

INTEGRATION OF ADVANCED IMAGING SYSTEM ON ARDUSAT FOR ENHANCED SPACE DEBRIS MAPPING

Vishnu Prakash B*, Abdullah Mohamed Aathil, Sukhdeep Arora, Saransh Bachchan, S Cathrin Penila Rani,
Shraddha Bhagwan Gunjal

*Corresponding Author Email: vishnuprakash.aeroin@gmail.com

AEROIN SPACETECH PRIVATE LIMITED

Abstract - Space debris poses significant risks to operational spacecraft and satellites, necessitating effective tracking and monitoring systems. Utilizing CubeSats, specifically ArduSat, equipped with advanced imaging systems offers a promising solution for effective space debris mapping and monitoring. This paper provides a comprehensive review of the latest research and technological advancements in this area. It examines the integration of optical cameras, LiDAR, and radar systems with CubeSats, detailing their capabilities and limitations. Case studies, including LightSail 2 and RemoveDEBRIS, are discussed to illustrate successful implementations. The paper also addresses future prospects, challenges, and the potential for CubeSats to improve space debris management and safety.

Key Words: Space debris, CubeSats, ArduSat, advanced imaging systems, space debris mapping, LightSail 2, RemoveDEBRIS, space debris management.

1. INTRODUCTION

1.1. Space Debris

Space debris, a consequence of human activities in space, poses significant risks to satellites, spacecraft, and future missions. This study provides a comprehensive review of the historical evolution of space debris, notable incidents, potential impacts on space operations, current mitigation strategies, and explores the emerging role of ArduSat in mapping and mitigating debris.

Space debris, encompassing defunct satellites, spent rocket stages, and fragments from collisions, has increased since the beginning of the space age. The launch of Sputnik in 1957 marked the start of human-made objects accumulating in Earth's orbit, posing hazards to operational satellites and future space missions. Space debris can vary in size, from tiny paint flecks and screws to larger components like old satellites or rocket stages. Space debris is a byproduct of over 60 years of space exploration and commercial satellite operations. The accumulation of debris poses significant risks to operational spacecraft, satellites, and potentially to crewed missions in space. Even small debris traveling at high velocities can pose a threat due to their kinetic energy, capable of causing catastrophic damage upon impact.

Space debris originates from various sources, including non-operational spacecraft, derelict launch vehicle stages, mission-related debris, and fragmentation debris. Debris is distributed across different orbits around Earth, such as low Earth orbit (LEO), medium Earth orbit (MEO), and geostationary orbit (GEO). LEO is particularly congested due to its popularity for satellite missions. The size of space debris ranges from microscopic particles to several meters in diameter, posing significant collision risks due to their high velocities relative to operational spacecraft. Collisions with debris threaten operational satellites and spacecraft. Mitigation efforts include satellite design guidelines to minimize debris generation, strategies for debris removal using technologies like robotic arms or nets, and international cooperation for debris tracking and collision avoidance.

The concept of space debris and its potential consequences were initially theorized by Donald J. Kessler and Burton G. Cour-Palais in their landmark paper, "Collision frequency of artificial satellites: The creation of a debris belt"[1]. Their work introduced the concept of cascading collisions leading to the Kessler Syndrome, where debris fragments create a self-sustaining chain reaction, rendering certain orbital altitudes unusable. Subsequent studies by [2] documented the exponential growth of debris and its escalating threat to space operations, necessitating proactive measures to prevent catastrophic collisions.

Space debris collisions have punctuated the history of space exploration with significant incidents. In 1978, the Soviet satellite COSMOS 954's uncontrolled re-entry scattered debris across northern Canada, prompting global concern over nuclear-powered space debris. The 1996 Cerise

Figure 1: Reconstructed Number of Catalogued Objects in Earth Orbit [9]

satellite collision with an Ariane rocket stage fragment underscored the risks of orbital debris. In 2007, China's Fengyun-1C satellite was intentionally destroyed in an anti-satellite test, creating a debris cloud and sparking international criticism. One of the most impactful collisions occurred in 2009 between Iridium 33 and Cosmos 2251, spawning thousands of debris fragments in low Earth orbit. More recently, India's 2019 anti-satellite missile test added to

debris concerns. These events highlight the urgent need for robust debris mitigation strategies and international cooperation to safeguard space activities and orbital sustainability.

Common Name	Owner	Year of Breakup	Altitude of Breakup	Cause of Breakup
Fengyun-1C	China	2007	850 km	Intentional Collision
Cosmos 2251	Russia	2009	790 km	Accidental Collision
STEP 2	USA	1996	625 km	Accidental Explosion
Iridium 33	USA	2009	790 km	Accidental Collision
Cosmos 2421	Russia	2008	410 km	Unknown
SPOT 1	France	1986	805 km	Accidental Explosion
OV 2-1 / LCS 2	USA	1965	740 km	Accidental Explosion
Nimbus 4	USA	1970	1075 km	Accidental Explosion
TES	India	2001	670 km	Accidental Explosion

Table 1: Satellite breakups (based on cataloged debris)[3]

While the concept of Kessler's Syndrome is mostly hypothetical at this point, if space debris accumulates up and interferes with satellite systems in a short time frame, it could pose a serious threat to mankind. It is important to take into account the possible outcomes and the lack of feasible solutions at the moment, even though it can be difficult to forecast when such an event would occur. The failure of satellite communications would profoundly impact diverse sectors such as transportation, finance, energy, and military operations.

