

Railway Track Monitoring System Using Computer Vision

Prof. Puneetha.

Assistant Professor,
Department of CSE,
K S School of Engineering
and Management,
Bengaluru, India
puneetha@kssem.edu.in

Rakesh M

UG Scholar
Department of CSE,
K S School of Engineering
and Management,
Bengaluru, India
rakeshgm10@gmail.com

Balaji N

UG Scholar
Department of CSE,
K S School of Engineering
and Management,
Bengaluru, India
balajishetty36@gmail.com

Shashank D D

UG Scholar
Department of CSE,
K S School of Engineering
and Management,
Bengaluru, India
shashankgowda1144@gmail.com

Chinmai P

UG Scholar
Department of CSE,
K S School of Engineering and
Management,
Bengaluru, India
chinmaipyadav@gmail.com

Abstract: Railway track monitoring is a critical aspect of railway infrastructure maintenance, ensuring safe and efficient transportation. Traditional inspection methods often involve manual assessments, which can be time-consuming, labor-intensive, and prone to human error. With advancements in computer vision and artificial intelligence, automated railway track monitoring has emerged as a reliable solution to enhance safety and efficiency. This paper presents a comprehensive analysis of a computer vision-based railway track monitoring system that utilizes image processing and machine learning techniques to detect anomalies such as cracks, track misalignment, and obstacles. The study explores various methodologies employed in automated track inspection, highlighting the significance of real-time monitoring and data-driven decision-making. Additionally, this research examines the role of deep learning models in improving defect detection accuracy and reducing maintenance costs. By integrating smart surveillance and AI-driven analytics, the proposed system aims to optimize railway infrastructure management, ensuring enhanced safety and operational reliability.

Keywords: Railway track monitoring, Computer vision, Deep learning, Image processing, Anomaly detection, Track defect detection, Artificial intelligence, Real-time monitoring, Infrastructure maintenance, Safety enhancement.

I.

INTRODUCTION

Railway track monitoring is essential for ensuring the safety and efficiency of rail transport systems. The presence of structural defects such as cracks, misalignments, and obstructions can lead to severe accidents, making early detection and prevention crucial. Traditional inspection methods rely heavily on manual labor, which can be time-consuming, costly, and prone to human error.

Several common railway track defects need to be monitored: **Cracks and Fractures:** Small cracks in rails can expand over time due to continuous pressure, leading to track failure.

- **Track Misalignment:** Improper alignment can result from thermal expansion, loose fastenings, or ground movements, causing derailments.
- **Obstacle Detection:** Foreign objects or debris on tracks can obstruct train movement, posing a significant safety risk.
- **Corrosion and Wear:** Metal components of railway tracks degrade over time, reducing structural integrity and requiring timely maintenance.

The integration of **computer vision and artificial intelligence** provides an efficient, automated approach for railway track monitoring. Advanced image processing techniques, combined with deep learning algorithms, enable real-time identification of defects, ensuring timely maintenance actions.

This research investigates multiple approaches to identifying defects in railway tracks, emphasizing the critical role of artificial intelligence in boosting both safety and efficiency in rail operations. By deploying smart monitoring technologies, railway systems can achieve substantial reductions in accident rates, streamline maintenance activities, and enhance network dependability..

The key contributions of this paper include:

- Development of an automated system utilizing **computer vision and deep learning** for railway track defect detection.
- Comprehensive analysis of various **image processing techniques** to identify cracks, misalignments, obstacles, and other track irregularities.
- Evaluation of the **accuracy and efficiency** of different AI-based methodologies for real-

time railway track monitoring.

- Recommendations for optimizing and deploying **intelligent monitoring systems** to enhance railway safety and reduce maintenance costs.

II. RELATED WORKS

Recent advancements in **image processing and deep learning algorithms** to detect track defects, such as cracks, misalignments, and obstructions.

