

Smart Vehicle Feature using Embedded System and IoT

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ABSTRACT:

A comprehensive study of motor vehicle safety is presented here. As headlamp are the most important aspects in night drives to switch into high and low beams as per requirement, intensity of head lamp as per sunlight has to be taken care which is not available in automotive work prototype of the headlight system which is made by using Arduino, sensors, LEDs and more. The prototype of this multi featured headlamp system consists of turning headlamp on, off and provides facility to automate switching of headlamp intensity from low beam to high beam due to lack of street light facility. And also that eliminates the need for manual control by the driver since switching is done automatically. In this model, rain sensor detects the rain and wipers will also be on automatically and fog will also be cleared by automotive heater which clears the driver screen and facilitates the driver to drive. The alcohol sensor perceives the presence of ethanol in the air. When the driver breathes near the alcohol sensor. he detects the ethanol in the breath and provides a yield based on alcohol concentration. Depending on the alcohol content, it will detect whether the driver is drunk or not. Ultrasound sensors are electronic devices that calculate the distance of the target by emitting ultrasound sound waves and convert these waves into electrical signals. Thus, senses the vehicle and objects opposed by these mechanisms. This model has gathered three different features of the headlamp system. These functions are automatic from the headlamp during the night, automatic adjustment of the light intensity with respect to opposite light beam and automatic switching ON due to lack of streetlights. This concept is very useful in applications of the car, which ensures the safety of the driver behind the wheel.

I. PROBLEM STATEMENT:

This system of headlights helps the driver to focus on the correct path that directs the direction to turn in either direction along the turning roads at night. Another major issue for drivers at night is the glare effect. When exposed to very bright light, the person's vision becomes blurred. To avoid glare, the headlamp passes from the high beam to the dipped beam and vice versa.

II. PROPOSED METHOD:

The circuit utilized in this study is a straightforward assembly of parts that are currently used with the ESP32 microcontroller. It is made up of several parts such as an LDR, LED, DHT11senso4r3, rain sensor, servomotor, buzzer, and relay. In order to keep the design straightforward and simple to apply, the components have been carefully and accurately chosen. When a night light is needed, an automatic control system turns it ON and OFF without the need for manual action. It self-detects whether or not light is required. When the amount of darkness reaches a specified level, the light is automatically turned ON, and when there is another source of light, such as daylight, the light is turned OFF. As a light sensor and for detection, we utilise an Arduino and a light-detecting resistor.

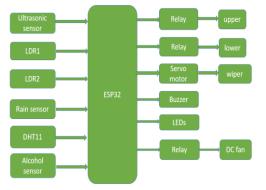


Fig 1. System Architecture

III.METHODOLOGY:

This section demonstrates the procedures used to examine the circuit, which is a straightforward assembly of frequently used circuit components with an ESP32 microcontroller.



These are made up of many parts, including servo motors, buzzers, LEDs, LDRs, and DHT11 sensors. In order to make the design straightforward and simple to apply, these components have been chosen with attention and accuracy. When there is a demand for light, an automatic light control system turns ON and OFF without operator intervention. It will automatically determine whether light is required or not called Light Dependent Resistors. An LDR's resistance is typically very high-it might be anywhere between 1000 and 10,000 ohms-but when it is illuminated with light, the resistance dramatically decreases. The temperature sensor detects the fog and sends the information to the microcontroller, which then uses relay to turn the heater fan on and off automatically. We also use a rain sensor to detect the rain and servo motor wipers to turn on and off automatically. A driver's intoxication level is determined by an alcohol sensor. Use of an ultrasonic sensor for detection of obstacles.

IV. SYSTEM REQUIREMENTS: ESP32:

The ESP32 is a potent and adaptable IoT programming platform that has attracted a lot of attention recently. The main characteristics, architecture, and uses of the ESP32 module are the article explores the ESP32's technical specifications, programming possibilities, and development tools, demonstrating its potential for fostering innovation and facilitating the implementation of cutting-edge IoT solutions.



Fig. 2. ESP 32

1. Introduction The ESP32 is an IoT development platform that is incredibly well-liked and frequently used. It has extraordinary capabilities for embedded systems. The ESP32 module will be thoroughly explained in this paper, with a focus on its architecture, features, and applications. The ESP32 has developed into a vital tool for IoT enthusiasts, academics, and developers because to its strong hardware and broad software support.

2. ESP32 Architecture The ESP32 is based on a potent 32bit dual-core microcontroller, which makes it possible to run numerous operations at once and improves the performance of the microcontroller system. Operating at clock frequencies of up to 240 MHz is the architecture and. The module includes a wide range of peripherals, including as PWM controllers, UART, SP2I, I2C, and more, allowing for the smooth integration of sensors and actuators.

3. Connection Methods The ESP32's integrated Wi-Fi and Bluetooth functions are some of its most important characteristics. The module offers seamless communication to local networks and the internet by supporting a variety of Wi-Fi protocols, including 802.11 b/g/n. The ESP32 also incorporates Bluetooth Classic and Bluetooth Low Energy (BLE), making it simple to communicate with other devices and supporting Internet of Things (IoT) applications that demand close-proximity wireless connectivity.