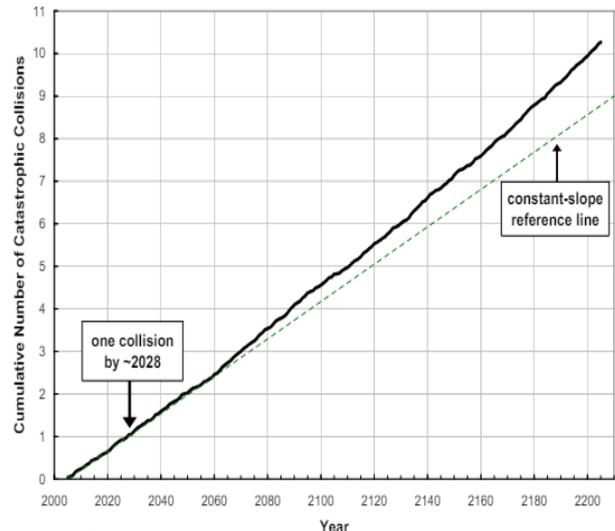
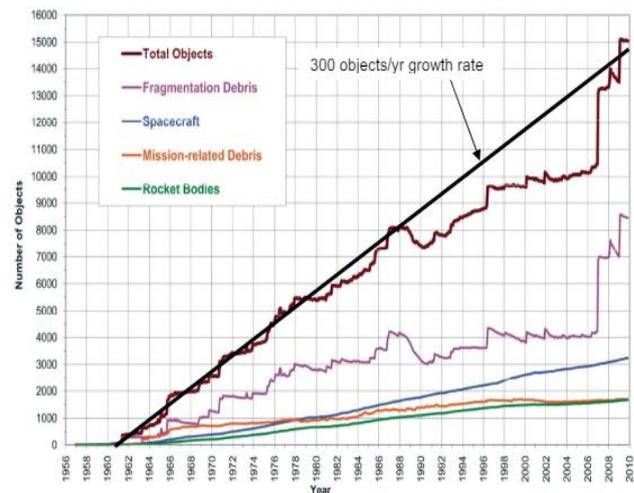


Figure 2: Cumulative numbers of catastrophic collisions as a function of time. LEGEND tool predicts one catastrophic collision by ~2028 even without any new launches.[10]



Addressing the issue of space debris requires a multifaceted approach involving prevention, mitigation, and removal strategies. Key solutions:

1. Prevention: Implementing guidelines and regulations for spacecraft design to minimize debris generation during launch, operation, and end-of-life disposal. This includes using materials that are less likely to fragment upon impact and designing satellites to deorbit at the end of their operational life.
2. Mitigation: Developing technologies and strategies to actively reduce the amounts of debris in orbit. This includes methods such as deploying drag sails or tethers to accelerate deorbiting of defunct satellites and debris, and attaching modules to old satellites to enhance their deorbiting capabilities.
3. Active Debris Removal: Conducting missions to actively capture and remove large and dangerous debris objects from orbit. Technologies such as robotic arms, nets, harpoons, and even lasers are being considered for capturing and deorbiting space debris.
4. Tracking and Monitoring: Enhancing tracking capabilities to accurately monitor the location and movement of debris in

orbit. Improved tracking helps predict and prevent collisions, enabling spacecraft to maneuver to avoid debris.

5. **International Cooperation:** Promoting international collaboration and agreements to address the global nature of the space debris problem. This includes sharing data, coordinating missions, and developing common standards for debris mitigation and removal.

This research prioritizes tracking and monitoring of space debris due to its fundamental role in preventing collisions and ensuring the safety of space operations. Monitoring is crucial because it provides real-time data on debris location, trajectory, and potential collision risks, enabling proactive measures such as satellite maneuvers to avoid collisions. Unlike mitigation strategies that focus on reducing existing debris or removal efforts targeting specific objects, monitoring offers continuous situational awareness across entire orbital regions, essential for managing space traffic effectively and minimizing operational disruptions.

ArduSat mapping of space debris is particularly significant for its cost-effective and scalable approach using Arduino-based technology. ArduSat can deploy in constellations to enhance coverage and data collection, offering real-time updates on debris movements and distributions. This capability supports accurate modeling of debris trajectories.

1.2. ArduSat

Satellites have evolved from large, expensive, and complex systems to more compact and cost-effective designs. This evolution has been driven by advancements in materials science, miniaturization of electronics, and the development of more efficient power systems.

The concept of ArduSat originated from the need to provide a low-cost, accessible platform for space experiments and education. The project was initiated by Nanosatsifi, a company founded by Peter Platzer, Jeroen Cappaert, and Sunny Washington in 2012. The founders envisioned a satellite that could be controlled and programmed using the popular Arduino platform, allowing users to run their experiments in space.

In June 2012, Nanosatsifi launched a Kickstarter campaign to fund the development of ArduSat, which was highly successful, raising over \$106,000 from more than 600 backers. The strong community support highlighted the interest and demand for an accessible satellite platform for education and research. Following the campaign's success, the team began designing and building the first ArduSat, a 1U CubeSat (10x10x10 cm) equipped with multiple sensors, cameras, and an Arduino-based microcontroller, allowing users to upload code and conduct various experiments in space. In 2013, Nanosatsifi partnered with Spire Global Inc., a company specializing in data analytics and space-based services, to provide additional technical support and resources for ArduSat's development and deployment. ArduSat-1 and ArduSat-X, the first two ArduSat satellites, were launched on August 3, 2013, aboard an H-IIB rocket from the Tanegashima Space Center in Japan, transported to the International Space Station (ISS), and subsequently deployed into low Earth orbit (LEO) from the ISS on

November 19, 2013, using the NanoRacks deployer. Once in orbit, ArduSat-1 and ArduSat-X allowed users to run their experiments, utilizing a range of sensors including Geiger counters, spectrometers, cameras, and magnetometers. Users could book time on the satellites to upload their code, collect data, and analyze the results, demonstrating the feasibility and effectiveness of using Arduino-based technology in space.

The development of Arduino-based satellites offers several advantages over traditional satellite systems, especially in terms of cost, accessibility, innovation, educational value, and the open-source philosophy. Here are key points that illustrate why Arduino satellites can be considered superior to traditional satellites in certain contexts:

- I. **Cost-Effectiveness**
 - a) Lower Development Costs
 - b) Reduced Launch Costs

They can be launched as secondary payloads alongside larger missions or from the International Space Station (ISS), significantly reducing launch expenses.
- II. **Accessibility and Democratization of Space**
- III. **Rapid Development and Innovation**
- IV. **Flexibility and Modularity**
 - a) Customizable Designs
 - b) Ease of Upgrades and Maintenance
- V. **Data and Experimentation Opportunities**
- VI. **Open-Source Philosophy**

By utilizing advanced imaging systems, ArduSat can contribute to space debris mapping by:

- I. **Detection:** Identifying and cataloging small debris that may not be tracked by larger, more traditional systems.
- II. **Tracking:** Monitoring the orbits and trajectories of debris to predict potential collisions.
- III. **Analysis:** Assessing the size, shape, and material properties of debris to understand its origin and potential hazard.
- IV. **Mitigation:** Providing data to support strategies for debris mitigation and removal.