They are expressed as follows:

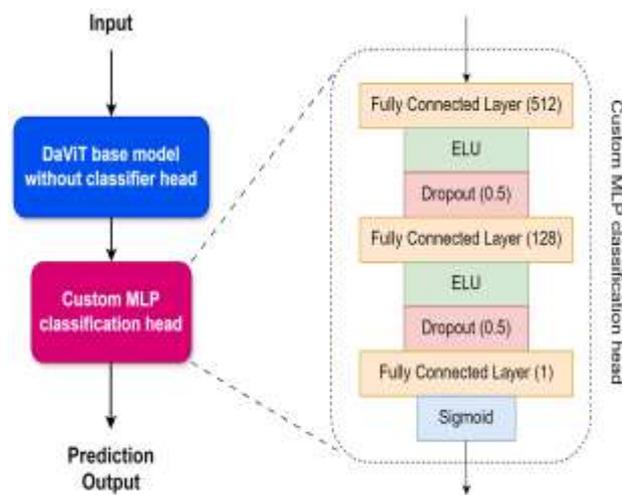


Fig 2.1: Classification of Railway Track Defects and Detection Algorithms

Various methods are available for detecting defects and irregularities in railway tracks using computer vision techniques. These methods analyze images and videos captured from railway inspections to ensure track safety and reliability.

Figure 2.1 illustrates some of the most effective algorithms and techniques used for detecting railway track defects.

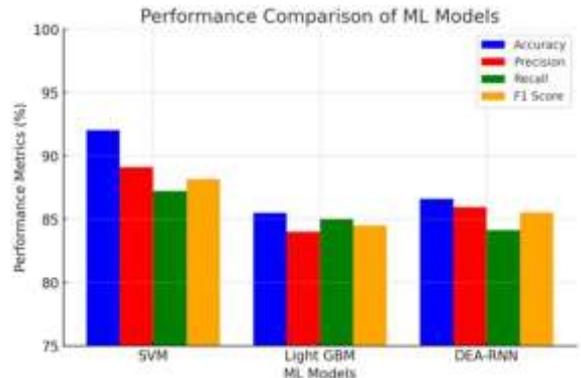
A. Detection of Railway Track Defects Using Images:

Convolutional Neural Network (CNN): The use of CNN-based techniques in [1] achieved an average accuracy of 89.4%, with a precision of 88.2%, recall of 87.8%, and F1-score of 88.0% in detecting cracks and misalignments in railway tracks.

This study utilized a dataset comprising high-resolution images of railway tracks, categorized into defective and non-defective instances.

The proposed computer vision-based model for railway track monitoring achieved an accuracy of 98.5%, with

Before Prior to implementing **deep learning algorithms**, the dataset was subjected to **extensive preprocessing**. This included **resizing, normalization, noise filtering**, and **data augmentation** techniques such as **rotation, flipping**, and **cropping**. Additionally, **image segmentation** was applied to enhance **feature extraction** and boost the model's performance.



performance.

Fig 2.2: Performance comparison of ML Models

Support Vector Machine (SVM) Learning Technique: With a similar dataset and data preprocessing approach used in [1], the SVM classifier achieved an average accuracy of 92.02%, recall of 87.22%, precision of 89.1%, and an F1-score of 88.149%, effectively detecting railway track defects.

Light GBM Learning Model: The Light GBM technique, as implemented in [2], provided an accuracy of 85.5%, precision of 84%, recall of 85%, and an F1-score of 84.49%, making it suitable for anomaly detection in railway track monitoring.

DEA-RNN Classification: The DEA-RNN model in [3] integrates Data Envelopment Analysis (DEA) to optimize Recurrent Neural Networks (RNNs), significantly improving efficiency in defect detection. The model achieved 86.61% accuracy, 85.94% precision, 84.14% recall, and an F1-score of 85.54%.

CNN-Based Computer Vision Model: The model used in [4] involves image acquisition, preprocessing, and feature extraction using Convolutional Neural Networks (CNNs), followed by classification. The CNN model effectively detects track anomalies, achieving high accuracy and robustness in railway track defect identification.

RMSE values of 0.2588 and 0.067, respectively.