4. Tools for Programming and Development The ESP32 platform provides a variety of programming possibilities to meet various development needs. It was emphasised in the abstract of this essay. The ESP32 is a fantastic solution for a variety of embedded systems and Internet of Things projects because to its dual-core microcontroller, built-in Wi-Fi and Bluetooth connections. and extensive peripheral compatibility It supports the Arduino framework, which offers newcomers a comfortable and user-friendly environment for development. The ESP-IDF (Espressif IoT Development Framework), a comprehensive collection of libraries and tools created especially for the ESP32, is available to advanced developers. The platform's adaptability is further increased by support for MicroPython and JavaScript.Application. The ESP32's adaptability makes it suited for a variety of IoT and embedded systems applications. It can be used in smart agriculture, wearable technology, industrial monitoring and control, and other applications. With its processing power, peripheral compatibility, and built-in Wi-Fi and Bluetooth connectivity, the 50enables simple integration with cloud services, data analytics, and remote monitoring solutions.

5. Obstacles and Future Focus Despite the ESP32's many advantages, there are some issues that must be resolved if it is to be used to its full potential. These include real-time performance needs, security concerns, and power consumption optimisation. The ESP32's capabilities are being increased and these elements are the subject of ongoing research and development.

DHT11:



Fig.3. DHT11



The DHT11 sensor can be included as a component of a larger system in a smart car to give monitoring capabilities for temperature and humidity. The DHT11 sensor can be applied in the following ways to smart vehicles: Climate Control Optimisation: To detect the temperature and humidity levels inside the car, the DHT11 sensor can be strategically placed. The climate control system of the car can utilise this information to automatically change the heating or cooling settings to keep the occupants comfortable. The device can optimise energy use and deliver a comfortable driving experience by precisely monitoring the temperature and humidity.Defogging and Defrosting: High interior humidity levels can result in window fogging or icing, which can seriously impair visibility.

MQ-3 SENSOR (Alcohol Sensor):

Similar to standard breathe analyser this alcohol sensor is suited for detecting the presence of alcohols on our breathe. It responds quickly and with high sensitivity. Based on alcohol concentration ,the sensor outputs an analogue resistive signal.



Fig. 4 . MQ-3 Sensor(Alchohol Sensor)

Features:

- 5V DC or AC circuit
- Requires heater voltage
- Operation Temperature: -10 to 700C
- Heater consumption: less than
- 750mW Dimensions:
- 16.8mm diameter
- 9.3 mm height without the pins

The MQ-3 gas sensor's structure and configuration are depicted in Fig. (Configuration A or B). The sensor is made up of a tiny AL2O3 ceramic tube, a Tin Dioxide (SnO2) sensitive layer, a measuring electrode, and a heater that are all placed into a crust that is constructed from plastic and stainless steel net. The heater creates the ideal working environment for sensitive components. The four pins on the wrapped MQ-3 are utilised.Out of which two are utilized to supply heating current, while the other two are used to fetch signals.

ULTRASONIC SENSOR:

Ultrasonic sensors, which provide precise and trustworthy distance measurement capabilities, have significantly increased in popularity in the field of sensing technology. The fundamental concepts, operational procedures, and applications of ultrasonic sensors are covered in detail in this study.



Fig 5. ULTRASONIC SENSOR

The paper discusses developments in ultrasonic sensing technology, especially in the context of embedded systems that are IoT enabled. It examines how ultrasonic sensors may be integrated with IoT platforms and shows how this can improve automation, object detection, and navigation in a variety of applications. The problems and potential possibilities for ultrasonic sensor technologies in the IoT era are also covered in the article.

1. Introduction The ability of ultrasonic sensors to precisely measure distance and detect things without physical contact makes them widely used in a variety of sectors. The functioning principles, technical details, and applications of ultrasonic sensors are all covered in-depth in this study. Additionally, the possibility for enhanced automation, object detection, and navigation is examined by integrating ultrasonic sensors with IoT-enabled embedded systems.

2.Ultrasonic Sensors: Their Operational Principles To measure distances and find objects, ultrasonic sensors use the transmission and reception of high-frequency sound waves. The transducer in the sensors transforms electrical energy into ultrasonic waves and back again. The distance can be precisely determined by measuring the time required for ultrasonic waves to reach an object and return, using the medium's speed of sound.

3. Technical Information and Ultrasonic Sensor Types 1. Technical characteristics of ultrasonic sensors include operating frequency, detection range, beam width, and resolution. Ultrasonic sensors come in a variety of forms, each with unique capabilities and uses, including proximity sensors, range sensors, and imaging sensors. The paper gives a summary of these types and requirements while emphasising how well they fit various use cases.

4. Uses for Ultrasonic Sensors Numerous industries, such as industrial automation, robotics, automotive systems,



healthcare, and security, use ultrasonic sensors. They are frequently utilised for parking assistance, object recognition, distance measurement, collision avoidance, and liquid level sensing. The usage of ultrasonic sensors in practical applications in the real world is demonstrated in the article through case studies and examples drawn from various fields.