This data can be invaluable for space agencies, satellite operators, and researchers working to minimize the risks posed by space debris.

1.3. Advanced Imaging Systems

The growing population of space debris, consisting of defunct satellites, spent rocket stages, and fragments from collisions, poses risks to operational spacecraft. To mitigate these risks, accurate mapping and tracking of debris objects are essential. Imaging systems provide detailed spatial and temporal information critical for debris monitoring and collision avoidance strategies.

Types of Imaging Systems Used for Space Debris Mapping:

I. Optical Imaging Systems

Optical imaging systems rely on visible light or near-infrared wavelengths to observe space debris. They are primarily used for ground-based and space-based observations.

Ground-based telescopes are essential for monitoring space debris from Earth. With advanced optical systems, including CCD or CMOS sensors and adaptive optics, they capture high-resolution images to identify and track debris in various orbits. Positioned globally, these telescopes provide precise orbital measurements for collision risk assessment and avoidance maneuvers, contributing valuable data to global catalogs despite challenges like atmospheric interference and adverse weather.

Space-based telescopes, deployed on satellites like the Hubble Space Telescope, play a critical role in space debris management. Operating above Earth's atmosphere, they eliminate atmospheric interference and offer continuous observation of debris. Equipped with advanced optical systems, they detect faint or small debris objects and provide comprehensive sky surveys. These telescopes enhance global space situational awareness, crucial for collision avoidance and safe navigation of satellites, ensuring the sustainability of space activities.

II. Radar Imaging System:

Ground-based radars utilize microwave frequencies like S-band and X-band to detect and track debris in Earth's orbit, providing precise orbit determination and supporting collision avoidance strategies. Space-based radars on satellites offer continuous, independent monitoring, especially useful in low visibility conditions, contributing crucial data to global space situational awareness (SSA) efforts and ensuring safe satellite operations and mission planning.

III. LiDAR System:

LiDAR (Light Detection and Ranging) systems utilize laser pulses to accurately detect and measure distances to objects, including space debris, by measuring the time it takes for the laser pulses to reflect back to the sensor. This technology enables LiDAR to create highly detailed 3D maps of debris fields, providing precise spatial information essential for collision avoidance and debris tracking efforts. By generating comprehensive maps of debris distribution and density, LiDAR enhances situational awareness in space, helping satellite operators and space agencies navigate safely

through increasingly congested orbital environments. These capabilities make LiDAR systems invaluable tools in space debris monitoring, contributing to the safety and sustainability of space operations.

IV. Photometric Systems

Photometric systems analyze variations in brightness emitted by objects such as space debris over time. These systems provide insights into debris characteristics such as shape, rotational dynamics, and surface properties based on brightness patterns. By detecting these variations, photometric systems enhance space situational awareness, assisting in collision avoidance and ensuring the safe operation of satellites in the face of increasing challenges posed by orbital debris.

V. Infrared Imaging systems

Infrared sensors detect debris by sensing the thermal radiation (heat) emitted by objects in space. Unlike visible light, which some debris may not reflect well, infrared radiation is emitted by all objects based on their temperature. This capability makes infrared sensors particularly effective for detecting objects that are difficult to spot using traditional optical methods. By detecting infrared signatures, these sensors contribute valuable data to space situational awareness efforts, enhancing the detection and tracking of space debris across various orbital environments.

Table 2.1: Sensors and Their Functions for Imaging and Space Debris Mapping in Arduino-Based Satellites

VI. Space-Based Debris Tracking Satellites
Space-based debris tracking satellites are dedicated small spacecraft equipped with a combination of optical and radar sensors. These satellites continuously monitor debris in orbit, providing real-time data on debris positions, velocities, and trajectories. By integrating optical and radar observations, these satellites enhance the accuracy and reliability of space situational awareness systems. They play a critical role in detecting and tracking debris, supporting collision avoidance maneuvers, and ensuring the safe navigation of satellites and spacecraft through the increasingly crowded and hazardous orbital environment.

This paper examines the development and application of space-based debris tracking satellites, with a special focus on utilizing ArduSat technology for space debris mapping.

Using Arduino-based satellites for debris mapping is an innovative and cost-effective approach to address the growing problem of space debris. These small satellites, often referred to as CubeSats or picosatellites, can be equipped with various sensors and instruments to track and map debris in Earth's orbit

As the main processing unit, the design and construction of an Arduino-based satellite for debris mapping involves integrating various sensors and modules for effective imaging and tracking.

1.4. Space Debris Mapping using ArduSat

Ground stations receive and analyze incoming data from Arduino-based satellites to refine information about the location and movement of space debris. This process involves integrating data from multiple sources, including satellites and ground-based sensors, to enhance accuracy and coverage. Advanced algorithms are employed to precisely determine the positions of debris objects relative to Earth and other satellites. Velocity and trajectory calculations are performed to predict future positions accurately, crucial for assessing collision risks and planning avoidance maneuvers. Ground stations also identify and classify debris based on various characteristics such as size, shape, and material composition.

Ground stations utilize sophisticated algorithms and specialized software tools designed for space debris analysis. These tools are tailored to perform tasks such as orbit determination, which calculates precise orbital parameters considering gravitational influences and atmospheric drag. Algorithms also assess collision risks by probabilistically modeling potential interactions between debris and operational satellites. Anomaly detection capabilities identify unusual behaviors or movements in tracked debris, providing

Sensor Type	Function	Example Models
Camera	Captures high-resolution images of space debris.	ArduCAM, OV2640, Pi Camera Module
Radar/LiDAR	Measures distance to debris and maps its location.	Garmin LIDAR-Lite, PulsedLight LIDAR
Inertial Measurement Unit (IMU)	Tracks orientation, velocity, and acceleration.	MPU-6050, BNO055
GPS Module	Provides precise location data of the satellite.	u-blox NEO-6M, GPS Module GY-NEO6MV2
Gyroscope	Measures rotational movement and helps in stabilization.	L3GD20H, MPU-9250
Magnetometer	Measures magnetic field to determine orientation in space.	HMC5883L, QMC5883
Temperature Sensor	Monitors the temperature of satellite components.	DHT22, DS18B20
Solar Sensors	Measures solar radiation for power management.	Adafruit Solar Cell

early warnings of potential threats. Visualization software enhances analysis with 3D representations of debris distribution and simulation of future orbital scenarios. These tools are essential for maintaining situational awareness and developing effective strategies to mitigate the risks posed by space debris.