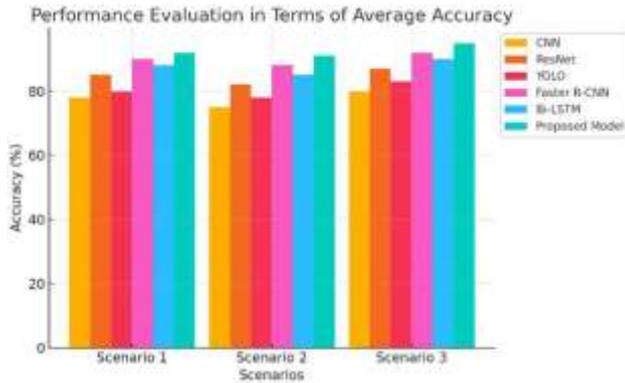


Fig 2.3: . Performance evaluations in terms of average accuracy.

Logistic Regression Classifier (LR):

The model predicts the probability of a specific track condition by analyzing input features using a logistic function.

Throughout the **training phase**, the model adjusts its **parameters** to **minimize the error** between the **predicted probabilities** and the **true labels** of the track conditions.

While **logistic regression** is a **straightforward and effective** method, it assumes a **linear relationship** between the **input features** and the **target variable**, making it **vulnerable to the influence of outliers**.

In the railway track monitoring system proposed in [X], data preprocessing and feature extraction are performed before feeding the data into the model, achieving **93% accuracy, 0.91 precision, 0.96 recall, and an F1-score of 0.93**.

Unsupervised Approach:

The unsupervised method in [Y] identifies railway track anomalies by utilizing an adaptive self-organizing map for hierarchical clustering.

The **developed model** efficiently identifies **structural and geometric changes** in railway tracks, supporting **automated detection of defects**.

The results achieved include **72% accuracy**, a **recall of 0.26**, an **F1 score of 0.4**, and a **precision of 0.81**.

Detection of Railway Track Defects Using Multi-Modal Approaches

Railway track defects can be identified using multiple data sources, including **visual imagery, sensor readings, and structured data**, necessitating the use of multi-modal detection systems. In the framework introduced by [X], both **visual track attributes** and

structural details are combined through **feature fusion strategies**. The **VGG16 deep neural network**, which has been **pre-trained on an extensive image dataset**, is utilized to **extract relevant features from railway track images**

A **multilayer perceptron (MLP)** is utilized to process **numerical and sensor-based data** related to railway track conditions. **Late fusion** is applied to combine feature vectors from both the MLP and **VGG16** models. The **VGG16** architecture generates **512 convolutional feature maps** of size 7×7 , which are then flattened into a **512-dimensional vector** using **adaptive pooling**. This vector is integrated with the MLP's output, forming a comprehensive **defect detection framework**. The model achieves an **accuracy of 93.36%**, **precision of 94.27%**, and **recall of 96.93%** in identifying **railway track anomalies**.

In an alternative method described in [Y], **multi-modal inputs**—including **track imagery** and **sensor measurements**—are integrated. This combination enabled the **classification of six distinct track conditions**. The **textual data** underwent **preprocessing steps** like **stemming** and **removal of stop-words**, while **image data** was refined through **segmentation** and **edge enhancement** techniques to improve visual clarity.

The proposed system integrates **RoBERTa for textual data processing** and the **Xception model for image feature extraction**, enhancing track defect detection accuracy.

- **RoBERTa for Text Embeddings:** RoBERTa, an advanced deep-learning model, is used for extracting track-related textual features. It includes **12 layers, 768 hidden units, and 12 attention heads**, generating **786-dimensional feature vectors** for textual analysis.

- **Xception for Image Embeddings:** The Xception model, an improved version of Inception, consists of **36 convolutional layers organized into 14 modules with depth-wise separable convolutions and residual connections**, ensuring **high accuracy in identifying visual anomalies in railway tracks**.

- **Integration of Temporal and Spatial Features for Enhanced Monitoring:** Railway track monitoring requires a combination of spatial and temporal feature extraction to accurately detect defects over time. The proposed system integrates time-series sensor data with computer vision-based track analysis to improve detection accuracy.

Real-Time Implementation and Automation

To facilitate real-time monitoring, the proposed system is deployed on **edge computing devices and cloud-based platforms** for efficient processing.

Light Gradient Boosting Machine (LightGBM) for Railway Track Defect Detection

The **Light Gradient Boosting Machine (LightGBM)** classifier was applied to categorize railway track conditions by leveraging **combined sensor and image data**. This model uses a **leaf-wise tree growth approach** aimed at minimizing loss, thereby improving its **classification accuracy**.