5. Embedded Systems with Ultrasonic Sensor Integration for the Internet of Things In terms of data collection, processing, and decision-making, the integration of ultrasonic sensors with IoT platforms and embedded systems offers a number of major benefits. Real-time distance measurements, object detection data, and other sensor information can be analysed and used for automation, navigation, and monitoring applications by integrating ultrasonic sensors with IoT networks. The study examines ultrasonic sensor integration issues, protocols, and architectures for IoT-enabled embedded devices.

6 .Advancements and Future Directions

The capabilities of ultrasonic sensors continue to be improved, and their range of applications is growing. The study addresses recent advancements, such as miniaturisation, increased precision, increased range, and integration with machine learning and artificial intelligence systems. Future developments in the field of ultrasonic sensor technology are also investigated, including multisensor fusion, energy efficiency enhancement, and enhanced object recognition algorithms.

7. Challenges and Things to Think About While there are many advantages to using ultrasonic sensors, there are some issues that must be resolved for best performance. Environmental interference, distance-related accuracy restrictions, and the impact of various materials on wave propagation are a few of these. The use of mitigation measures and current research initiatives in these areas are discussed.

Relays :

An electrically controlled switch is a relay. Other operating theories are also utilised, however an electromagnet is commonly used in relays to mechanically operate a switching mechanism. Relays are employed when several circuits need to be controlled by a single signal or when a low-power signal is required to control a circuit with perfect electrical isolation between the control and controlled circuits. The first relays were utilised in long-distance telegraph circuits to duplicate and retransmit signals from one circuit to another. Early computers and telephone exchanges both made heavy use of relays to carry out logical processes.



Fig.6. Relay

A contactor is a sort of relay that can manage the high power needed to directly operate an electric motor. With no moving parts and switching performed by a semiconductor device, solid-state relays regulate power circuits. To safeguard electrical circuits from overload or defects, relays with calibrated operating characteristics and occasionally several operational coils are utilised; in contemporary electric power systems, digital instruments still called "protective relays".

DC Fan:

A specific kind of fan that utilizes direct current (DC) electricity is a DC fan found in smart cars. It is frequently employed for cooling purposes, especially in automotive applications. Here are some significant specifics regarding DC fans in smart vehicles:

Function: The main purposes of DC fans in intelligent vehicles are to move air and remove heat. They aid in keeping a number of parts cool, including the engine, radiator, battery, and other electronic systems.

Power Source: DC fans use the electrical system of the car to run, often using the alternator or battery. They are made to operate with the vehicle's DC voltage, which is commonly 12 volts (for the majority of passenger cars) or 24 volts (for larger cars or commercial purposes). Axial fans and centrifugal fans are two examples of the many types and sizes available for smart vehicles. The most typical type of fan has blades that rotate around an axis and circulate air perpendicular to the axis of revolution. Conversely, centrifugal fans are frequently employed when increased air pressure is required since they circulate air perpendicular to the plane of revolution. The application and cooling needs determine the fan's precise dimensions and features. Control and regulating speed: Different techniques can be used to manage and regulate DC fans in smart automobiles. Using pulse width modulation (PWM) techniques, which change the duty cycle of the power supply to regulate the fan's speed, the speed of the fan can be changed. Moreover, temperature sensors or Based on cooling requirements, the fan speed can be automatically modulated using feedback data from vehicle systems.

Connecting to smart systems DC fans can be included into the climate control or smart system of smart automobiles. They may be combined with other intelligent features or



managed through the vehicle's central control unit. For instance, as part of an automated cooling system or based on temperature readings from various sensors, the fan speed may be changed. Integration with Smart Systems: DC fans can be integrated with the smart system or climate control system in smart automobiles. They may be combined with other intelligent features or managed through the vehicle's central control unit. For instance, as part of an automated cooling system or based on temperature readings from various sensors, the fan speed may be changed system.

Real-time distance measurements, object detection data, and other sensor information can be analysed and used for automation, navigation, and monitoring applications by connecting ultrasonic sensors to IoT networks. The study examines ultrasonic sensor integration issues, protocols, and architectures for IoT-enabled embedded devices.

Energy Efficiency: Compared to conventional AC fans, DC fans are typically more energy-efficient. They could be built with brushless DC (BLDC) motors, which are more effective, operate more quietly, and last longer. In smart vehicles, where optimizing power usage is essential for overall efficiency and battery life, this energy efficiency is especially significant.

In order to maintain ideal temperatures and cool important components in smart vehicles, DC fans are essential. They contribute to the overall dependability and functioning of the vehicle's cooling system by helping to prevent overheating, guarantee effective operation, and prevent overheating driver.

Low-intensity rain may cause the wipers to run at a slower speed, saving energy and making less noise. On the other hand, in times of intense downpour, the wipers can operate more quickly to maintain clear view. The rain sensor can communicate with other systems in the smart car in addition to managing the wipers. For instance, it can interact with the car's lighting system to turn on the headlights or change their brightness when it's dark outside. Advanced driving assistance systems (ADAS) can integrate the rain sensor to provide input for functions like adaptive cruise control, collision warning, and lane keeping assist.

Overall, a smart car's rain sensor is essential for improving visibility and safety since it automates the functioning of the windscreen wipers and works in tandem with other car systems to adjust to shifting weather conditions. Drivers can focus on the road ahead without having to constantly modify the wiper settings thanks to the more convenient and comfortable driving experience it offers.





