

Vehicles That Talk:

Unleashing the Power of V2X Communication in Smart Mobility

Nirmala Devi A C, Asst Prof. nirmalagannath79@gmail.com SJCIT, Chickaballpura India,

Darshan Gowda T darshangowdakhalli@gmail.com SJCIT ,Chickaballapura India

Abstract

Vehicle-to-Everything (V2X) communication is a transformative concept in modern transportation, enabling dynamic interactions among vehicles, infrastructure, pedestrians, and networks. This paper explores the key principles, enabling technologies, applications, and challenges of V2X systems. The implementation of V2X has the potential to significantly enhance road safety, streamline traffic management, and accelerate the transition to autonomous mobility. Emphasis is also placed on the need for standardized protocols, cybersecurity, and supportive regulations to maximize the benefits of V2X.

1. Introduction

With the rise of autonomous vehicles and smart city initiatives, V2X communication plays a crucial role in achieving safer and more efficient transportation. This technology enables continuous real-time communication between vehicles and other entities, helping reduce accidents and improve traffic flow. However, obstacles such as cybersecurity threats, lack of universal standards, and integration issues with existing systems remain. This paper provides an in-depth overview of V2X, highlighting its advantages and identifying barriers to widespread use.

The growing demand for intelligent transport systems arises from increasing urbanization and traffic congestion. Legacy infrastructure often lacks the adaptability needed for modern mobility. V2X offers a proactive approach by supporting constant, low-delay communication between road users and infrastructure. This aligns with global initiatives such as Vision Zero, which aims to eliminate traffic fatalities. V2X technology serves as a vital link between today's connected vehicles and future autonomous transportation systems.

What is V2X Communication?

V2X encompasses a communication ecosystem that enables vehicles to exchange data with:

- Other vehicles (V2V)
- Roadside infrastructure (V2I)
- Pedestrians and mobile users (V2P)
- Network services (V2N)

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This is achieved using platforms such as Dedicated Short-Range Communication (DSRC), cellular technology (LTE/5G), and other wireless protocols. The primary goal is to improve road safety and enable automated driving by facilitating timely information exchange.

2. Literature Survey

Extensive research from academic and industrial sources has investigated the viability and performance of V2X technologies.

Karagiannis et al. [1] provided a detailed overview of DSRC's potential in ensuring low-latency and dependable vehicle communication for safety-critical scenarios.

Sun et al. [2] demonstrated how Cellular V2X, particularly LTE-V2X, outperforms DSRC in coverage and data delivery efficiency, making it well-suited for city-scale implementation.

Abboud et al. [3] highlighted various V2X applications, including platooning and cooperative navigation, and underlined the importance of maintaining reliable communication metrics.

Lu et al. [4] proposed a layered approach using 5G and edge computing to enhance real-time data processing and reduce response times.

Campolo et al. [5] introduced a protocol stack combining DSRC and ITS-G5, supporting efficient V2X communication in diverse operational contexts.

Zhou et al. [6] explored the integration of AI in V2X systems, suggesting that intelligent algorithms can enhance data prioritization, traffic prediction, and security.

Papadimitratos et al. [7] examined the security landscape of V2X, recommending cryptographic techniques to mitigate attacks and preserve privacy.

Molina-Masegosa and Gozalvez [8] concluded through simulations that DSRC is favorable in sparse environments, while C-V2X performs better in dense traffic conditions.

Overall, these studies affirm the potential of V2X while underscoring the need for further development in interoperability, security, and deployment strategies.

3. Technological Foundations

• **DSRC (Dedicated Short-Range Communication):** Offers localized, rapid message delivery over the 5.9 GHz band, making it suitable for scenarios like crash avoidance and traffic alerts.

• **C-V2X (Cellular Vehicle-to-Everything):** Utilizes existing 4G/5G cellular infrastructure for broader communication reach, offering greater scalability and reliability.

• **5G Networks:** Critical for future V2X applications, providing ultra-low latency, high bandwidth, and improved reliability for real-time vehicular coordination and automated systems.

