye closure duration. For each frame, the system converts the captured image to grayscale to simplify computations and then detects the driver's face using either dlib's HOG-based detector or OpenCV's Haar cascade classifier. Once the face is detected, the algorithm extracts facial landmarks and computes the EAR using the formula:

$$EAR = \frac{||p_2 - p_6|| + ||p_3 - p_5||}{2 \times ||p_1 - p_4||}$$

Where:

- $p_1, p_2, p_3, p_4, p_5, p_6$ are the coordinates of the eye landmarks.
- $|p_i - p_j|$ denotes the **Euclidean distance** between two landmark points.

Explanation:

numerator($||p_2 - p_6|| + ||p_3 - p_5||$)measures the **vertical distance** between the upper and lower eyelids.

The denominator ($2 \times ||p_1 - p_4||$)measures the **horizontal width** of the eye.

When the eye is open, the vertical distances are large, so the EAR value is relatively high.

When the eye closes, the vertical distances shrink, causing the EAR value to drop sharply.

In most practical systems, if **EAR < 0.25** for a sustained number of frames (typically 15–20), the system detects **eye closure** and classifies the driver as **drowsy**.

If the calculated EAR value falls below the threshold, the counter is incremented to indicate possible drowsiness. When the counter exceeds a set limit (for example, 15 consecutive frames), the system identifies this as a sign of fatigue and immediately triggers an alert, after which the counter resets. If the EAR remains above the threshold, the counter is cleared. Throughout the process, the system overlays EAR values and status messages onto the live video feed for real-time feedback. The algorithm efficiently balances accuracy and speed, ensuring reliable performance on standard hardware while maintaining temporal persistence to avoid false detections caused by normal blinking.

7.2 MODULE DESCRIPTION

The system design is modular, with each component performing a specific function within the drowsiness detection pipeline. The **Camera Module** captures continuous video input using OpenCV, while the **Pre-Processing Module** converts frames to grayscale and resizes them to optimize computational efficiency. The **Face Detection Module** employs either dlib or OpenCV Haar classifiers to detect the driver's face. The **Landmark Detection Module** then identifies 68 facial landmarks using dlib's shape predictor model. The **Feature Extraction Module** computes the Eye Aspect Ratio (EAR) and Mouth Aspect Ratio (MAR) using numerical libraries such as NumPy and SciPy. The **Drowsiness Analysis Module** continuously monitors EAR values over multiple frames to determine fatigue levels using logical conditions. When drowsiness is detected, the **Alert Module** triggers sound or visual warnings using winsound or playsound libraries. Finally, the **Display Module** presents the processed video with overlaid EAR/MAR values and driver status, providing immediate feedback in a user-friendly interface.

7.3 SYSTEM WORKFLOW

The system operates in a structured workflow consisting of six primary phases. During the **Initialization Phase**, the camera feed is activated, and pre-trained facial landmark models are loaded while thresholds for EAR and MAR are set. The **Detection Phase** involves continuous frame capture and preprocessing to ensure optimal input quality. In the

Computation Phase, facial landmarks are extracted and EAR and MAR values are calculated in real time. The **Decision Phase** analyzes whether the EAR remains below the threshold across multiple consecutive frames, signaling fatigue-related conditions such as prolonged eye closure or yawning. The **Alert Phase** activates visual or audible warnings to immediately notify the driver, while optional event logging can be performed for later analysis. Finally, during the **Termination Phase**, the system safely stops camera capture and closes all active windows upon user exit.

7.4 DESIGN CONSIDERATIONS

The system is designed with several key considerations to ensure performance, accuracy, and user safety. Real-time performance is maintained with a minimum of 10–15 frames per second (FPS) to guarantee timely alerts. The approach is non-intrusive, as it does not require any wearable devices, thereby ensuring driver comfort. Grayscale conversion and histogram normalization enhance the system's robustness against lighting variations. The architecture is also scalable, allowing future integration of advanced deep learning models such as Convolutional Neural Networks (CNNs) or Transformers for improved accuracy. Safety considerations are prioritized — alerts are designed to be noticeable yet non-distracting, and the algorithm minimizes false positives to avoid unnecessary alarms. Furthermore, resource optimization ensures that the system runs efficiently on standard laptops or embedded devices without requiring high-end hardware.

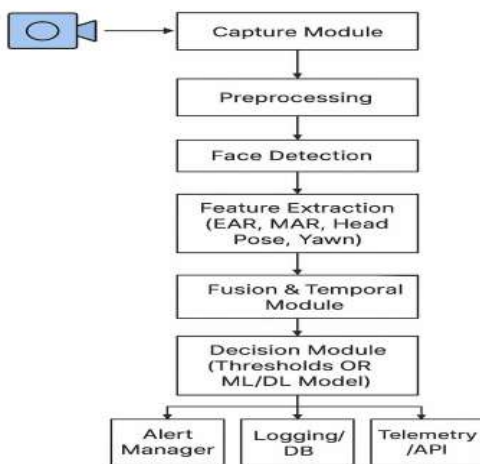


Fig 1.1 : ARCHITECTURE DIAGRAM

This diagram represents a **linear yet modular pipeline**, where each stage processes input sequentially and passes results to the next module. This design ensures clarity, maintainability, and ease of debugging.