Rain sensor

The purpose of a rain sensor in a smart car is to detect and track the presence and severity of rain or other precipitation on the windscreen. It is frequently utilised in contemporary automobiles with automated systems to increase the driver's comfort and safety. A tiny optical sensor, typically installed on the windscreen behind the rearview mirror, makes up the rain sensor. To measure the amount of light reflected back, this sensor either produces infrared light or makes use of a light-sensitive diode. The sensor notices a disruption in the light's ability to reflect when rains strike the windscreen.

The amount of rain or water droplets on the windscreen are continuously measured by the rain sensor. The electronic control unit (ECU) of the car receives this data and processes it to decide on the best course of action. The ECU analyses the intensity of the rain using algorithms and initiates various automated processes as necessary.

In a smart car, a rain sensor's primary function is to regulate the windscreen wipers' operation.

The rain sensor can automatically alter the speed and frequency of the wiper blades based on the intensity of the rain it detects, ensuring the driver has the best driver. Lowintensity rain may cause the wipers to run at a slower speed, saving energy and making less noise. On the other hand, in times of intense downpour, the wipers can operate more quickly to maintain clear view. The rain sensor can communicate with other systems in the smart car in addition to managing the wipers. For instance, it can interact with the car's lighting system to turn on the headlights or change their brightness when it's dark outside. Advanced driving assistance systems (ADAS) can integrate the rain sensor to provide input for functions like adaptive cruise control, collision warning, and lane keeping assist.

Overall, a smart car's rain sensor is essential for improving visibility and safety since it automates the functioning of the windscreen wipers and works in tandem with other car systems to adjust to shifting weather conditions. Drivers can focus on the road ahead without having to constantly modify the wiper settings thanks to the more convenient and comfortable driving experience it offers.



LDR

Due to their capacity to recognise and gauge light intensity, Light Dependent Resistors (LDRs), also known as photoresistors, are widely utilised in sensing technologies. The fundamental concepts, operational procedures, and applications of LDRs are covered in detail in this study. The study emphasises the developments in LDR technology, especially in the context of embedded systems with IoT capabilities. The potential of LDRs for applications including ambient light detection, light-controlled automation, and smart energy management are explored through the integration of LDRs with IoT platforms. The problems and prospects for LDR technology in the IoT era are also covered in the article.



Fig.9. LDR Sensor

1. Introduction Due to their ability to detect light, Light Dependent Resistors (LDRs) are frequently utilised in many different sectors. This article gives a thorough introduction of LDRs with a focus on their functional principles, technical details, and applications. The potential of LDRs to improve ambient light detection, light-controlled automation, and energy management is also studied through the integration of LDRs with IoT-enabled embedded systems.

2. LDRs' Operational Principles Due to a special characteristic of LDRs, the electrical resistance changes depending on the strength of the incident light. The materials used to create the sensors are typically semiconductors, which change their conductivity when exposed to light. LDRs fall under the category of passive parts that respond linearly or arithmetically to changes in light intensity..

3. LDR Types and Technical Specifications Resistance range, reaction time, spectrum sensitivity, and dark resistance are just a few of the technical characteristics that LDRs might have. There are various LDR kinds available, including Cadmium Sulphide (CdS) and Lead Sulphide (PbS) sensors, each of which has unique properties and is appropriate for a variety of applications. The document gives a summary of these kinds and standards, emphasizing their application cases.

4. LDRs' applications LDRs are used in a variety of industries, including as energy management, photography,

security systems, and lighting control systems. They are frequently used for automatic street lighting, smart home systems, ambient light sensing, and exposure control in photography. In order to demonstrate the usefulness of LDRs in actual applications, the paper provides case studies and examples from various disciplines.

4. Embedded systems that integrate LDRs with the Internet of Things Embedded systems and IoT platforms can benefit from improved data collecting, analysis, and automation capabilities because to the inclusion of LDRs.Real-time light intensity data can be gathered, processed, and used by connecting 4L9DRs to IoT networks for a variety of applications, including smart lighting management, adaptive display brightness, and energy-efficient systems. The integration issues, protocols, and architectures for integrating LDRs into embedded systems with IoT support are examined in this study.

5.Advancements and Future Directions LDR technology is constantly improving, which broadens its potential uses. The study addresses recent advancements in intelligent light control, such as miniaturisation, enhanced sensitivity, broader spectrum range, and integration with machine learning algorithms. Future developments in LDR technology are also examined, including enhanced spectrum sensing, increased signal-to-noise ratios, and sensor integration for multi-modal data collecting.

6. Challenges and Things to Think About While LDRs provide many advantages, there are some problems that must be solved for best performance. These include temperature dependence, a constrained dynamic range, and cross-sensitivity to other environmental conditions. The use of mitigation measures and current research initiatives in these areas are discussed.

