

Millimeter-Wave V2V Communication: Unveiling Challenges and Opportunities for Safe and Efficient Transportation

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Abstract

Millimeter-wave technology promises to revolutionize vehicle-to-vehicle communication. Unlike other systems, mmWave has a broad spectrum with high bandwidth, enabling vehicles to continuously share information as the precise location, speed and sensor data freely. This means that cars can perceive their environment better in that they become aware of their surroundings. mmWave V2V communication enables the exchange of information in real-time, and this is crucial in promoting cooperative perception which ensures improved road safety as it quickens how cars recognize or react to possible dangers. However, additional studies in mmWave technology are necessary to effectively address the problem of interference and signal reliability in high-speed traffic conditions. Moreover, the creation of inexpensive mmWave transceivers and signal processing algorithms is needed to make it viable for everyday vehicles. As these challenges are tackled, mmWave V2V communication can bring about the next revolution in the field of transportation, which allows for the development of a fully connected and intelligent transportation infrastructure.

Keywords- Millimetre-wave, V2V communication, Signal processing algorithms, High bandwidth.

I. INTRODUCTION

The ever-growing number of vehicles on the road necessitates innovative solutions to improve traffic flow and safety. V2V communication allows vehicles to exchange information such as position, speed, and direction, enabling them to "talk" to each other. This real-time data sharing fosters cooperative awareness, improving driver reaction times and facilitating maneuvers. Traditional V2V communication relies on technologies like Dedicated Short-Range Communication (DSRC) with limitations in data rate and range. Here, mmWave technology emerges as a disruptive force, offering the potential to revolutionize V2V communication and transform transportation. Imagine a future where congested roads become a

thing of the past. With mmWave, vehicles can anticipate each other's movements, leading to smoother traffic flow and potentially reducing the stop-and-go nature of current commutes. This technology holds the promise of not only enhancing safety but also optimizing fuel efficiency and creating a more predictable driving experience for everyone.

II. OVERVIEW OF MILLIMETER WAVE TECHNOLOGY

Millimeter-wave (mmWave) technology operates in the electromagnetic spectrum between 30 GHz and 300 GHz, offering a vast spectrum compared to traditional V2V communication solutions. This translates to significantly higher bandwidth, enabling the real-time exchange of complex data like sensor information (LiDAR, Radar) crucial for autonomous

driving and advanced safety features. While the range of mmWave signals is shorter than some existing V2V technologies, its directional beams can focus transmission, potentially mitigating interference in dynamic traffic environments. Additionally, mmWave boasts exceptionally low latency, a critical factor for applications requiring fast reaction times, like collision avoidance maneuvers. These combined advantages position mmWave as a disruptive force with the potential to revolutionize V2V communication and transform transportation.

Imagine cruising confidently, not with white-knuckled tension, but with a sense of calm trust. With the help of mmWave technology, your car will be in constant dialogue with others on the road, anticipating slowdowns before they even appear in your line of sight. A discreet notification on your dashboard, perhaps akin to a virtual chorus of brake lights from far ahead, will prompt your car to seamlessly adjust its speed, avoiding the stop-and-go chaos that plagues traditional commutes. This isn't science fiction, it's the very near future of transportation powered by mmWave.

The benefits extend far beyond a more relaxing drive. Picture a highway where large trucks electronically lock into a fuel-saving formation, gliding together in a precise dance of efficiency – a dramatic shift from the gas-guzzling, single-lane giants of today. Envision a world where your car receives real-time alerts about a hidden pothole or a stalled vehicle around the bend, giving you ample time to react and maintain a safe distance. This is the power of cooperative driving enabled by mmWave, a technology poised to revolutionize transportation. By transforming individual vehicles into a connected ecosystem, mmWave paves the way for a future that is not only safer and more efficient, but fundamentally changes the way we experience the road.

III. CHALLENGES IN V2V COMMUNICATION USING MILLIMETER WAVE TECHNOLOGY

While mmWave offers exciting possibilities for V2V communication, several challenges need to be addressed for widespread adoption. The dynamic nature of traffic presents difficulties in maintaining reliable signal transmission. Developing accurate channel models that predict signal propagation and mitigate interference caused by buildings, other vehicles, and weather conditions is crucial. Researchers are actively exploring machine learning

and ray tracing techniques to create more robust channel models. Additionally, mmWave signals are highly directional, requiring efficient beam steering techniques to ensure consistent communication as vehicles move. Advancements in antenna design with multiple elements and improved algorithms for beamforming are being explored to achieve dynamic and precise beam steering capabilities. Furthermore, cost-effective mmWave transceivers suitable for mass production in vehicles are necessary for widespread implementation. Research in integrated circuit design and manufacturing processes is ongoing to reduce the cost and complexity of mmWave transceivers, making them more feasible for everyday vehicles. Addressing these challenges through advancements in signal processing algorithms, antenna design, transceiver technology, and channel modelling is key to unlocking the full potential of mmWave V2V communication and paving the way for a future of connected and intelligent transportation.

