

Traffic Sign Classification Using CNN

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ABSTRACT

This study presents a novel approach for traffic sign classification leveraging Convolutional Neural Networks (CNNs). With the proliferation of autonomous vehicles and advanced driver assistance systems, accurate and efficient traffic sign recognition is imperative for safe and efficient navigation. The proposed CNN-based method utilizes deep learning techniques to automatically extract discriminative features from traffic sign images, enabling robust classification across diverse environmental conditions and variations in sign appearance. Experimental results demonstrate the effectiveness of the proposed approach. This research contributes to the advancement of intelligent transportation systems by providing a reliable and scalable solution for real-time traffic sign classification. Our findings highlight the potential of deep learning for robust and accurate traffic sign classification in real-world scenarios.

INTRODUCTION

The objective of this project is to develop a robust traffic sign classification system using Convolutional Neural Networks (CNNs) for autonomous driving applications. This entails designing and training a CNN model capable of accurately recognizing various traffic signs under different environmental conditions. Key objectives include collecting and preprocessing a diverse dataset, optimizing the model's architecture and parameters for high accuracy, evaluating its performance rigorously, and exploring deployment options in real-world autonomous driving systems.

The project aims to contribute to advancements in autonomous driving technology by improving traffic sign classification capabilities, ultimately enhancing the safety and efficiency of autonomous vehicles on roadways.

LITERATURE REVIEW

Previous Approaches: Early attempts at traffic sign classification relied on handcrafted features and traditional machine learning algorithms. However, these methods often struggled with scalability and generalization to diverse traffic sign datasets and environmental conditions.

CNN Architectures: Numerous CNN architectures have been proposed for traffic sign classification, ranging from simple models like LeNet to deeper and more complex networks such as VGGNet, GoogLeNet, and ResNet. These architectures leverage the spatial hierarchy of features present in traffic sign images to achieve superior classification performance.

Dataset Considerations: Researchers typically evaluate CNN

models using benchmark datasets such as the German Traffic Sign Recognition Benchmark (GTSRB) and the LISA Traffic Sign Dataset. These datasets encompass a wide variety of traffic sign classes and variations in lighting, weather, and camera perspectives, enabling thorough evaluation of model robustness. learning process.

PROBLEM STATEMENT

In the rapidly evolving landscape of education, the shift towards full online learning has become a prevalent mode of instruction. However, ensuring high levels of student engagement in this virtual environment poses a significant challenge. Understanding and profiling the factors that influence students' engagement in full online learning.

- Technological Challenges
- Motivational Factors
- Social Interaction

METHODOLOGY

The model architecture chosen is a Convolutional Neural Network (CNN) with multiple convolutional layers followed by max-pooling layers and fully connected layers.

Input Layer: The input shape is defined based on the shape of the input images.

Convolutional Layers: The model consists of four convolutional layers. The first two layers have 32 filters each with a kernel size of (5, 5), followed by ReLU activation functions. The subsequent two layers have 64 filters each with a smaller kernel size of (3, 3).

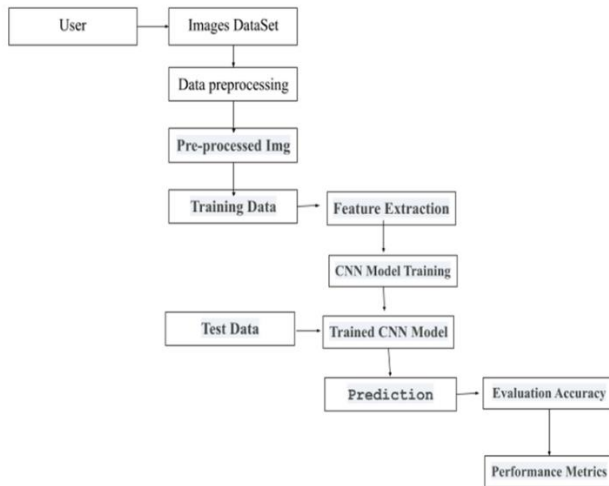
Max Pooling Layers: Max-pooling layers with a pool size of (2, 2) are added after every two convolutional layers.

Dropout Layers: Dropout layers are included after every max-pooling layer to mitigate overfitting by randomly dropping a fraction of neurons during training (25% dropout rate).

Flatten Layer: The flatten layer converts the 3D feature maps into a 1D vector, which is then fed into the fully connected layers.

Fully Connected Layers: Two fully connected dense layers are added.

ARCHITECTURE



EXPERIMENTAL RESULTS

OUTPUT:



CONCLUSION

The development of a traffic sign classification system using Convolutional Neural Networks (CNNs) with a graphical user interface (GUI) marks a significant step forward in enhancing road safety and traffic management. The integration of CNNs enables accurate and efficient recognition of various traffic signs, crucial for ensuring safe navigation on roads. Additionally, the inclusion of a user-friendly GUI facilitates easy interaction with the system, making it accessible to both drivers and traffic management personnel. The project's success in combining advanced deep learning techniques with intuitive user interfaces underscores the potential of technology to address complex real-world challenges effectively. Moving forward, further improvements in GUI design and functionality, coupled with ongoing advancements in CNN algorithms, promise to revolutionize intelligent transportation systems, paving the way for safer and more efficient road networks globally.

FUTURE WORK

In future iterations, several enhancements can be incorporated into the traffic sign classification system using CNN deep learning and a graphical user interface (GUI). Firstly, optimizing the system for real-time performance is crucial, achieved through techniques like model quantization and optimization to reduce computational load. Secondly, adding the capability to detect dynamic signs, such as electronic message boards, would provide more comprehensive traffic information in real-time. Thirdly, implementing semantic segmentation techniques could improve accuracy, especially in scenarios with partially obscured signs. Additionally, integrating other sensor data like LiDAR or radar would enhance the system's robustness.

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