

SOLAR BASED SMART AGRICULTURE ROBOT

Vyas S. N.^{1,} Mashalkar S.D.²

^{1,2} Professor, SSWP, Solapur, Maharashtra.

Akshaya Gudur³ E&TC Engineering, Shri Siddheshwar Women's Polytechnic.

Ankita Kinagi⁴ E&TC Engineering, Shri Siddheshwar Women's Polytechnic.

Vaishnavi Mude⁵ E&TC Engineering, Shri Siddheshwar Women's Polytechnic.

Varsha Potu⁶ E&TC Engineering, Shri Siddheshwar Women's Polytechnic.

Ankita Vallamdeshi⁷ E&TC Engineering, Shri Siddheshwar Women's Polytechnic.

^{3,4,5,6,7}Student, SSWP, Solapur, Maharashtra.

Abstract – In response to the evolving demands of contemporary agriculture, the Solar-Based Smart Agriculture Irrigation Robot project represents an innovative integration of robotics and renewable energy to enhance the efficiency and sustainability of farming practices. This project aims to develop a versatile, autonomous robot equipped with a suite of functionalities, including automated irrigation, vegetation management, seeding, and targeted watering. Powered by a 2S Li-ion battery pack, supported by a 12W solar panel, the robot demonstrates a commitment to eco-friendly energy use and operational resilience in off-grid agricultural regions. Through a user-friendly mobile app interface, farmers can remotely control and monitor the robot, revolutionizing farm management. The project's significance lies in its potential to address challenges such as water scarcity and labor shortages, contributing to precision agriculture and fostering a greener future for farming practices. This abstract encapsulates the project's dedication to technological innovation, efficiency, and sustainable agriculture.

2. INTRODUCTION

This agricultural robot is designed for smart irrigation and cultivation. It is powered by a 2S lithium-ion battery pack and supplemented by a 12W solar panel, providing flexibility between battery and solar power sources. The robot utilizes a Node MCU for wireless communication, enabling remote control through a dedicated phone app. The locomotion of the robot is achieved through four

The locomotion of the robot is achieved through four geared motors with a speed rating of 100 RPM. These motors are intricately controlled by an L293D motor

driver, allowing for precise and synchronized movement. The choice of 100 RPM geared motors ensures a balance between speed and torque, crucial for agricultural tasks. One notable feature of this robot is its adaptability through attachments. It incorporates a radial cooling fan repurposed as a seed sprayer, showcasing the inventive use of existing technology. This seed sprayer attachment facilitates controlled and uniform dispersal of seeds during cultivation.

The central control unit, the NodeMCU, acts as the brain of the robot. It enables wireless communication, allowing the user to control the robot remotely using a mobile phone app. This feature enhances the robot's usability, providing a convenient and efficient means of managing agricultural tasks.

The power system is a key aspect of the project. The robot can be powered by the 2S lithium-ion battery pack, offering mobility and autonomy. Alternatively, it can harness solar energy through the 12W solar panel, promoting sustainability and reducing reliance on traditional power sources.

In summary, this agricultural robot integrates advanced control systems, energy-efficient power sources, and innovative attachments to facilitate smart irrigation and cultivation. The combination of geared motors, an adaptable seed sprayer, wireless control, and dual power sources makes it a comprehensive and sustainable solution for modern agricultural practices.



International Journal of Scientific Research in Engineering and Management (IJSREM)

Volume: 08 Issue: 04 | April - 2024

SJIF Rating: 8.448

ISSN: 2582-3930



Fig:-Circuit Diagram of Solar Powered Irrigation Bot.

ADVANTAGES

- Real-time Environmental Monitoring: Continuous tracking of temperature and humidity to ensure an optimal environment.
- Integration of wide, rugged types enhances traction for stable and controlled movement.
- Versatility is expanded, allowing the robot to traverse challenging terrains in agricultural fields.
- Wide types contribute to reduced soil compaction, promoting healthy plant growth.
- A broader type base ensures overall stability, crucial for precise movements during tasks.
- Rugged types provide increased resistance to obstacles, minimizing disruptions during operation.