V2V communication is about to get a major upgrade with millimeter wave (mmWave) technology. Imagine cars on the road acting like a team, sharing information instantly. This could be data on location, speed, and even planned maneuvers. With mmWave, these real-time exchanges could revolutionize how we drive. Think of it as creating a super-fast Wi-Fi network between vehicles, leading to features like automatic collision avoidance and smoother traffic flow.

However, mmWave technology isn't without its challenges. Unlike traditional systems, mmWave's high frequencies are easily blocked by obstacles like buildings or bad weather. This limitation in range is like trying to shout across a vast field – the signal might not reach its destination.

To overcome these hurdles, engineers are developing clever solutions. One approach is called beamforming, which acts like a special megaphone for the mmWave signal. By focusing the signal in a specific direction, it can reach its target vehicle more effectively.

In essence, mmWave holds immense potential for V2V communication, but it requires careful planning and innovative techniques. It's about finding the sweet spot between harnessing the power of high-speed data exchange and addressing the limitations of the technology itself. By doing so, we can create a future where cars talk to each other, paving the way for safer and more efficient roads for everyone.

IV. LITERATURE SURVEY

Researchers are exploring the potential of millimetre-waves for vehicles to communicate with each other. This technology promises ultra-fast data exchange, perfect for sharing sensor information between cars. Imagine vehicles sharing real-time blind spot data or upcoming hazards, leading to a significant improvement in road safety through cooperative driving. However, there's a hurdle. Millimeter-waves are weaker and more prone to blockage by other vehicles on the road. To address this challenge, researchers are meticulously analysing data collected from various driving environments. They believe that by refining how we predict how these signals travel, we can develop reliable and high-speed communication systems for future intelligent transportation systems. This would pave the way for a new era of connected and safer roads, revolutionizing the way we travel [1].

Millimeter-wave technology is being investigated for vehicle communication, potentially leading to safer roads. Cars sharing sensor data on blind spots and hazards could enable cooperative driving. However, millimetre-waves are weaker and more easily blocked by other vehicles. Engineers are analyzing data from various driving environments to refine how these signals travel in order to develop reliable and high-speed communication systems for future intelligent transportation systems. This could revolutionize travel by creating connected and safer roads. Traffic safety regulations and millimeter-wave frequency allocations in Europe, the United States, and Japan were reviewed. Short-range and long-range radar radio frequencies were analyzed for compatibility with communication standards. A radio channel model was developed to study how signals propagate at different wavelengths over various distances. Ultra-wideband radio communication was determined to be suitable due to the wide millimeter-wave bandwidth available. The study also investigated multiple access techniques to enable communication between multiple vehicles within a group. Finally, potential architectures for communicating-radars were proposed [2].

Beamforming, a technique that focuses radio waves into tight beams, is crucial for V2V communication in mmWave 5G due to the high signal loss at these frequencies. However, keeping these beams aligned between constantly moving vehicles is a challenge. This paper explores two beam management strategies: anchored refinement and fine tracking. Anchored refinement offers a reliable approach that uses fewer

resources, while fine tracking recovers from misalignment quicker but demands more resources. Ultimately, the best strategy depends on the desired balance between communication performance and resource usage. The paper highlights the need for further research to address interference and resource sharing in beamformed V2V networks [3].

Millimeter-wave technology is revolutionizing the way vehicles communicate. Unlike traditional methods, mmWave offers significantly faster data transfer rates. This is essential for the future of transportation, as vehicles become increasingly equipped with sensors like radars, cameras, and LiDARs. These sensors generate vast amounts of data that are critical for advanced driver-assistance systems (ADAS) and autonomous vehicles. By enabling high-speed data exchange between vehicles, mmWave paves the way for real-time sharing of information like location, speed, and surrounding hazards. This improved communication can significantly enhance traffic safety and efficiency. However, mmWave technology also presents challenges. The shorter range and higher susceptibility to blockage by obstacles compared to lower-frequency signals require innovative solutions. Additionally, efficiently directing the signal between moving vehicles (beamforming) adds another layer of complexity. Despite these hurdles, mmWave holds immense promise for the future of V2X communication, laying the groundwork for a safer and more efficient transportation system [4].