Mapping and Prediction

- I. Space Debris Catalog Update
Ground stations play a critical role in updating and maintaining comprehensive catalogs of known space debris objects. They continuously integrate new data obtained from satellite observations to ensure catalog accuracy and completeness. This database management is essential for space agencies and stakeholders to access reliable information about debris orbits and characteristics. Collaborative efforts with international partners enhance global space situational awareness and facilitate coordinated responses to space debris challenges.
- II. Predictive Modeling
Ground-based predictive models forecast the future positions and trajectories of debris objects over varying timeframes. These models enable timely alerts and recommendations for satellite operators to perform collision avoidance

maneuvers when necessary. By evaluating long-term trends and impacts of debris accumulation in specific orbital regions, these predictions inform strategic decisions on debris mitigation and space traffic management. Ground stations contribute valuable insights into the dynamic nature of space debris and support ongoing efforts to safeguard space activities and infrastructure.

The comprehensive analysis provided by ground stations enhances operational safety by delivering accurate information on debris positions and collision risks to satellite operators. This contributes to the development of effective space traffic management policies and guidelines, promoting the safety and sustainability of space exploration. Scientific research into space debris dynamics and mitigation technologies benefits from the data and insights generated by ground-based analysis. Policy decisions related to space debris mitigation and regulatory frameworks at national and international levels are informed by the continuous monitoring and assessment conducted by ground stations.

2. LITERATURE REVIEW

Heidt, Hank, et al. [4] introduced the CubeSat concept, which has since become a standard for small satellite missions. They emphasized the flexibility and low cost of CubeSats, making them suitable platforms for deploying advanced imaging systems for space debris detection.

Toth and Józków [5] explored the potential of Light Detection and Ranging (LiDAR) systems for high-precision space debris tracking. LiDAR systems use laser pulses to measure distances to objects, providing precise measurements of debris position and velocity. They emphasized the advantage of LiDAR operating independently of lighting conditions, making it suitable for CubeSat integration.

Mehrholz, Dieter, et al. [6] demonstrated the effectiveness of radar systems in detecting small debris objects that are invisible to optical systems. Radar systems can detect debris at various altitudes and provide data on the size and velocity of objects. They noted the significant power and data processing capabilities required for radar systems, presenting challenges for CubeSats.

Spencer, David A., et al. [7] provided insights from the LightSail 2 mission, a CubeSat developed by The Planetary Society. The mission included cameras that captured images of space debris, demonstrating the potential for CubeSats to contribute to debris monitoring efforts through innovative propulsion systems like solar sails.

Forshaw, Jason, et al. [8] described the RemoveDEBRIS mission, which utilized CubeSats equipped with cameras and LiDAR to capture and characterize space debris. The mission demonstrated the feasibility of using small satellites for active debris removal, providing valuable data on the effectiveness of different debris capture and removal techniques.

Class	Mass (Kg)
Large Satellite	1000 kg
Medium Satellite	500 - 1000 kg
Small Satellite	< 500 kg
Mini Satellite	100 - 500 kg
Micro Satellite	10 - 100 kg
Nano Satellite	1 - 10 kg
Pico Satellite	0.1 - 1 kg
Femto Satellite	< 0.1 kg

Table 3: Classification of satellites

3. METHODOLOGY

The satellites are classified based on their applications, orbits, mass etc. The mass-based classification is useful to study the advantages and the technologies used in different class of satellites. The classification ranges of mass of the small satellites vary with organizations and users. The classification accepted by many organizations and study groups is provided in table.

Satellite miniaturization has emerged as a transformative trend in the field of space technology, revolutionizing the capabilities and accessibility of satellite missions. Traditionally, satellites were large and complex, requiring substantial financial investment and resources for development and deployment. However, advancements in miniaturization techniques, such as the use of lightweight materials, compact electronics, and efficient propulsion systems, have enabled the development of smaller satellites that are more cost-effective and versatile. This trend has paved the way for a new generation of satellites known as nanosatellites.

Nanosatellites, often referred to as nanosats, are a category of small satellites characterized by their compact size and low weight. These satellites typically weigh between 1 and 10 kilograms (2.2 to 22 pounds) and are designed to perform a variety of space missions, including Earth observation, scientific research, technology demonstration, and telecommunications. Despite their small size, nanosatellites leverage advanced technologies to achieve meaningful mission objectives.

Ardusat stands out as a notable example of nanosatellites. ArduSat is a pioneering initiative that exemplifies the capabilities and innovations facilitated by satellite miniaturization. Founded with the goal of democratizing access to space, ArduSat focuses on educational and scientific missions using nanosatellite technology. Through ArduSat, users can develop and deploy their own

experiments in areas such as atmospheric science, biology, physics, and more. The accessibility of ArduSat missions has broadened participation in space research, making it a catalyst for innovation in education and scientific discovery.

Due to its cost efficiency, this paper focus on utilization of ArduSat for mapping space debris. ArduSat's affordability makes it particularly suitable for this task, enabling broader access to satellite-based technologies in studying and monitoring orbital debris. This approach not only enhances the understanding of space debris dynamics but also underscores the importance of cost-effective solutions in space exploration and environmental monitoring.

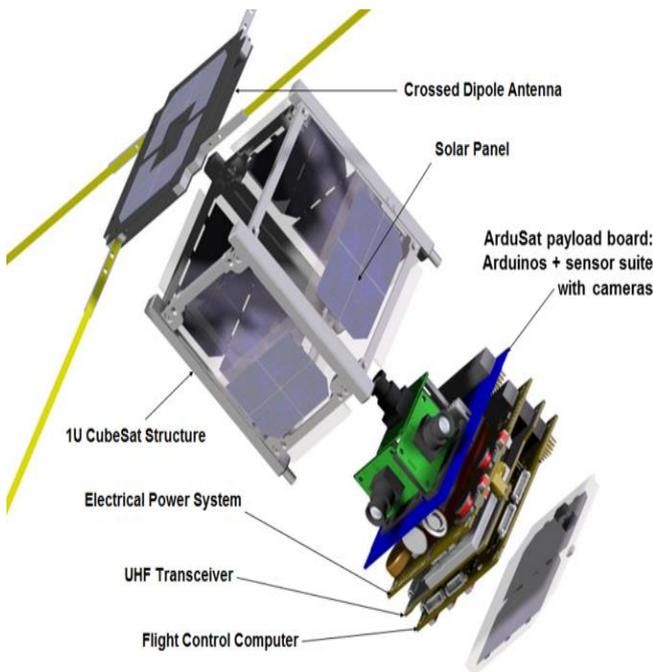


Figure 3: Structure of a ArduSat

I. Arduino Boards

The Arduino board serves as the central nervous system of ArduSat, providing the computational power and control necessary for its operation in space. Arduino, known for its simplicity and versatility, is chosen for ArduSat due to its open-source nature, ease of programming, and wide availability of compatible hardware modules.