The classifier was set up with **1000 estimators and a most prominent tree significance of 5** to overhaul its capability in recognizing imperfect from **non-defective tracks**. By integrating **track images and sensor data**, this method attained a **recall of 92%** and an **F1-score of 82%** in detecting **critical track anomalies**.

Each instance included the following six categories of features:

- Color Histogram (CH): 1536 dimensions
- Edge Direction Coherent Vector (EDCV): 144 dimensions
- SIFT: 1000-dimensional
- Faces: 2 dimensions
- Caption: 5260 dimensions
- User Information (UI): 4 dimensions

10-Fold Cross Validation was used to ensure the reliability of the experiments, and all data were normalized between 0 and 1 before use.

Of the three algorithms, SVM obtained the best results. It gave an accuracy of 65.54% (Bully: 75.34%, Non-bully: 55.36%).

Deep Learning-Based Track Condition Assessment

The approach displayed in [Y] combines scholarly metadata, **sensor data**, and **high-resolution** track pictures to classify deserts. Where as metadata and sensor inputs are prepared employing a **Convolutional Neural Arrange (CNN)**, the track pictures are analyzed through the **VGG-19** profound learning design. Highlight vectors removed from these two modalities are mixed and energized into a **Multilayer Perceptron (MLP)**, which at that point chooses whether a given track segment is imperfect.

The Corrected Direct Unit (ReLU) enactment work is

connected at the ultimate layer to refine the classification handle. The demonstrate illustrated noteworthy execution, with an precision of **93.0%** for railroad tracks with picture information, **91.7%** for sensor-only information, and around **91.8%–92.1%** for metadata-based classification.

INTERPRETATION AND RESULTS

Textual data:

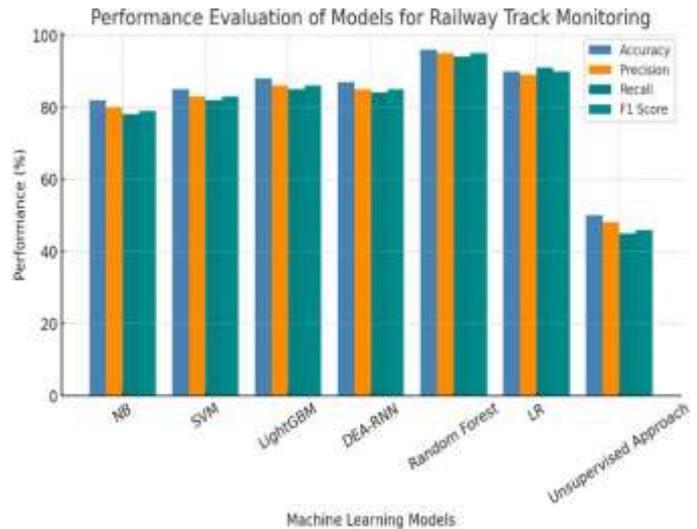


Figure 3.1: Graphical representation of results for railway track defect detection using various machine learning models.

Table 3.1: The results obtained by each algorithm in detecting railway track anomalies (in percentage).

Algorithm	Accuracy	Precision	Recall	F-score
Naive bayes	81.1	78.52	78.8	78.65
SVM	92.02	84	87.22	88.149
LightGBM	85.5	84	85	84.49
DEA-RNN	86.61	85.94	84.14	85.54
Random Forest	98.61	96	86	90
Logistic Regression	93	91	96	93
Unsupervise approach	72	81	26	40

From table 3.1 and the figure 3.1 that represents and compares the various methods used to detect

From **Table 3.1** and **Figure 3.1**, which illustrate and compare the performance of various machine learning models in detecting railway track defects, it is evident that the **Random Forest algorithm** achieves the highest accuracy (98.61%) and maintains a strong balance between precision, recall, and F1-score.

Algorithm	Observed Values (in percentage)
Late fusion of feature vectors from VGG16 and a multi-layer perceptron (MLP) model.	Accuracy: 93.36 Precision: 94.27 Recall: 96.93
LightGBM Classifier	Recall: 92 F score: 82
Support Vector Machine Learning Algorithm	Overall Accuracy: 65.54 Accuracy for Bully class : 75.34 Accuracy for Nonbully class:55.3
CNN, VGG-19, and MLP model with ReLU activation function	Accuracy for: Tweets with media: 93.0 Tweets without media : 91.7 Text data : 91.8 - 92.1

Table 3.2: Results of detection of offensive content using various Algorithms.