BUZZER:

Current flows instantly to the brass contactor screw. The current keeps moving into the coil because the screw is in contact with the vibrator arm. It emerges from the coil and flies past the locked code key before returning to the battery. This current flow produces a magnetic field surrounding the iron bolt, just like in an electric pencil. The vibrator arm is drawn to the bolt because it has turned into an electromagnet. But as the arm begins to move in the direction of the bolt, the circuit is opened. As a result, the current pauses. The magnetic field disintegrates as a result, enabling the vibrator arm to spring back against the contactor. Now that the circuit has been repaired, current begins to flow once more, and the cycle restarts. No matter how quickly we press and release the code key, the current will still make hundreds of round trips through the circuit. And because of the resulting rapid motions of the vibrator arm, a buzzing sound is heard. Not only is the code set fun to build, but it is even more fun to use, especially with a fellow operator. So that both of you can send as well as receive messages, you will want to build two identical sets of buzzers and code keys. They're really not hard to make. For each set you will need the following materials





Fig.10. Buzzer

SERVO MOTORS :

Servo motors are crucial parts of motion control systems because they allow for precise positioning and velocity control. This article gives a thorough explanation of servo motors, covering its fundamental concepts, operational procedures, and practical uses. The improvements in servo motor technology, particularly as they relate to embedded systems with IoT capabilities, are highlighted in the article. It investigates how servo motors can be used with IoT platforms and illustrates their potential for use in robotics, automation, and smart home systems. The challenges and prospects for servo motor technology in the IoT era are also covered in this article.



Fig.11.Servo Motor

1. Introduction In motion control systems, servo motors are essential because they allow for accurate positioning and velocity control. In-depth information about servo motors is presented in this study, with a focus on their uses, technical details, and operating principles. Additionally, the use of servo motors in IoT-enabled embedded systems is investigated, showcasing their potential to improve robotics, automation, and smart home systems.

2. The Operation of Servo Motors Rotating actuators known as servo motors are used to precisely translate electrical information into mechanical motion. They typically include a control system, an encoder or potentiometer for feedback, and a DC motor. The control system receives position or velocity commands and adjusts the motor's operation to achieve the desired motion.

3. Servo Motor Types and Technical Specifications There are many different technical requirements for servo motors,

including torque, speed, voltage, and resolution. There are various servo motor types, including DC, AC, and stepper motor-based servos, each with unique properties and applicability for various applications. The paper gives an overview of these categories and requirements while highlighting applications for each.

4. Uses for servo motors Servo motors are used in a variety of industries, including as robotics, industrial automation, aerospace, and consumer electronics. They are frequently used in robotic arms, CNC machines, 3D printers, camera gimbals, and automated assembly systems for precise positioning. The usage of servo motors in practical applications in the real world is demonstrated in the article through case studies and examples drawn from various fields.

5. Servo Motor Integration with IoT-Enabled Embedded Systems Servo motor integration with embedded systems and IoT platforms enables improved automation, control, and monitoring capabilities. Remote operation, adaptive control, and data-driven optimisation are made possible by coupling servo motors to IoT networks and exchanging realtime control commands and feedback information. The study examines servo motor integration issues, protocols, and designs for IoT-enabled embedded devices.

6. Developments and Proposed Courses of Action The capabilities of servo motors are continually being improved, and their range of applications is growing. Recent advancements are covered in the study, such as increased precision, greater torque-to-weight ratios, and integration with cutting-edge control algorithms. Future developments in servo motor technology are also investigated, including sophisticated motion planning, self-calibration, and machine integration.Challenges and Considerati1o2ns While servo motors offer numerous benefits, there are challenges that must be resolved in order to perform at their best. These include real-time control of complicated systems, stability and tuning difficulties, and power consumption optimisation. The use of mitigation measures and current research initiatives in these areas are discussed.

Arduino IDE:

A simple software programme called the Arduino Integrated Development Environment (IDE) was specifically for programming Arduino microcontroller boards. This article gives a general overview of the Arduino IDE with a focus on its functions, features, and applications for quick prototyping and development. Because of its user-friendly interface, wide library support, and straightforward programming language, the Arduino IDE is suitable for both inexperienced developers and seasoned professionals. The paper explores the technological features, the programming process, and the integration possibilities offered by the Arduino IDE, demonstrating its capability to promote quick and easy creation of Arduino-based systems.





Fig.12. Arduino IDE

1. Introduction When creating projects with Arduino microcontroller boards, the Arduino IDE is absolutely essential. This article gives a general overview of the Arduino IDE with a focus on its functions, features, and applications for quick prototyping and development. The Arduino IDE is an approachable tool for both novice and professional developers due to its user-friendly interface and simplified programming language.

2. Specifications and Usability A number of capabilities provided by the Arduino IDE make it easier to deploy and programme Arduino-based systems. These consist of a userfriendly code editor with syntax highlighting and autocompletion, a built-in compiler and uploader for uploading code to Arduino boards, a serial monitor for communication and debugging, as well as a vast library ecosystem that offers pre-built code modules for various functionalities.

3. Programming Process The Arduino IDE's programming approach is quite simple to understand. The code is written by users in the IDE's code editor, checked for mistakes, converted to machine code, and then uploaded to the Arduino board. As a result of the IDE's feedback on faults and warnings, problems during development are simpler to spot and address.