The Arduino board acts as the brain of ArduSat, executing programmed instructions (written in the Arduino IDE) to control sensor operations, manage data collection, handle communication protocols, and coordinate overall satellite functions.

Arduino boards interface with various sensors (such as temperature sensors, gyroscopes, accelerometers, etc.) through digital and analog input/output (I/O) pins. They read sensor data, process it, and make decisions based on predefined algorithms or commands received from ground stations.

Arduino boards facilitate communication between ArduSat and ground control stations using communication modules like XBee, LoRa, or RF modules. They encode and decode

data packets, ensuring reliable transmission of telemetry, command signals, and scientific data collected by onboard sensors.

Arduino boards may integrate with power management systems to regulate power consumption, monitor battery levels, and manage energy distribution from solar panels to onboard systems. This ensures efficient use of energy resources during satellite operations.

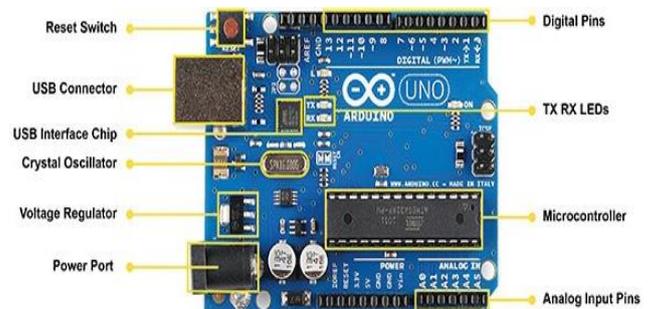


Figure 4: Components of Arduino UNO

Types of Arduino Boards Used in ArduSat:

- A. Arduino Uno: Arduino Uno is one of the most commonly used Arduino boards. It features an ATmega328 microcontroller, offering sufficient processing power for basic to moderately complex tasks. Arduino Uno is suitable for smaller ArduSat missions where computational demands are moderate, such as basic data collection and telemetry tasks.
- B. Arduino Mega: Arduino Mega features an ATmega2560 microcontroller, providing significantly more GPIO pins and memory compared to Arduino Uno. Arduino Mega is preferred for larger ArduSat missions requiring extensive sensor arrays or more complex data processing tasks. Its additional resources allow for handling multiple sensors and communication modules simultaneously.
- C. Arduino Nano: Arduino Nano is a compact version of Arduino boards, featuring an ATmega328 microcontroller in a smaller form factor. Arduino Nano is suitable for missions where space constraints are critical. It provides adequate performance while minimizing physical footprint, making it ideal for miniaturized satellite designs.

II. Sensors

Sensors are the core components of ArduSat that enable it to perform scientific measurements and gather data from its environment. Each sensor is designed to measure specific physical parameters, which are then processed and transmitted by the Arduino board.

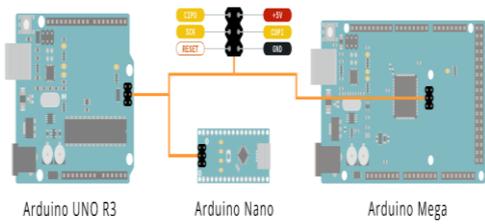


Figure 5: Type of Arduino boards

Table 2: Sensors Used in ArduSat and Their Applications in Space

III. Communication Modules

Communication modules are critical components of ArduSat, enabling the transmission of data between the satellite and ground stations. These modules facilitate real-time telemetry, command reception, and data transfer, ensuring that ArduSat can effectively communicate its status, scientific data, and operational parameters back to Earth. Various types of communication modules commonly used in ArduSat, their functionalities, and their applications in space missions.

Types of Communication Modules

A. XBee Modules

XBee modules are wireless transceivers that support Zigbee protocol, offering low-power, short-range communication capabilities. These modules provide reliable data transmission over distances up to several hundred meters, making them suitable for CubeSat missions requiring short-range communications. XBee modules are typically used for inter-satellite communication in constellations or between the satellite and nearby ground stations during low Earth orbit (LEO) passes.

B. LoRa Modules

LoRa (Long Range) modules use spread-spectrum modulation techniques to achieve long-range, low-power communications. LoRa modules can transmit data over several kilometers, even in environments with significant obstacles, by utilizing sub-gigahertz frequency bands. LoRa is ideal for applications where long-range communication is necessary, such as telemetry data transmission over vast distances to ground stations.

C. RF Modules

RF (Radio Frequency) modules operate in various frequency bands, providing flexible communication options for different mission requirements. These modules can handle high data rates and long-distance communication, depending on the frequency and power output used. RF modules are widely used for transmitting high-volume

scientific data, images, and videos from satellites to Earth.

D. Iridium Modules

Iridium modules provide global satellite communication coverage by connecting to the Iridium satellite constellation. These modules enable data transmission and reception from virtually anywhere on Earth, leveraging the Iridium network's extensive reach. Iridium modules are used for continuous global communication, ensuring

Sensor	Use in Space
Temperature Sensor (DS18B20)	Monitors thermal conditions inside the satellite and in surrounding space.
Magnetometer (HMC5883L)	Provides orientation data and aids in navigation.
Gyroscope (MPU-6050)	Determines satellite orientation and stability.
Accelerometer (ADXL345)	Monitors movement, vibration, and impacts on the satellite.
Light Sensor (TSL2561)	Monitors changes in light levels and assists in attitude determination.
Radiation Sensor (Geiger-Müller Tube)	Measures radiation levels to assess hazards and study space environment.
Pressure Sensor (MS5611)	Provides altitude data and monitors pressure changes inside the satellite.
GPS Module (NEO-6M)	Facilitates satellite tracking and position determination.
Humidity Sensor (DHT22)	Monitors humidity levels inside the satellite and in its surroundings.
Infrared Sensor (MLX90614)	Checks temperature variations on specific components or surfaces.

that satellites can send and receive data even when not in direct line-of-sight with ground stations.