Car-to-car communication is revving up for the fast lane of data thanks to millimetre waves. These high-frequency bands promise huge capacity for features like advanced safety systems and in-car entertainment. However, keeping the signal strong is a challenge due to constantly moving vehicles, network shifts, and pesky obstacles. To address this, a new method for managing resources in mm Wave V2V communication has been proposed. It analyzes data on signal paths and vehicle data queues to create optimal connections and fine-tune signal beams for each link. Simulations show this approach keeps data flowing smoothly, significantly improving reliability, minimizing delays, and boosting overall throughput compared to traditional methods [5].

Self-driving cars, needing a 360-degree view, rely on various sensors to navigate. But their own sensors can only see so far. Millimeter-wave (mmWave) technology acts like a walkie-talkie for these cars, allowing them to communicate with each other.

Imagine car A using mmWave to "ask" car B what's behind a building or around a blind corner! By sharing sensor data, cars can effectively extend their perception range. This is like gaining superpowers to see through obstacles. With a more complete picture of the road, self-driving cars using mmWave can navigate more safely and efficiently. It's like having a team effort on the road, constantly sharing information to avoid surprises and ensure a smooth ride. While individual sensors have limitations, mmWave creates a cooperative network. Think of it as a carpool lane for information. Cars can relay what their cameras and lidars detect, like accidents or stopped vehicles hidden from view. This shared awareness extends a car's "vision" beyond its physical sensors, similar to how animals use echolocation to navigate in darkness. By combining data, self-driving cars using mmWave can anticipate situations better, improving reaction times and reducing the risk of accidents. It's a communication revolution for autonomous vehicles, paving the way for a safer and more efficient future of transportation [6].

Imagine self-driving cars with a combination of super sight and night vision! A novel approach for car-to-car communication (V2X) is being explored that merges the strengths of millimeter-wave (mmWave) radar and cameras. mmWave radar, with its long reach and ability to see through challenging weather, acts like super sight, excelling at detecting objects' movement and distance. However, it struggles with details, like the difference between a car and a motorcycle. Cameras, on the other hand, provide high-resolution images with clear details, like night vision. But their range is limited, especially in low-light conditions. By fusing these two technologies, V2X communication gains significant advantages. The radar provides a long-range view, like spotting a car far down the road even in fog. The camera then fills in the details, allowing the car to identify it as a red sedan, not just a moving blip. This combined data allows self-driving cars to not only see further but also understand their surroundings more precisely. It's like having a more complete picture, crucial for safe navigation. Additionally, this approach offers built-in redundancy. If heavy rain hinders the camera, the radar data can still guide the car safely. This ensures that autonomous vehicles can make informed decisions even in less-than-ideal conditions, paving the way for a safer and more reliable future of transportation [7].

Cars of the future will be like rolling data centers, packed with sensors that constantly gather information about their surroundings. This creates a massive need

for robust and high-speed communication between vehicles (V2V) to share this data and enable features like cooperative perception. Here's where millimeter-wave (mmWave) technology steps in. It offers a wide swath of the radio spectrum, perfect for transmitting large amounts of data quickly. Think of it as a multi-lane highway compared to the narrow, congested roads of traditional wireless technologies. But there's a catch! To truly harness the power of mmWave for V2V communication, we need to understand how these signals behave as they travel between vehicles. This field of study is called mmWave V2V channel modeling and measurement. This article delves into the latest research on this topic. It explores existing methods for measuring and modeling these channels, providing a roadmap for researchers. It even showcases recent experiments conducted in the 60 GHz band to see how mmWave signals behave under real-world conditions, with vehicles moving and potentially blocked by buildings or other obstacles. The future holds exciting challenges. Researchers are constantly working to refine our understanding of mmWave V2V channels. This includes developing more sophisticated models that can account for complex factors like multipath propagation (signals bouncing off objects), the high sensitivity of mmWave to weather conditions, and the dynamic nature of traffic itself. By overcoming these challenges, we can unlock the full potential of mmWave and pave the way for a future of safer, more efficient, and truly connected intelligent transportation systems [8].