4. Libraries and Illustrations The Arduino IDE includes a sizable number of libraries and examples that make it easier to implement various features. These libraries offer prewritten code for typical tasks like managing actuators, reading sensor data, and communicating with other devices. The paper discusses the library ecosystem and showcases examples of how libraries can be utilized in Arduino projects.

5. Compatibility and Integration2 The Arduino IDE ensures compatibility with a variety of microcontrollers and development boards by working with a wide range of Arduino boards and derivatives. Developers can increase the capability of the IDE by integrating third-party libraries, which is supported by this feature. Furthermore, for more complex debugging and development workflows, the Arduino IDE can be connected to outside platforms and tools.

6. Uses for the Arduino IDE The Arduino IDE is used in a variety of fields, such as robotics, home automation, the

Internet of Things, and education. It offers a platform for learning electronics and programming, enables quick prototyping of projects, encourages experimentation, and facilitates learning. The case studies and examples in this paper show how to use the Arduino IDE in practical settings.

7. Benefits and Drawbacks The Arduino IDE provides a number offeatures, including its simplicity, broad library support, and hardware compatibility with a variety of platforms. It offers a user-friendly environment on which beginners can begin programming microcontrollers. However, it is constrained in terms of sophisticated debugging tools and scalability for large-scale applications. Embedded C Language:

A programming language called embedded C was created expressly for creating software for embedded systems. It is a C programming language variation that is designed for situations with limited resources, such microcontrollers and other embedded devices. Embedded C combines the strength and adaptability of the C language with particular features and modifications made for the development of embedded systems.

Here are some of Embedded C's main characteristics and attributes: Data Types: Embedded C supports the standard data types available in the C language, such as integers, floating-point numbers, characters, and pointers. It also provides additional data types specific to embedded systems, such as bit-fields and fixed- width integer types (e.g., uint8_t, int16_t) for precise control over memory usage and hardware interactions

Memory Management: Fine-grained control over memory allocation and management is possible with embedded C. It offers capabilities such as declaring variables in particular memory locations (such as RAM or ROM), optimising data structures for effective Memory usage, including the use of bit-fields and packing structures, as well as pointer access to specific memory locations

Operations on I/O: Embedded C offers methods for establishing connections with the input and output peripherals of embedded systems. Timers, GPIO (General Purpose Input/Output) pins, UARTs (Universal Asynchronous Receiver/Transmitter), SPI (Serial Peripheral Interface), I2C (Inter-Integrated Circuit), and other devices can all be programmed and managed.

Interrupt Handling: Embedded systems often rely heavily on interrupts to respond to events in real- time. Embedded C provides features for defining interrupt service routines (ISRs) that handle interrupts and allow for efficient eventdriven. These ISRs can be associated with specific interrupt sources and executed asynchronously.

Embedded C makes use of compiler-specific directives to manage the compiler's behaviour and produce effective code for the target platform. Control over memory alignment, levels of optimisation, and other compiler-specific features is provided by these directives.

Low-Level Access: Embedded C enables developers to interface with the embedded system's underlying hardware



by granting them direct access to hardware registers and memory locations. For tasks like setting up peripherals, building device drivers, and accessing specialised hardware features, this low-level access is necessary.

Constraints of Real-Time: Many embedded systems work in real-time settings and need accurate timing control. Delay functions, timers, and scheduling algorithms are elements of Embedded C that enable developers fulfil real-time deadlines and guarantee the prompt completion of crucial activities.

It's crucial to understand that Embedded C isn'tarchitecture comprising the Linux kernel, native libraries, the Android Runtime (ART), the framework, and the application layer. The framework layer provides various APIs and services for building Android applications, including those that interact with IoT devices and networks.

1. Key Features and Capabilities Android offers a rich set of features and capabilities that enable the development of IoT applications. These include access to various sensors, connectivity options (such as Wi-Fi, Bluetooth, and NFC), support for multimedia, user interface components, data storage options, and integration with cloud services. Additionally, Android's security model ensures the protection of sensitive data and user privacy.

2. Applications of Android in IoT Android applications find extensive applications in the IoT domain, including home automation, healthcare monitoring, smart cities, industrial automation, and wearable devices. Android apps can collect sensor data, control IoT devices, provide real-time notifications and its smooth integration with IoT frameworks makes it a flexible platform for creating intelligent systems that are connected to one another. In order to demonstrate Android's potential for allowing creative IoT applications, the paper addresses the technological considerations, programming environment, and integration choices accessible for Android app development.

3. Initialization IoT applications now have more options thanks to the rising prevalence of mobile devices. The architecture, essential characteristics, and applications of Android app development in the context of IoT are highlighted in this article. Android is a strong platform for creating smart and connected systems due to its adaptability, wide adoption, and ability to integrate with IoT frameworks.

4. The Environment for Developing Android Apps With the Android Studio IDE, Android Software Development Kit (SDK), and Java programming language, Android offers a complete development environment. The development environment provides resources for developing code, designing user interfaces, testing, and debugging Android programmes. The article presents code samples for typical IoT-related tasks and talks about the Android app development process Integration with IoT Frameworks and Protocols Android apps can integrate with various IoT frameworks and protocols to allow smooth interaction and communication with IoT networks and devices. Popular frameworks that offer standardised IoT communication protocols and APIs include MQTT, CoAP, and AllJoyn. The article examines integration possibilities and provides examples of Android apps interacting with IoT devices using various protocols.