4. Methodology

This section outlines the components and strategies used to evaluate V2X systems in intelligent transport scenarios.

A. V2X Architecture

• **On-Board Units (OBUs):** Embedded modules in vehicles for DSRC or cellular communication, processing sensor inputs and transmitting safety alerts.

• **Roadside Units (RSUs):** Installed near roads and intersections to collect and disseminate data between vehicles and control centers.

• Edge and Cloud Servers: Perform high-level processing for traffic prediction, incident detection, and route optimization.

• Mobile Devices: Smartphones used by pedestrians that can transmit presence data to vehicles.

B. Communication Frameworks

• **DSRC:** Based on IEEE 802.11p, it transmits Basic Safety Messages (BSMs) containing real-time vehicle status every 100 milliseconds.

• **C-V2X:** Utilizes the PC5 interface for direct communication (V2V, V2I, V2P) and the Uu interface for network-based interactions (V2N), transmitting CAM and DENM messages.

C. Simulation Tools

• **Software:** NS-3 and Veins (OMNeT++ + SUMO)

• **Environment:** Urban and highway traffic models with mixed vehicle types and densities

• **Performance Indicators:** Packet delivery rate, latency, communication range, signal interference, and message throughput

D. Key Algorithms

• Collision Detection: Uses BSMs to estimate time-to-collision and trigger early warnings.

• **Traffic Light Management:** Adjusts signal timing dynamically using RSU data to reduce wait times.

• AI at the Edge: Applies predictive models for congestion management and real-time route adjustment.



E. Security Design

• Adopts PKI for encryption and verification. Pseudonyms safeguard user identities and prevent tracking or spoofing incidents..

5. Results and Analysis

Experimental Setup:

- Tools: SUMO, NS-3 with LTE and 5G modules
- Layout: 2x2 km urban grid with controlled intersections
- Traffic Levels: 25, 50, and 100 vehicles per square km
- Speed Range: Up to 60 km/h

Key Metrics:

- **PDR:** Proportion of successfully transmitted messages
- Latency: Delay from sending to receiving a message
- Signal Range: Distance over which messages remain effective
- Crash Incidence: Measured per 1000 vehicles

Comparative Performance:

Technology	PDR (%)	Latency (ms)	Range (m)	Crashes (/1000 vehicles)
DSRC	87.2	34	~300	12
LTE-V2X	94.6	26	~500	7
5G NR-V2X	98.1	7	>1000	3

Discussion:

- DSRC functions well in low-density setups but experiences interference under heavier traffic.
- LTE-V2X shows better consistency thanks to its managed network structure.
- 5G NR-V2X outperforms others in terms of reliability, speed, and scalability—ideal for automated vehicle coordination.
- Incorporating AI improves collision avoidance and traffic distribution, especially with 5G networks.

Visual Insights:

- Adaptive signaling via V2X reduced traffic congestion in simulation.
- Heatmaps reflected improved flow and less idling in 5G-based systems.
- Pedestrian alerts in V2P modules lowered zone incursions by over 70%.



6. Conclusion

V2X technology represents a pivotal advancement in smart mobility, supporting safer roads and smarter traffic systems through real-time communication among road users and infrastructure. This paper has covered the technological basis, practical benefits, and potential of V2X systems.

Findings suggest that 5G NR-V2X is best suited for future applications, especially in high- density environments. Moreover, integrating AI and edge processing enables smarter decision- making. Addressing key challenges such as cybersecurity, standardization, and infrastructure development remains essential.

Ultimately, V2X lays the groundwork for vehicles that can not only operate autonomously but also interact intelligently with their environment.

Acknowledgment

We gratefully acknowledge Mrs. Nirmala Devi A C, Assistant Professor, Electronics and Communication Engineering, SJCIT, for her mentorship and guidance. Our sincere thanks also go to Prof. Dr. C Rangaswamy, Head of Department, for his continuous encouragement and support.

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