The vision of seamless traffic flow with self-driving cars hinges on robust communication for cooperative perception. While millimeter-wave (mmWave) technology offers high data rates for V2X communication, its limitations in range and blockage by obstacles pose a significant challenge. This research proposes a novel relay strategy that addresses these limitations while incorporating a critical aspect often neglected: information value. Imagine a network of autonomous vehicles receiving traffic data via mmWave. Traditionally, relaying would simply repeat all messages. This research proposes an intelligent filtering system. Vehicles assess the information they receive based on its relevance to their immediate needs. A critical event like an accident far ahead holds significantly more value than routine traffic updates. The proposed approach leverages a model that considers a car's "awareness range" – the distance it needs to perceive its surroundings for safe navigation. This awareness range dictates the information value a message holds for a specific vehicle. Through complex mathematical models encompassing network

density and mmWave signal range, the researchers analyze the effectiveness of this information-centric relay strategy. The findings demonstrate a significant improvement in overall communication reliability within the network. This paves the way for further development of intelligent relay strategies that prioritize valuable information for cooperative perception in autonomous vehicles. This approach can contribute to a future where self-driving cars collaborate seamlessly, enhancing safety, efficiency, and ultimately, the overall driving experience [9].

The emergence of 5G technology brings exciting possibilities for vehicle-to-vehicle (V2V) communication using millimeter-wave (mmWave) frequencies. This technology, termed Giga-V2V (GiV2V), holds immense potential for applications like automated car platooning, which necessitates high-speed data transfer for precise vehicle coordination. To establish a standardized approach for GiV2V communication, a dedicated standard is currently under development by 3GPP, the governing body for 5G mobile technology. In the interim, researchers are exploring the applicability of existing mmWave technologies. This study investigated the potential of Wireless Gigabit Alliance (WiGig) technology, commonly used for indoor devices based on the IEEE 802.11ad standard. WiGig offers gigabit wireless connectivity in the 60 GHz band, with a range of approximately 10 meters. Its commercialization success in applications like internet access points showcases its potential. To assess WiGig's suitability for GiV2V communication, researchers built a testbed using commercially available devices mounted on vehicles. Experiments were conducted on a real-world campus environment and city roads with varying speed limits. While the study revealed limitations due to short communication range and disconnections caused by vehicle speed variations, it also highlighted the technology's impressive data transfer capabilities. This suggests WiGig could be a potential candidate for GiV2V communication, although further development is crucial to address the identified limitations and ensure reliable long-range connectivity for future autonomous vehicle applications [10].

V. MILLIMETER-WAVE CHANNEL MEASUREMENTS

The utilization of mmWave frequencies for V2V communication introduces novel challenges and opportunities in wireless vehicular networks. Both the European Union and the United States have allocated specific frequency bands for Intelligent Transportation

Systems (ITS), primarily focusing on the 5.9 GHz band, with additional attention given to the 2.4 GHz and 5 GHz bands. However, due to spectrum scarcity below 6 GHz, interest has surged in enabling 5G vehicular communications at mmWave frequencies. In Europe, bands such as 63–64 GHz, 76–77 GHz, and 77–81 GHz have been allocated for V2V communications, while in the United States, the IEEE 802.11ad and 802.11ay standards have been specified for mmWave-based physical layers, allowing for high bandwidths and data rates up to 100 Gb/s as shown in Fig.1. Traditional V2V communication systems typically operate in the sub-6 GHz bands depicted on the left side of the image. These frequencies offer a narrower bandwidth, akin to a single-lane road. Information travels reliably over longer distances because signal strength weakens less at these lower frequencies. In contrast, mmWave communication ventures into a much higher frequency territory, ranging from 30 GHz to 300 GHz. This translates to a significantly wider bandwidth, imagine a multi-lane highway compared to the single lane. This broader bandwidth allows for a much higher volume of data to flow freely between vehicles, facilitating the exchange of complex information like high-resolution sensor data. Recent regulatory proposals in the US, such as authorizing operations at 28, 37, and 39 GHz, and making 64–71 GHz available for unlicensed mobile use, further facilitate the use of mmWave frequencies for vehicular communications. Understanding the channel characteristics in various environments, including line-of-sight (LOS) and non-line-of-sight

(NLOS) scenarios, is crucial for optimizing mmWave V2V communication systems. Measurements at mmWave frequencies have revealed significant path loss, small-scale fading, delay spread, and Doppler spread, influenced by factors such as vehicle obstruction, building reflections, and diffraction effects. Despite limited studies, efforts to characterize mmWave V2V channels are underway, emphasizing the need for comprehensive measurements and analysis to inform the design and deployment of reliable and efficient mmWave V2V communication systems. Related work can be found in [4].