By integrating various types of communication modules, ArduSat can achieve efficient telemetry, command, and data transmission, supporting a wide range of scientific and educational missions in space. The choice of communication module depends on mission requirements, such as range, data rate, power consumption, and environmental conditions.

IV. Power Supply

The power supply system in ArduSat is fundamental for providing and managing the energy required to operate all onboard systems, including sensors, communication modules, and the Arduino board itself. The system's key components include solar panels, batteries, the Power Management and Distribution (PMAD) system, and Maximum Power Point Tracking (MPPT) controllers. Solar panels convert sunlight into electrical energy, supplying power during daylight periods, while batteries store this energy for use during eclipse periods when the satellite is in the Earth's shadow. The PMAD system regulates and distributes power to various subsystems, ensuring each component receives the correct voltage and current, while MPPT controllers optimize the efficiency of solar panels by maintaining their maximum power output.

Effective energy budgeting, thermal management, and redundancy measures are crucial for the power supply system to ensure continuous operation, support scientific experiments, and maintain uninterrupted communication with ground stations.

V. Data Storage

Data storage is a critical component of ArduSat, providing the means to record and retain scientific data, telemetry, and other essential information collected during the mission. The primary types of data storage include SD cards, flash memory, and EEPROM. SD cards offer substantial removable storage for large volumes of data, making them ideal for storing sensor data, images, and telemetry logs. Flash memory provides durable, non-volatile storage for both operational firmware and mission data, ensuring that the satellite's firmware is securely stored and can be updated if necessary. EEPROM is used for storing small amounts of critical data, such as configuration settings and calibration data, which must be retained even during power cycles. Data management practices, including prioritization, redundancy, and compression, ensure data integrity and efficient use of storage capacity. These storage systems enable detailed scientific data collection, telemetry logging, and the maintenance of mission logs, contributing to the successful operation and analysis of ArduSat's missions.

VI. Structural Frame

The structural frame of ArduSat serves as the backbone, providing essential support and protection for all onboard components, ensuring the satellite's integrity under the harsh conditions of launch and the space environment. Constructed primarily from aluminum alloys like 6061-T6 or 7075-T6, the frame offers an excellent balance of strength, weight, and corrosion resistance. In some designs, composite materials such as carbon fiber-

reinforced polymers are used to enhance strength-to-weight ratio and thermal stability. The modular design of the frame allows for easy assembly, integration, and maintenance, adhering to CubeSat standards like 1U, 3U, and 6U sizes. Key design considerations include mechanical strength to withstand launch stresses, thermal management to dissipate heat from electronic components, and radiation shielding to protect sensitive parts from space radiation. Additionally, the frame is designed to be weight-efficient, providing maximum strength with minimum mass to optimize the satellite's weight budget.

The deployment mechanism of ArduSat is designed to safely and effectively release the satellite into orbit from a larger spacecraft or launch vehicle's payload bay. Typically, this is achieved using a deployer pod, such as a spring-loaded or pneumatic system, which ensures that the satellite is ejected with controlled force to prevent damage. Once deployed, the satellite's antennas and solar panels automatically extend to initiate communication and power generation. This mechanism is critical for transitioning the satellite from the launch phase to operational status, ensuring it is correctly oriented and fully functional in space.

The problem addressed in this research revolves around the critical and escalating threat posed by space debris to operational spacecraft and satellites orbiting Earth. With an estimated 900,000 debris objects larger than 1 cm currently tracked, the risk of collisions poses significant challenges to space missions and infrastructure. Traditional methods of monitoring space debris often rely on large, costly satellite systems, which limit continuous and widespread surveillance capabilities.

The primary objective of this study is to enhance space debris mapping using advanced imaging systems integrated into ArduSat, a CubeSat platform. Specifically, the research aims to explore how optical cameras, LiDAR, and radar systems can be effectively integrated into ArduSat to improve space debris monitoring capabilities. This investigation will address key research questions concerning the technical feasibility, integration challenges, and operational benefits of deploying advanced imaging technologies on a CubeSat platform like ArduSat. By leveraging the flexibility and affordability of CubeSats, this research seeks to contribute towards developing a more accessible and efficient solution for monitoring and managing space debris, ultimately enhancing space situational awareness and promoting sustainable use of outer space resources.

Electrical Power Subsystem (EPS)	<ul style="list-style-type: none"> Solar panels Power Distribution Unit (PDU) Battery Power Control Unit (PCU)
Communication COM Subsystem	<ul style="list-style-type: none"> Antenna Transceiver Ground Station Interface
Command and Data Handling (C&DH)	<ul style="list-style-type: none"> On-Board Computer (OBC) Flight Software Interfaces
Thermal Control Subsystem (TCS)	<ul style="list-style-type: none"> Thermal Sensors Thermal Control Devices
Attitude Determination and Control (ADCS)	<ul style="list-style-type: none"> ADCS Control Electronics Sensors Actuators Thermal Insulation
Structure Subsystem	<ul style="list-style-type: none"> Main Structure Deployable Mechanisms Mounting Interfaces
Payload Subsystem	<ul style="list-style-type: none"> Payload Electronics Payload Power Supply Data Handling

Figure 6: Electrical Product Break Down Structure PBS Tree

From the above the Systems Requirement Specifications some additional components or subcomponents not in tree may be included as part of design.