APPLICATION

- The smart agricultural robot, equipped with a 2S lithium-ion battery pack, solar power compatibility, 100 RPM geared motors, L293D motor driver, Node MCU for remote control, seed sprayer, and wide, rugged types, finds applications in precision farming.
- It excels in tasks such as targeted seeding, spraying, and cultivation due to the precision provided by the 100 RPM geared motors and L293D motor driver.
- The robot's automated irrigation capabilities, facilitated by the seed sprayer and versatile attachments, ensure controlled and uniform water distribution across agricultural fields.
- Its innovative seed sprayer attachment allows for efficient and uniform seed dispersal, optimizing planting processes across various crops.

- Remote monitoring and control through the Node MCU enable farmers to manage the robot efficiently, providing real-time oversight of agricultural activities.
- Sustainability is a key aspect with the integration of a 2S lithium-ion battery pack and a 12W solar panel, offering alternative and renewable power sources for reduced environmental impact.
- Wide, rugged tires enhance the robot's adaptability to varied terrains, making it suitable for deployment in fields with uneven surfaces or challenging topographies.

FUTURE SCOPE

- Enhanced Sensor Integration: Integrate more sensors for comprehensive health monitoring.
- Integration of Artificial Intelligence (AI): Incorporating AI algorithms for real-time data analysis and decision-making.
- Advanced Sensing Technologies: Employing hyperspectral imaging and advanced sensors for detailed soil and crop data.
- Machine Learning for Crop Recognition: Integrating machine learning models for crop identification and customized operations.
- Integration with Precision Agriculture Technologies: Collaborating with drones or satellite data for precise farm management.
- Autonomous Navigation and Swarm Robotics: Advancing autonomous navigation for coordinated swarm robotics in large-scale coverage.
- Enhanced Energy Harvesting Technologies: Exploring advanced solar panels and kinetic energy harvesting for increased autonomy.
- Real-time Data Sharing and Connectivity: Facilitating real-time data sharing within a connected ecosystem.

CONCLUSIONS

In conclusion, the smart agricultural robot project represents a groundbreaking initiative in modern farming, amalgamating innovative technologies to address key challenges. With features like a 2S lithium-ion battery pack, solar power compatibility, 100 RPM geared motors, L293D motor driver, Node MCU for remote control, seed sprayer, and wide, rugged tires, the project offers a holistic solution for precision farming.



REFERENCES

- 1. Paper by K. N. Nandan, R. Kirthana, and P. Sure discusses an "*IoT based solar powered Agri Bot for irrigation and farm monitoring*".2018
- K Kapoor, K K Pandey , A K Jain , A Nandan, *"Evolution of solar energy in India"* ., A review Renewable and Sustainable Energy Reviews , volume 40, p. 475 - 487 Posted: 2014, Crossref.
- Mathad GP, Reddy S, Punith CM, Murthy BV (2018) "IoT based mobile charging with solar energy by coin insertion". In: Proceedings of ISSRD International Conference, 24th June 2018, Bengaluru, India.
- D. S. Rahul, S. K. Sudarshan, K. Meghana, K. N. Nandan, R. Kirthana and P. Sure, "IoT based solar powered Agri Bot for irrigation and farm monitoring: Agri Bot for irrigation and farm monitoring," 2018 2nd International Conference on Inventive Systems and Control (ICISC), Coimbatore, India, 2018.
- Hameed, I.A., A. la Cour-Harbo, and O.L. Osen. "Side-to-side 3D coverage path planning approach for agricultural robots to minimize skip/overlap areas between swaths", Robotics and Autonomous Systems, 2016.
- 6. Nelson Mimura Gonzalez, Tereza Cristina Melo de Brito Carvalho, Charles Christian Miers. "Cloud resource management: towards efficient execution of large-scale scientific applications and workflows on complex infrastructures", Journal of Cloud Computing.
- "EFFICIENT TRACKING FOR WOMEN SAFETY AND SECURITY" International Journal of Advanced Research in Comp, DEC, 2017, Issue 8-9, page: 328-330, ISSN: 0976-5697.
- P. Bosilj, T. Duckett, and G. Cielniak, "Connected attribute morphology for unified vegetation segmentation and classification in precision agriculture," Computers in Industry, Special Issue on Machine Vision for Outdoor Environments, vol. 98, pp. 226–240, 2018.