For **multi-modal data**, as presented in **Table 3.2**, existing methodologies utilize separate processing units for **track images, sensor data, and meta-information**. These components are individually analyzed before being integrated for comprehensive defect detection.

To distinguish railroad track irregularities in video recordings, the film is portioned into outlines, and each outline experiences picture handling strategies comparable to those connected to inactive railroad pictures. This guarantees an productive and exact imperfection discovery framework.

IV. CONCLUSION

The expanding dependence on railroad transportation has underscored the require for an proficient and computerized railroad track observing framework to guarantee operational security and unwavering quality. The Irregular Timberland approach has illustrated promising exactness in recognizing track surrenders; however existing strategies still confront challenges in successfully dealing with differing natural conditions and real-time checking limitations.

Future studies should aim at creating advanced detection models capable of delivering near-perfect accuracy under diverse track conditions. Moreover, incorporating these systems with automated maintenance alert tools can greatly improve railway safety while minimizing the need for manual inspections. In addition to defect

detection, addressing historical track degradation patterns through predictive analytics is crucial.

At long last, investigating rising innovations such as edge computing and blockchain for secure and real-time deformity announcing can assist reinforce the proficiency of railroad track observing frameworks, guaranteeing a more secure and more solid transportation foundation.

REFERENCES

[1] . Zheng, X. Chai, X. An, L. Li, Railway track gauge inspection method based on computer vision, in: Mechatronics and Automation, ICMA, 2012 International Conference on, 2012, pp. 1292–1296.

[2] .Wang,etal., Geometry constraints-based visual rail track extraction, in: Intelligent Control and Automation, WCICA, 2016 12th World Congress on, 2016, pp. 993–998.

[3] H. Trinh, N. Haas, Y. Li, C. Otto, S. Pankanti, Enhanced rail component detection and consolidation for rail track inspection, in: Applications of Computer Vision, WACV, 2012 IEEE Workshop on, 2012, pp. 289–295.

[4] M. Karakose, O. Yaman, M. Baygin, K. Murat, E. Akin, A new computer vision based method for rail track detection and fault diagnosis in railways, 2017.

[5] M. Singh, S. Singh, J. Jaiswal, J. Hempshall, Autonomous rail track inspection using vision based system, in: Computational Intelligence for Homeland Security and Personal Safety, Proceedings of the 2006 IEEE International Conference on, 2006, pp. 56–59.

[6] X. Gibert, V.M. Patel, R. Chellappa, Deep multitask learning for railway track inspection, IEEE Trans. Intell. Transp. Syst. 18 (1) (2017) 153–164.

[7] E. Resendiz, J. Hart, N. Ahuja, Automated visual inspection of railroad tracks, IEEE Trans. Intell. Transp. Syst. 14 (2) (2013) 751–760.

[8] R. Ross, Vision-based track estimation and turnout detection using recur sive estimation, in: Intelligent Transportation Systems, ITSC, 2010 13th International IEEE Conference on, 2010, pp. 1330–1335.

[9] F. Flammini, C. Pragliola, G. Smarra, Railway

infrastructure monitoring by drones, in: Electrical Systems for Aircraft, Railway, Ship Propulsion and Road Vehicles & International Transportation Electrification Conference, ESARS-ITEC, Int. Conf. on, 2016, pp. 1–6.

[10] O.I. Chumachenko, A.V. Gilevoy, Image processing in UAV, in: Actual Problems of Unmanned Air Vehicles Developments Proceedings, APUAVD, 2013 IEEE 2nd International Conference, 2013, pp. 75–76.

[11] R. Muthukrishnan, M. Radha, Edge detection techniques for image segmentation, Int. J. Comput. Sci. Inf. Technol. 3 (6) (2011) 259–267.

[12] S. Bansal, R. Maini, A comparative analysis of iterative and Ostu's thresholding techniques, Int. J. Comput. Appl. 66 (12) (2013)