VI. MILLIMETER-WAVE CHANNEL MODELLING

Modelling for mmWave vehicle-to-vehicle (V2V) communication encompasses various techniques aimed at understanding and predicting the behaviour of radio propagation in vehicular environments at millimetre-wave frequencies. Several types of

modelling approaches are employed to capture the complex characteristics of mmWave V2V channels:

A. Deterministic models: Deterministic model for mmWave V2V communication simulate the propagation of electromagnetic waves with a focus on individual signal paths. These models offer detailed insights into signal behaviour, accounting for factors such as reflections, diffractions, and scatterings. By tracing the path of each signal ray as it interacts with surrounding objects, deterministic models provide a granular understanding of how radio waves propagate in complex vehicular environments. They are particularly suitable for analyzing specific scenarios with known geometry, such as urban canyons or highway settings. However, their computational intensity can be a limitation, especially in scenarios with numerous reflecting surfaces, which may hinder scalability for large-scale simulations. Nonetheless, deterministic models remain invaluable tools for gaining in-depth insights into mmWave channel characteristics and optimizing V2V communication systems for real-world deployments.

B. Statistical models: Statistical models for mmWave V2V communication focus on capturing the statistical

properties of channel characteristics such as path loss, shadowing, and multipath fading. Unlike deterministic models, which provide detailed insights into individual signal paths, statistical models generalize channel behaviour across diverse environments. They offer scalability and flexibility, making them suitable for modelling various scenarios encountered in vehicular communication. By analyzing empirical data and applying statistical techniques, these models can predict channel parameters with reasonable accuracy, facilitating system design and optimization. However, their lack of granularity may limit their ability to capture specific propagation effects in certain scenarios, and they often rely on empirical data for calibration and validation, which can introduce uncertainties. Despite these limitations, statistical models serve as valuable tools for understanding the overall statistical behaviour of mmWave V2V channels.

C. Hybrid models: Hybrid models for mmWave V2V communication integrate deterministic and statistical approaches to achieve a balance between accuracy and efficiency. By combining detailed insights from deterministic ray tracing with the scalability of statistical modelling, these hybrid models offer a

Model Type	Bandwidth				Antenna Position	Frequency Selectivity	Stationarity
Deterministic models	Wideband	External to vehicle	Dynamic	High - 1 GHz and above			
Stationary models	Variable	Variable Vehicle-mounted or external	Stationary	Moderate-100 MHz to 1 GHz			
Hybrid models	Flexible	Variable Vehicle-mounted or external	Dynamic	Moderate-100 MHz to 1 GHz			
Machine Learning	Flexible	Variable Vehicle-mounted or external	Dynamic				Moderate-100 MHz to 1 GHz