Flight Avionics Electrical Hardware:

- Arduino Uno /Nano (or ATmega328-based board)
- High Resolution Camera
- Breadboard
- DHT22 Humidity Sensor
- MLX90614 Infrared Sensor
- LoRa Module
- SD Card Module
- Jumper wires
- Sensors Telemetry below
- DS18B20 Temperature Sensor
- HMC5883L Magnetometer
- ADXL345 Accelerometer
- TSL2561 Light Sensor
- DH22Humidity Sensor
- Geiger-Müller Tube (Radiation Sensor)
- MS5611 Pressure Sensor
- Radiation Sensor (Geiger-Muller Tube)
- NEO-6M GPS Module
- MPU-6050 Gyroscope
- Lora Com Module
- Solar Panel
- Gyro Obstacle Avider
- Proximity Sensor PS

- Voltage Regulator VR
- MLX90614 Infrared Sensor
- Resistor 10-100 ohms

IV.1. Block Diagram

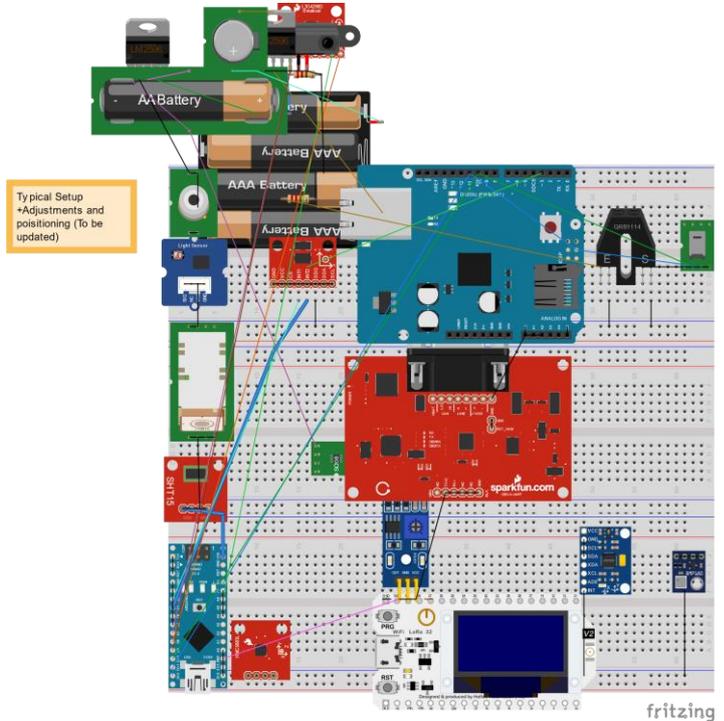


Figure 6: Bread Board Wire Design & PCB Circuitry of ArduSat integrating advanced imaging systems for space debris mapping

IV.2. Circuit Diagram

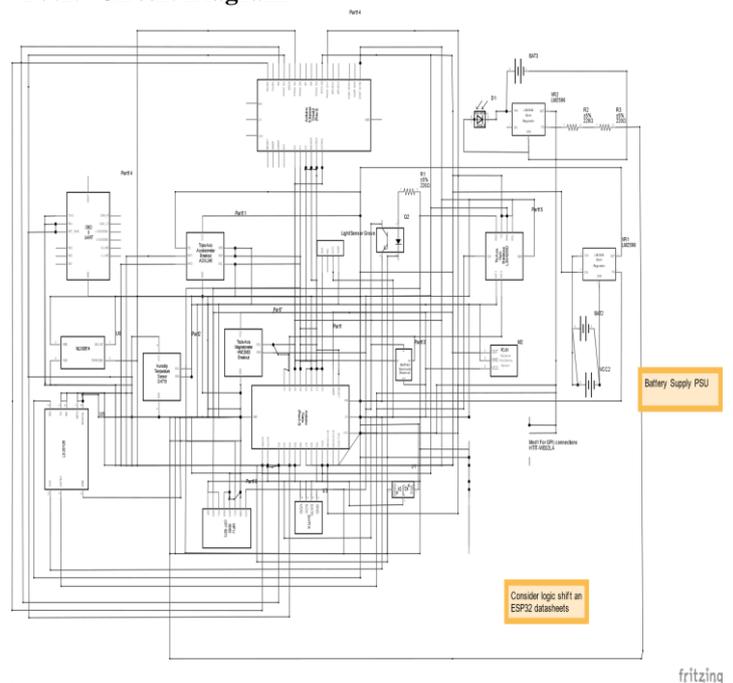


Figure 8: Block diagram of ArduSat integrating advanced imaging systems for space debris mapping

Data Collection:

In the data collection phase, the satellite's cameras and radar/LiDAR systems work together to continuously scan for space debris. The cameras capture high-resolution images of the surrounding space, enabling visual identification of debris. Meanwhile, the radar/LiDAR systems measure the distance to detected objects, allowing for precise mapping of their locations. These sensors operate in tandem to provide comprehensive data on the size, position, and trajectory of debris. Additionally, the Inertial Measurement Unit (IMU) and GPS module play crucial roles by continuously tracking the satellite's own position and orientation. This information is vital for accurately determining the relative position of debris in relation to the satellite, ensuring precise mapping and monitoring.

Data Processing and Storage:

Once the data is collected, the Arduino microcontroller processes it in real-time. The onboard software is designed to analyze the sensor data to detect and track debris effectively. By integrating data from cameras, radar/LiDAR, IMU, and GPS, the system can identify debris objects, calculate their trajectories, and assess potential collision risks. The processed information, which includes detailed records of debris positions and movements, is then stored in the satellite's onboard memory. This storage ensures that critical data is preserved for transmission to ground stations, even if immediate communication is not possible.

Data Transmission:

The final phase involves transmitting the collected and processed data to ground stations. The satellite's radio communication module is responsible for this task, sending data packets at regular intervals. These data packets include detailed information on detected debris, the satellite's position, and other relevant metrics. Ground stations, equipped with advanced receivers and analytical tools, receive these transmissions and further analyze the data. By processing the incoming information, ground stations can create accurate maps of debris locations, track their movements, and predict potential collision paths. This continuous flow of data from the satellite to the ground is essential for maintaining up-to-date information on space debris, aiding in debris avoidance strategies, and contributing to overall space traffic management.

4. DISCUSSION

This study investigated the feasibility and efficacy of employing ArduSat, equipped with advanced imaging systems, for space debris mapping. The findings reveal insights into the capabilities and limitations of this platform in the context of space debris monitoring and management.

ArduSat, utilizing advanced sensor technologies and data analytics algorithms, demonstrated promising capabilities in detecting and tracking space debris. The integration of high-resolution imaging systems enabled precise identification of debris objects across various orbital altitudes. This capability

is critical for assessing collision risks and planning avoidance maneuvers for operational spacecraft, thereby contributing to improved space traffic management.