5. Benefits and Difficulties A large developer community, thorough documentation, and a wide selection of tools and frameworks are just a few benefits of developing IoT apps for Android. However, difficulties including device fragmentation, reduced power consumption, security issues, and data privacy must be solved during the development process web and mobile applications. This paper provides an overview of Firebase, focusing on its architecture, key features, and applications in the realm of IoT- enabled Firebase's capabilities systems. for real-time synchronization, scalable database management, authentication, and cloud messaging make it an attractive solution for IoT application development.

6. Firebase Architecture Firebase is built on a scalable and distributed cloud infrastructure that ensures high availability and reliability. It consists of various components, including Firebase Realtime Database, Firebase Authentication, Firebase Cloud Messaging, Firebase Hosting, and Firebase Functions. These components work together to provide a seamless and efficient development and deployment experience. The Interface We designed for Vehicle Monitoring looks like the given below .

Vehicle Monitoring	
Distance:	0
Alcohol:	NO
Humidity:	2147483648
LDR Left:	HIGH
LDR Right:	HIGH
Rain:	YES
Temperature:	32.6

Fig.13. Screenshot of MIT Application.

GOOGLE FIREBASE :

Firebase is a bunch of backend distributed computing administrations and application improvement stages given by Google. It has information bases, administrations, verification, and reconciliation for various applications, including Android, iOS, JavaScript, Node.js, Java, Solidarity, PHP, and C++



Fig.14. Google Firebase

Introduction Firebase is a cloud-based platform that offers a range of services and tools for building valuable in the IoT domain. These include real-time data synchronization, which enables instantaneous

updates across multiple devices, scalable and secure database management, user authentication and authorization, cloud messaging for efficient communication, hosting for



web applications, and serverless functions for executing code in response to events.

4. IoT applications for Firebase IoT systems have several uses for Firebase, which also makes it possible for developers to create dependable and scalable solutions. It can be used for effective cloud messaging for notifications and alerts, real-time sensor data collection and synchronisation, remote device control and management, user authentication, and access control in IoT applications. The application of Firebase in actual IoT settings is demonstrated in the paper through case studies and examples.

5. Options for Integration and Development For developers to use Firebase's capabilities in IoT applications, the platform offers a variety of integration options and programming interfaces. It enables cross-platform interoperability by supporting a variety of development platforms, such as JavaScript, Android, iOS, and Unity. In addition, Firebase provides software development kits (SDKs) and REST APIs for seamless IoT device and application integration.

6. Benefits and Difficulties For the creation of IoT applications, Firebase has a number of benefits, such as quick prototyping, real-time updates, scalability, and strong security measures. However, during the development and deployment process, issues like data privacy and compliance, scalability in large-scale deployments, and cost optimisation need to be taken into account and handled.

LITERATURE SURVEY:

1)Adaptive Headlight System for Accident Prevention Published in: 2014 International Conference on Recent Trends in Information Technology Shreyas S, Kirthanaa Raghuraman, Padmavathy AP, S Arun Prasad, G. Devaradjane Madras Institute of Technology, Anna University Chennai, India 1. The work in this paper is focusing on the design and operation of a microcontrollerbased Adaptive Headlight System (AHS) for automobiles is the subject of this study. The major goal of this system is to provide a cost estimate. When driving in the dark, this is an efficient strategy for illuminating blind spots. during the night and when visibility is obstructed order to make the objects visible in those dimly lit areas as a result, accidents are avoided. The concept of adaptive headlamps is not new in high end cars like Volvo, BMW, Audi etc. The components that are used to implement the adaptive headlight system are Microcontroller unit, DC Generator, Photo diode, Stepper motor etc. limitation is the maximum degree of turn achieved on the left headlamp is 37 degrees and on the right-hand side is 43 degrees.

2)Intelligent Automatic High Beam Light Controller Mohammed Alsumady and Shadi. A. Alboon Hijjawi Faculty for Engineering Technology, Electronics Engineering Department, Yarmouk University, Irbid, 21163, Jordan Published by license under the OCP Science imprint, a member of the Old City Publishing Group. The work in this paper focusing on an automatic high beam light controller is required to make night time driving safer and more friendly to other cars on the road. This study provides a simple, lowcost, and easy-to- implement method. Install and build an intelligent high beam light controller that turns on and off automatically. They are using simple LDR sensor, which is sense simple light intensity. The technology was developed and tested on a real car that was driven at night. The results of the experiments suggest that the system can detect incoming car lights from a distance of roughly 230 meters. 3)Night Time Vehicle Detection for Driving Assistance Light Beam Controller P. F. Alcantarilla, L. M. Bergasa, P. Jim'enez, M. A. Sotelo, I. Parra, D. Fern'andez Department of Electronics. University of Alcal'a de Henares (Madrid), Spain pablo.alcantarilla, bergasa, pjimenez, sotelo, parra. S.S. MayoralFICO MIRRORS, SA - Research Department Mollet del Vall'es (Barcelona), Spain Silvia. They demonstrate a successful system for recognising cars in front of a camera-assisted vehicle (preceding vehicles moving in the same direction and oncoming vehicles travelling in the opposite direction) under nighttime driving conditions so that vehicle head lights can be automatically changed. Avoiding glares by switching between low and high beams for the motorists. In this paper they are studied on Clustering Process, Distance Estimation, Black Hat Transformation, Classification Using Support Vector Machines etc. On the one hand, the system's performance for headlights is excellent (detection distances of 300 m to 500 m), while on the other hand. Limitation is the performance of tail lights (distance from the vehicle) the detecting range (50 m - 80 m) has to be expanded.