Table.1: MM-Wave Channel Modelling

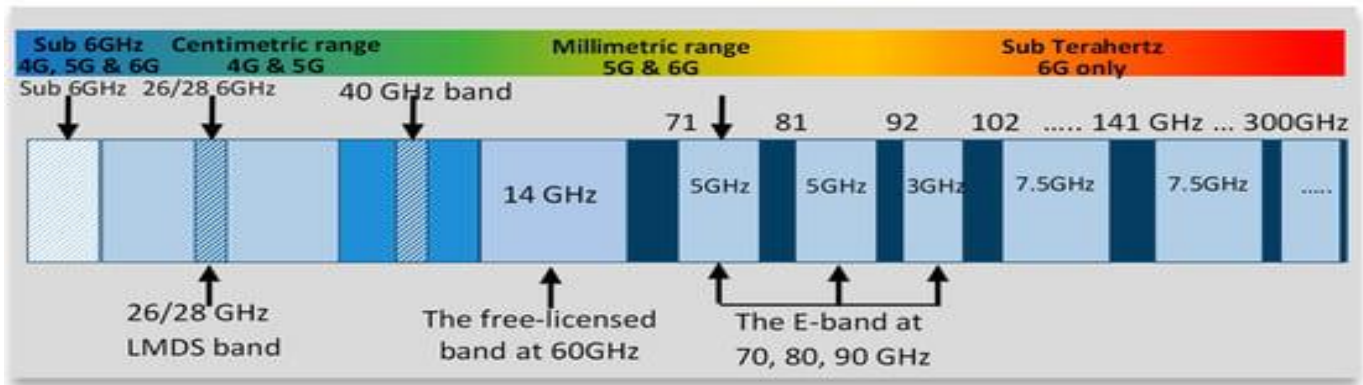


Fig.1: Candidate Bandwidths for millimetre-wave

comprehensive framework for analyzing channel characteristics across diverse environments. They provide detailed insights into specific scenarios while also enabling generalization to larger-scale simulations. Hybrid models are particularly useful for capturing complex propagation effects in realistic environments, such as urban streets or highway settings, where both deterministic and statistical aspects play crucial roles. However, the integration of deterministic and statistical components can introduce complexities, requiring careful calibration and validation to ensure accuracy. Despite these challenges, hybrid models represent a promising approach for accurately modelling mmWave V2V channels and optimizing communication systems for real-world deployment.

D. Machine Learning models: Machine learning approaches for mmWave V2V communication leverage algorithms to learn complex mappings between input features and channel characteristics from empirical data. These models offer flexibility and adaptability, allowing them to capture nonlinear relationships and intricate interactions within the channel environment. By analyzing large datasets of channel measurements, machine learning models can predict channel parameters and behaviours with high accuracy, facilitating system design and optimization. However, they are heavily reliant on the quality and representativeness of training data, which may introduce biases or inaccuracies. Additionally, the interpretability of machine learning models can be limited, making it challenging to understand the underlying physical mechanisms driving their predictions. Despite these challenges, machine learning techniques hold great promise for enhancing our understanding of mmWave V2V channels and improving the performance of communication systems in dynamic vehicular environments.

Form Table.1. The best modelling approach for V2V communication utilizing mmWave technology often lies in a hybrid model that integrates deterministic and statistical methods. Such an approach capitalizes on the strengths of both approaches while mitigating their individual limitations. Deterministic models excel in providing detailed insights into specific scenarios, capturing precise propagation effects accurately. Conversely, statistical models offer a broader understanding of channel behaviour across diverse environments. By integrating these approaches, a hybrid model can provide comprehensive insights into V2V communication channels, balancing accuracy with scalability. This flexibility allows for tailored analyses, adjusting the level of detail based on the complexity of the environment and computational resources available. Ultimately, the hybrid approach offers a robust framework for optimizing system performance, ensuring reliability, and facilitating real-world deployment of mmWave V2V communication systems [11].

VII. FUTURE CHALLENGES

Navigating the landscape of V2V communication using mmWave technology presents an array of future challenges that demand attention. One significant hurdle lies in addressing the scalability of mmWave systems to accommodate the growing demand for high-bandwidth applications while ensuring reliability and low latency. Achieving robustness in adverse weather conditions and mitigating signal attenuation due to obstacles like buildings and foliage remains a critical challenge. Additionally, the integration of mmWave technology into existing communication infrastructure necessitates careful planning to ensure seamless interoperability and compatibility. Overcoming regulatory barriers and spectrum allocation issues is paramount for widespread deployment, especially considering the scarcity of available mmWave spectrum. Moreover, ensuring

cybersecurity and privacy in V2V communication systems is imperative to safeguard sensitive data exchanged between vehicles. Furthermore, developing cost-effective and energy-efficient hardware solutions capable of meeting the stringent requirements of mmWave communication poses a significant challenge. Addressing these challenges will require interdisciplinary collaboration and innovative approaches to unlock the full potential of mmWave V2V communication for safer and more efficient transportation systems.

VIII. CONCLUSION

In conclusion, V2V technology utilizing mmWave holds immense potential to revolutionize transportation systems by enabling high-speed, low-latency communication between vehicles. The advantages of mmWave technology, including high data rates, wide bandwidth, and potential for low interference, make it well-suited for supporting a myriad of safety and convenience applications in vehicular networks. However, the successful implementation of mmWave V2V communication faces several challenges, such as scalability, signal attenuation, spectrum allocation, interoperability, cybersecurity, and hardware constraints. Overcoming these challenges will require concerted efforts from researchers, policymakers, and industry stakeholders to develop robust solutions that ensure reliable and secure communication while addressing regulatory and infrastructure requirements. Despite these challenges, the continued advancement of mmWave V2V technology holds promise for enhancing road safety, reducing congestion, and enabling the realization of connected and autonomous vehicles, ultimately leading to safer, smarter, and more efficient transportation systems.

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