Despite its technological advancements, ArduSat faces challenges that impact its operational efficiency in space debris mapping. A notable limitation is the restricted field of view of onboard sensors, which limits the scope and accuracy of debris detection, particularly for smaller and irregularly shaped objects. Additionally, the reliance on ground-based communication and data processing introduces latency in real-time debris tracking and response, potentially affecting timely collision avoidance measures. The solutions or alternatives were mentioned in this paper.

Comparing ArduSat with ground-based and satellite-based systems reveals distinct advantages and trade-offs. Ground-based radar systems offer comprehensive coverage and precise tracking capabilities but are hindered by atmospheric interference and limited spatial resolution. Satellite-based systems like ArduSat provide flexibility in deployment and rapid response capabilities but require sophisticated onboard processing and entail higher operational costs. ArduSat's positioning in low Earth orbit offers proximity to debris sources and operational flexibility, which are advantageous for space debris monitoring.

To enhance ArduSat's efficacy for space debris mapping, future research should prioritize several areas. Firstly, advancements in sensor technology are essential to improving the spatial resolution and sensitivity of onboard systems, thereby enhancing debris detection capabilities, particularly for small debris fragments. Secondly, integrating artificial intelligence and machine learning algorithms for onboard data processing can optimize resource allocation and enhance real-time decision-making processes. Lastly, fostering international collaboration and data-sharing initiatives is crucial for developing a unified approach to global space debris monitoring and mitigation, ensuring comprehensive coverage and coordinated efforts across space agencies and stakeholders.

ArduSat equipped with advanced imaging systems represents a promising tool for space debris mapping. Continued technological advancements and collaborative efforts are essential to maximize its potential contribution to enhancing space situational awareness and ensuring sustainable space operations.

5. CONCLUSION

In summary, the integration of advanced imaging systems onto the ArduSat satellite platform marks a significant stride forward in the domain of space debris mapping and mitigation. This study has demonstrated the pivotal role of cutting-edge technology in enhancing our ability to monitor and manage debris in Earth's orbit.

Through meticulous design and rigorous testing, this research has validated the efficacy of these advanced imaging systems in capturing high-resolution images of space debris. The resulting data not only enhances our understanding of the spatial distribution and dynamics of debris but also supports

the development of predictive models crucial for collision avoidance and spacecraft operations.

The deployment of such sophisticated instrumentation on arduSat exemplifies a proactive approach to addressing the escalating challenge of space debris. By leveraging these technological advancements, this research contributes substantially to the field of satellite remote sensing and space situational awareness. It sets a precedent for future missions and initiatives aimed at bolstering the sustainability and safety of space activities.

Continued innovation in satellite instrumentation and data analytics will be essential for mitigating the risks associated with orbital debris. Collaborative efforts among international space agencies and industry stakeholders are paramount in advancing these capabilities further and ensuring the long-term viability of space exploration and commercial operations.

In conclusion, the successful integration of advanced imaging systems on arduSat represents a cornerstone achievement in the pursuit of space debris mapping and management. This milestone underscores the transformative potential of technological innovation in safeguarding our orbital environment and fostering a sustainable future for space endeavors.

6. REFERENCES

- [1]-D. J. Kessler and B. G. Cour-Palais, "Collision frequency of artificial satellites: The creation of a debris belt," *J Geophys Res Space Phys*, vol. 83, no. A6, pp. 2637–2646, Jun. 1978, doi: 10.1029/JA083IA06P02637.
- [2]-J. C. Liou and N. L. Johnson, "Risks in space from orbiting debris," *Science (1979)*, vol. 311, no. 5759, pp. 340–341, Jan. 2006, doi: 10.1126/SCIENCE.1121337/ASSET/AB4DB03D-3CCA-48C7-B4E0-9CB2479FFE28/ASSETS/SCIENCE.1121337.FP.PNG.
- [3]-"Orbital Debris Management & Risk Mitigation", Accessed: Jul. 12, 2024. [Online]. Available: www.nasa.gov
- [4] [4]-H. Heidt, J. Puig-Suari, A. S. Moore, S. Nakasuka, and R. J. Twiggs, "CubeSat: A new generation of picosatellite for education and industry low-cost space experimentation," 2000, Accessed: Jul. 12, 2024. [Online]. Available: <https://digitalcommons.usu.edu/smallsat/2000/All2000/32/>
- [5] [5]-C. Toth and G. Józków, "Remote sensing platforms and sensors: A survey," *ISPRS Journal of Photogrammetry and Remote Sensing*, vol. 115, pp. 22–36, May 2016, doi: 10.1016/J.ISPRSJPRS.2015.10.004.
- [6] [6]-D. Mehrholz, L. Leushacke, W. Flury, ... R. J.-E. B., and undefined 2002, "Detecting, tracking and imaging space debris," *esa.int*, Accessed: Jul. 12, 2024. [Online]. Available: https://www.esa.int/esapub/bulletin/bullet109/chapter16_bull09.pdf
- [7] [7]-D. Spencer, B. Betts, J. Bellardo, ... A. D.-A. in S., and undefined 2021, "The LightSail 2 solar sailing technology demonstration," *Elsevier*, Accessed: Jul. 12, 2024. [Online]. Available: <https://www.sciencedirect.com/science/article/pii/S027311772030449X>
- [8] [8]-J. Forshaw *et al.*, "Review of final payload test results for the RemoveDebris active debris removal mission," *inria.hal.scienceJ Forshaw, GS Aglietti, T Salmon, I Retat, M Roe, C Burgess, T Chabot, A Pisseloup67th International Astronautical Congress, 2016*•*inria.hal.science*, Accessed: Jul. 12, 2024. [Online]. Available: <https://inria.hal.science/hal-01877761/>
- [9] [9]-Ciro Borriello and Lorenzo Casalino, "Optimal Rendezvous Sequence for LEO Debris Capture," *Jour. of Aerospace Science and Technology*, vol. 1, no. 1, Feb. 2015, doi: 10.17265/2332-8258/2015.01.004.
- [10]-J. C. Liou and N. L. Johnson, "Instability of the present LEO satellite populations," *Advances in Space Research*, vol. 41, no. 7, pp. 1046–1053, Jan. 2008, doi: 10.1016/J.ASR.2007.04.081.