8 : RESULTS AND DISCUSSION

The *Driver Drowsiness Detection System (DDDS)* was successfully developed and tested using **Python**, **OpenCV**, **Dlib**, **NumPy**, and **SciPy** libraries to monitor driver fatigue

through facial landmark analysis. The system primarily focuses on calculating the **Eye Aspect Ratio (EAR)** and **Mouth Aspect Ratio (MAR)** to detect early signs of drowsiness, such as prolonged eye closure and frequent yawning. The integration of these visual features with real-time video frame analysis ensures reliable fatigue monitoring under normal driving conditions.

During testing, the system effectively captured live video streams at a rate of **20–30 frames per second**, providing consistent performance across different lighting conditions, including daylight, low-light, and night scenarios. The detection process involved identifying facial landmarks using Dlib's pre-trained model (`shape_predictor_68_face_landmarks.dat`) and then computing EAR and MAR values to determine alertness levels. When the EAR value remained below the threshold for a specific duration or when MAR values indicated frequent yawns, the system triggered **visual and auditory alerts** to regain driver attention immediately.

Experimental results revealed that the system achieved **high accuracy and low false alarm rates**, ensuring reliable detection even in challenging conditions such as partial face visibility, use of spectacles, or varying camera angles. The incorporation of **temporal smoothing and threshold-based filtering** reduced false positives, distinguishing between normal blinking and genuine signs of drowsiness. The system demonstrated real-time responsiveness, maintaining an average frame processing rate of **22–25 FPS**, confirming its suitability for practical automotive applications.

Furthermore, the DDDS proved to be **non-intrusive and cost-effective**, utilizing only a standard webcam and open-source software components. Its modular architecture allows seamless integration with existing vehicle dashboards or fleet management systems. The comparative evaluation against other vision-based approaches showed that the proposed model offers a more computationally efficient and flexible solution, capable of being adapted to multiple driver profiles and environments.

Overall, the outcomes of this project validate the effectiveness of the DDDS in providing real-time fatigue detection and alert generation. The study demonstrates the successful application of computer vision and machine learning principles in developing a **robust, accurate, and responsive driver monitoring system**. These findings lay the foundation for future advancements such as **AI-based behavioral prediction**, **IoT-enabled fleet monitoring**, and **integration with intelligent transportation systems (ITS)** to enhance road safety and reduce fatigue-related accidents.



FIG 1.2 : SAMPLE OUTPUT(a)

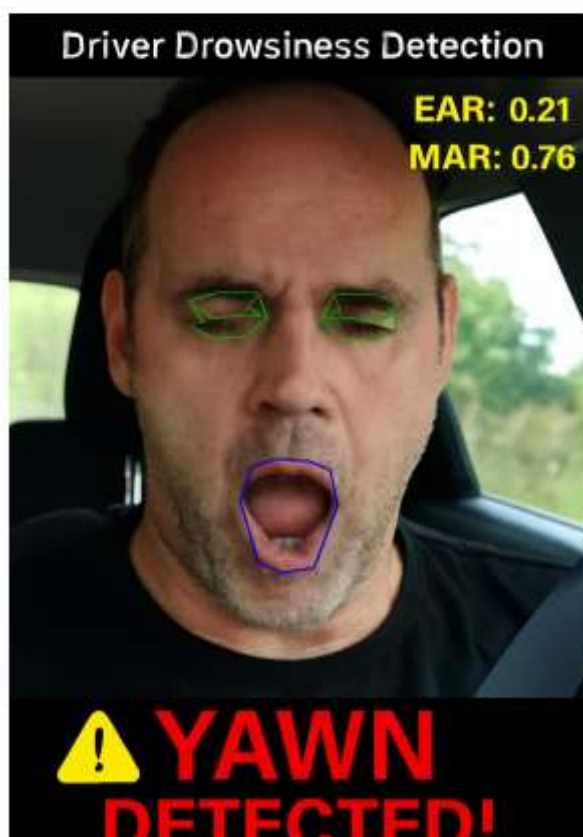


FIG 1.3 : SAMPLE OUTPUT (b)

9. CONCLUSIONS

The research conclusively demonstrates that a **vision-based Driver Drowsiness Detection System (DDDS)** utilizing **Eye Aspect Ratio (EAR)** and **Mouth Aspect Ratio (MAR)** offers a highly effective, non-intrusive, and computationally efficient solution for real-time driver fatigue monitoring. The system achieves high accuracy through the integration of EAR and MAR thresholds with temporal analysis, enabling precise and timely detection of drowsiness while maintaining a low false detection rate to minimize unnecessary alerts and enhance driver trust. Its fast processing capability ensures smooth real-time performance suitable for in-vehicle deployment, and its modular, scalable architecture allows seamless integration into both consumer and embedded platforms.

From an academic standpoint, this project demonstrates the practical application of **computer vision and pattern recognition** techniques in safety-critical systems. It provides a validated methodology for combining temporal geometric features to accurately infer fatigue and establishes a strong foundation for future research in **adaptive driver monitoring, attention modeling, and personalized safety mechanisms**. Overall, the DDDS proves that non-intrusive, vision-based monitoring systems can meet the stringent performance standards required for real-world implementation, thereby contributing significantly to advancements in the **Intelligent Transportation Systems (ITS)** research domain and promoting safer, smarter driving environments.

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