4) Temporal Coherence Analysis for Intelligent Headlight Control Antonio Lopez ', Jorg Hilgenstock, Andreas Busses, Ramon Baldrich ', Felipe Lumbreras, Joan Serrat. January 2008. The work in this paper focusing on, even when the traffic situation requires it, drivers use high lights sparingly at night. As a result, intelligent automatic regulation of vehicle headlights is critical. Because dazzling other drivers is prohibited. In this paper they are mostly studied on "Algorithm". The key problem in the application at hand is distinguishing between picture spots caused by vehicle lights and those caused by reflections in various structures.

5) Fuzzy Headlight Intensity Controller using Wireless Sensor Network Victor Nutt Electrical Engineering Arkansas State University Jonesboro, USA. Shubhalaxmi Kher Electrical Engineering Arkansas State University Jonesboro, USA. Mehul Raval Pattern Recognition and Image Processing Group DAIICT Gandhinagar, India. IEEE International Conference on Fuzzy Systems · July 2013. The work in this paper is focusing on, the data acquired by a wireless sensor network is used to

create a fuzzy controller (WSN). Low latency enables for faster adjustment of illumination intensity, reducing momentary blindness. For controller design, a number of factors are taken into account. The results reveal that the controller output is practically instantaneous and continuously generates a control signal. They are mainly studied on Headlight Intensity Controller, Design issues, Fuzzy inference system, Data acquisition etc. When both



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drivers use a greater lamp intensity setting, the problem becomes even worse. Increased speed as a result of lower traffic levels at night also enhances the severity of accidents. 6) A Multi Featured Automatic Head Light Systems Prototype for Automotive Safety Mr. Sandip S. Jadhav, Department of Automobile Engineering, Rajarambapu Institute of Technology, Islampur, Shivaji University Kolhapur, M.S. INDIA. Prof. Ansar A. Mulla Assistant Professor, Department of Automobile Engineering, Rajarambapu Institute of Technology, Islampur, Shivaji University Kolhapur,

M.S. INDIA. The work in this paper is focusing on, the driver has control over the headlamp, which can be altered from high to low beam (brightness) (dim). The headlight must be adjusted to the lighting conditions. The driver's required the prototype that has been created, reduces the problem by lowering the light. our vehicle's bright headlights to low beam automatically when it detects a vehicle approaching in close proximity in the opposite direction The dimmer's full operation is a using a sensor to create a simple electronic circuit Arduino, which detects and controls the headlight in accordance with the necessary conditions [1] This multi-featured prototype A headlight system has been developed. Automatic switch is used in this project. In this project there is some limitation, When the relative humidity in the atmosphere is greater than 195, the immediate fog lamp turns on. In the event that there is less moisture or It will get if the humidity in the atmosphere is less than 195. 7) Multi featured Automatic Headlight Switching System for Human Safety Mrs. A. Geetha, J. Pravin Balaji, M. Prakash Raj, V. Pravin Kumar. Assistant Professor, Department of Electronics and Communication Engineering, SSM Institute of Engineering and Technology, Dindigul UG Scholars, Department of Electronics and Communication Engineering, SSM Institute of Engineering and Technology. The work in this paper focusing on Arduino Board, LDR and Ultrasonic Sensor. Based on the detection of On-Coming, the system intends to automatically manage a vehicle's beam condition (high beam or low beam) during nighttime driving. This project includes a reverse parking sensor, which detects when the car is approaching an object while in reverse mode and emits a sound from a specific distance. In this project there are some limitations which is When driving at

night or in foggy conditions, motorists suffer a significant disadvantage due to the ray of light that falls straight upon their eyes. These phenomena have medicinal implications.

8) Automatic Vehicle Headlight Management System to Prevent Accidents Due to Headlight Glare Lakshmi K, Nevetha R, Ilakkiya S N, Ganesan R. International Journal of Innovative Technology and Exploring Engineering (IJITEE), ISSN: 2278-3075, Volume-8 Issue-9, July 2019. The work in this paper is based on headlight, vehicle, temporary blindness, LDR. During night driving, the high beam from the headlight creates a perilous condition. It causes momentary blindness in drivers, which can result in a collision or, in rare cases, an accident. The information is supplied to the microcontroller when a high beam falls on the surface of LDR. The intensity of the microcontroller is compared. Light comes in at the desired intensity. In this project there are some limitations which is when driving at night or in foggy conditions, motorists suffer a significant disadvantage due to the ray of light that falls straight upon their eyes.

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(pp. 1-6). IEEE. Fig. 5. – Block diagram for Lux-meter and Accelerometer based module

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